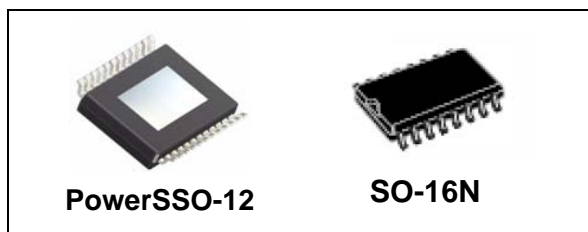


Double channel high-side driver with analog current sense for 24 V automotive applications


Datasheet - production data



Features

| | | |
|-----------------------------------|-----------|-----------------|
| Max transient supply voltage | V_{CC} | 58 V |
| Operating voltage range | V_{CC} | 8 to 36 V |
| Typ on-state resistance (per ch.) | R_{ON} | 100 m Ω |
| Current limitation (typ) | I_{LIM} | 22 A |
| Off-state supply current | I_S | 2 $\mu A^{(1)}$ |

1. Typical value with all loads connected.

- AEC-Q100 qualified 
- General
 - Very low standby current
 - 3.0 V CMOS compatible input
 - Optimized electromagnetic emission
 - Very low electromagnetic susceptibility
 - Compliant with European directive 2002/95/EC
 - Fault reset standby pin (FR_Stby)
 - Optimized for LED application
- Diagnostic functions
 - Proportional load current sense
 - High current sense precision for wide range currents
 - Off-state open-load detection
 - Output short to V_{CC} detection
 - Overload and short to ground latch-off
 - Thermal shutdown latch-off
 - Very low current sense leakage

- Protection
 - Undervoltage shutdown
 - Overvoltage clamp
 - Load current limitation
 - Self limiting of fast thermal transients
 - Protection against loss of ground and loss of V_{CC}
 - Thermal shutdown
 - Electrostatic discharge protection

Application

All types of resistive, inductive and capacitive loads

Description

The VND5T100LAJ-E and VND5T100LAS-E are monolithic devices made using STMicroelectronics® VIPower® technology, intended for driving resistive or inductive loads with one side connected to ground. Active V_{CC} pin voltage clamp protects the devices against low energy spikes.

These devices integrate an analog current sense which delivers a current proportional to the load current.

Fault conditions such as overload, overtemperature or short to V_{CC} are reported via the current sense pin.

Output current limitation protects the devices in overload condition. The devices latch off in case of overload or thermal shutdown.

The devices are reset by a low level pass on the fault reset standby pin.

A permanent low level on the inputs and fault reset standby pin disables all outputs and sets the devices in standby mode.

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1 Block diagram and pin description

Figure 1. Block diagram

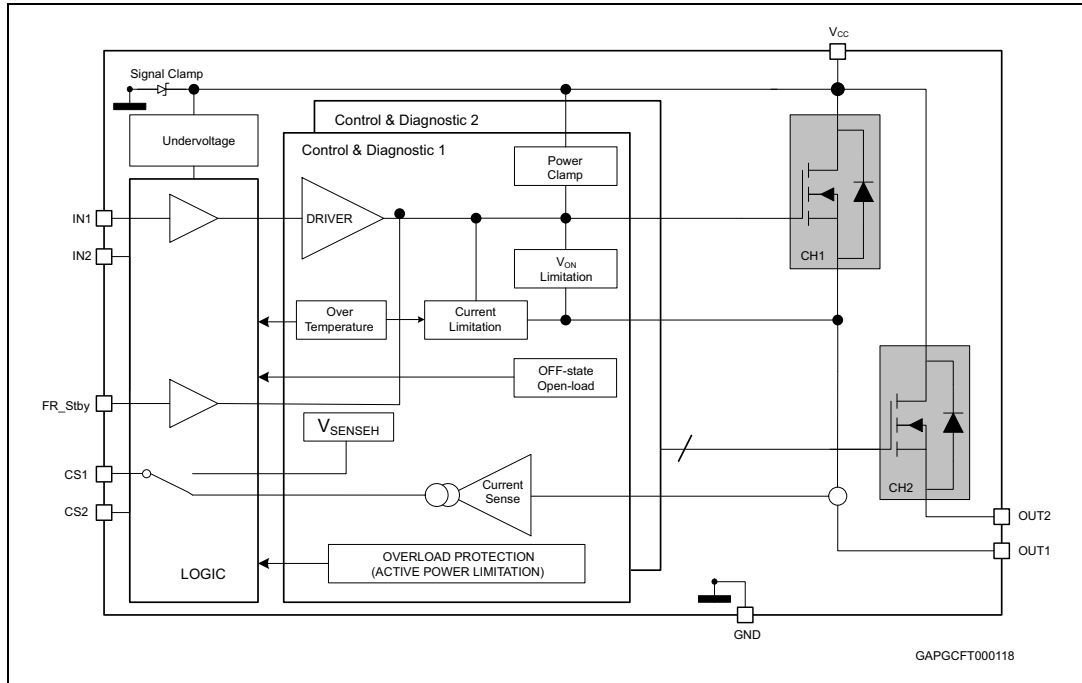


Table 1. Pin function

| Name | Function |
|------------------|--|
| V _{CC} | Battery connection |
| OUT _n | Power output |
| GND | Ground connection |
| IN _n | Voltage controlled input pin with hysteresis, CMOS compatible. It controls output switch state |
| CS _n | Analog current sense pin, it delivers a current proportional to the load current |
| FR_Stby | In case of latch-off for overtemperature/overcurrent condition, a low pulse on the FR_Stby pin is needed to reset the channel. The device enters in standby mode if all inputs and the FR_Stby pin are low. |

Figure 2. Configuration diagram PowerSSO-12 (top view)

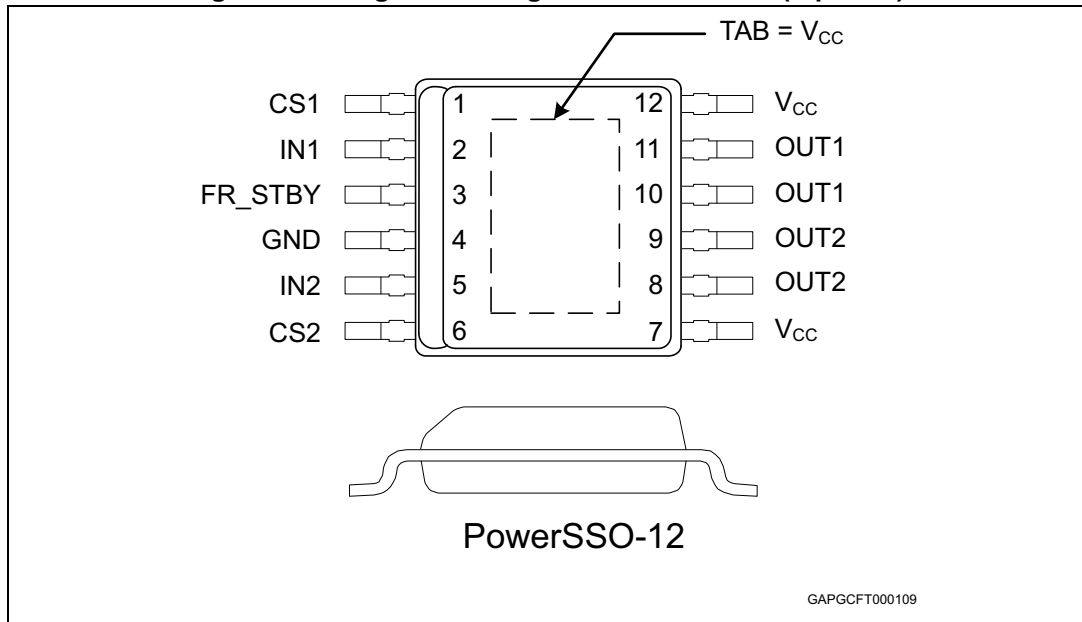


Figure 3. Configuration diagram SO-16N (top view)

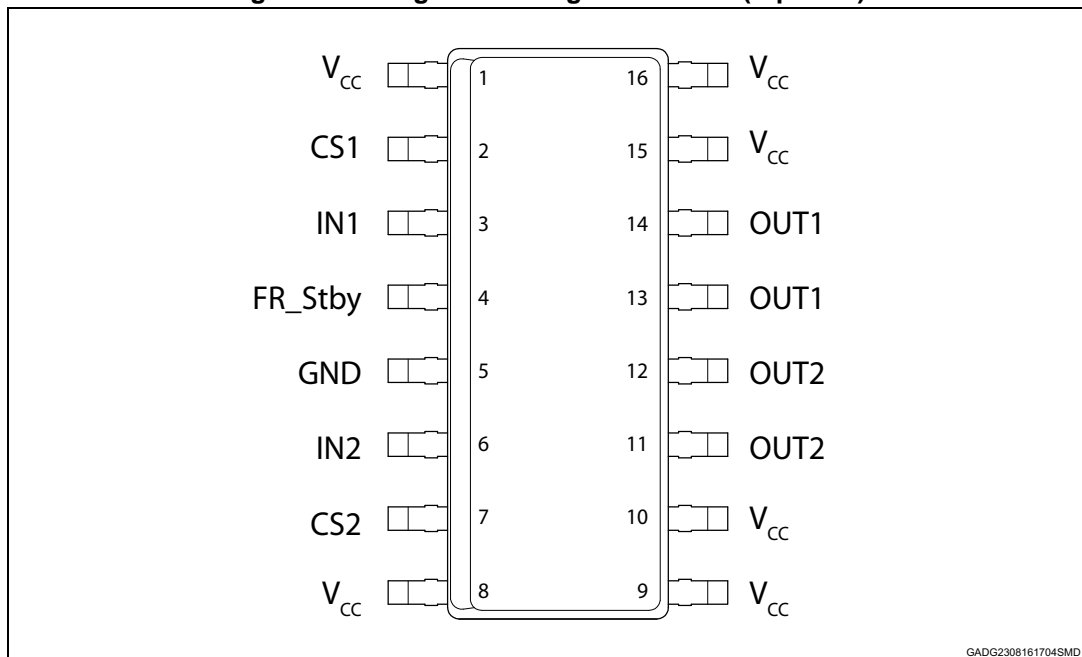


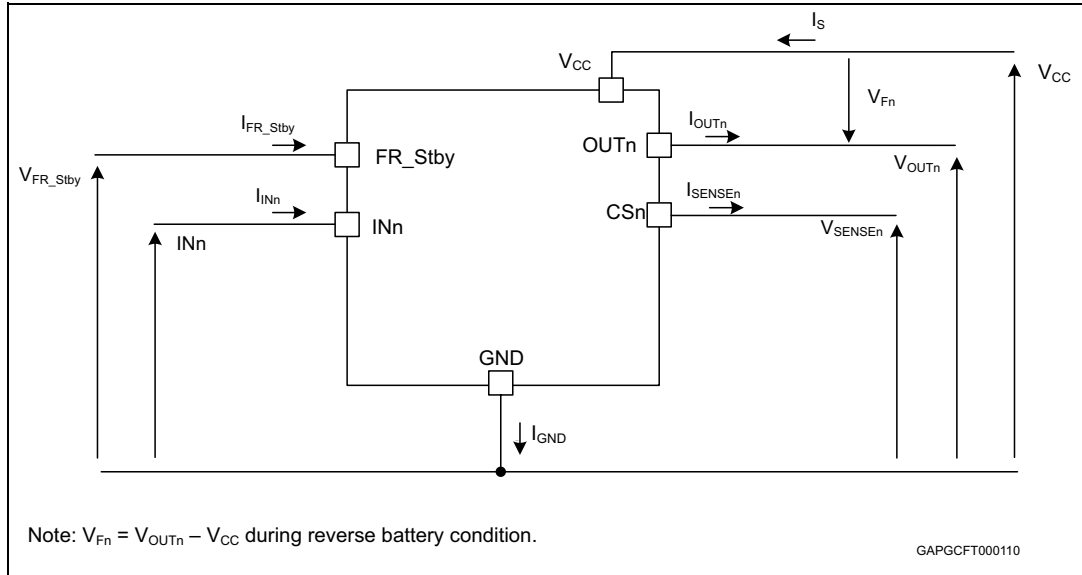
Table 2. Suggested connections for unused and not connected pins

| Connection / pin | Current sense | N.C. | Output | Input | FR_Stby |
|------------------|------------------------|------------------|-------------|------------------------|------------------------|
| Floating | Not allowed | X ⁽¹⁾ | X | X | X |
| To ground | Through 10 KΩ resistor | X | Not allowed | Through 10 KΩ resistor | Through 10 KΩ resistor |

1. X: do not care.

2 Electrical specifications

Figure 4. Current and voltage conventions



2.1 Absolute maximum ratings

Stressing the device above the ratings listed in [Table 3](#) may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to the conditions reported in this section for extended periods may affect device reliability.

Table 3. Absolute maximum ratings

| Symbol | Parameter | Value | Unit |
|----------------|--------------------------------------|----------------------------|------|
| V_{CC} | DC supply voltage | 58 | V |
| $-V_{CC}$ | Reverse DC supply voltage | 0.3 | V |
| $-I_{GND}$ | DC reverse ground pin current | 200 | mA |
| I_{OUT} | DC output current | Internally limited | A |
| $-I_{OUT}$ | Reverse DC output current | 20 | A |
| I_{IN} | DC input current | -1 to 10 | mA |
| I_{FR_Stby} | Fault reset standby DC input current | -1 to 1.5 | mA |
| $-I_{CSense}$ | DC reverse CS pin current | 200 | mA |
| V_{CSense} | Current sense maximum voltage | $V_{CC} - 58$ to $+V_{CC}$ | V |

Table 3. Absolute maximum ratings (continued)

| Symbol | Parameter | Value | Unit |
|------------|--|------------|------------------|
| E_{MAX} | Maximum switching energy ($L = 1.9 \text{ mH}$; $V_{bat} = 32 \text{ V}$; $T_{jstart} = 150^\circ\text{C}$; $I_{OUT} = I_{limL} \text{ (Typ)}$) | 70 | mJ |
| V_{ESD} | Electrostatic discharge (Human Body Model: $R = 1.5 \text{ K}\Omega$; $C = 100 \text{ pF}$) | | |
| | – INPUT | 4000 | V |
| | – CURRENT SENSE | 2000 | V |
| | – FR_STBY | 4000 | V |
| | – OUTPUT | 5000 | V |
| | – V_{CC} | 5000 | V |
| V_{ESD} | Charge device model (CDM-AEC-Q100-011) | 750 | V |
| T_j | Junction operating temperature | -40 to 150 | $^\circ\text{C}$ |
| T_{stg} | Storage temperature | -55 to 150 | $^\circ\text{C}$ |
| L_{Smax} | Maximum stray inductance in short circuit $R_L = 300 \text{ m}\Omega$, $V_{bat} = 32 \text{ V}$, $T_{jstart} = 150^\circ\text{C}$, $I_{OUT} = I_{limHmax}$ | 40 | μH |

2.2 Thermal data

Table 4. Thermal data

| Symbol | Parameter | Maximum value | | Unit |
|----------------|--|-------------------------------|-------------------------------|---------------------------|
| | | PowerSSO-12 | SO-16N | |
| $R_{thj-case}$ | Thermal resistance junction-case (with one channel ON) | 6 | — | $^\circ\text{C}/\text{W}$ |
| $R_{thj-pin}$ | Thermal resistance junction-pin (with one channel ON) | — | 26 | $^\circ\text{C}/\text{W}$ |
| $R_{thj-amb}$ | Thermal resistance junction-ambient | See Figure 28 | See Figure 32 | $^\circ\text{C}/\text{W}$ |

2.3 Electrical characteristics

$8\text{ V} < V_{CC} < 36\text{ V}$; $-40^{\circ}\text{C} < T_j < 150^{\circ}\text{C}$, unless otherwise specified.

Table 5. Power section

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|---------------|------------------------------------|---|------|------------------|------------------|---------------|
| V_{CC} | Operating supply voltage | | 8 | 24 | 36 | V |
| V_{USD} | Undervoltage shutdown | | | 3.5 | 5 | V |
| $V_{USDhyst}$ | Undervoltage shutdown hysteresis | | | 0.5 | | V |
| R_{ON} | On-state resistance ⁽¹⁾ | $I_{OUT} = 1.5\text{ A}$; $T_j = 25^{\circ}\text{C}$ | | 100 | | m Ω |
| | | $I_{OUT} = 1.5\text{ A}$; $T_j = 150^{\circ}\text{C}$ | | | 200 | |
| V_{clamp} | Clamp voltage | $I_S = 20\text{ mA}$ | 58 | 64 | 70 | V |
| I_S | Supply current | Off-state: $V_{CC} = 24\text{ V}$; $T_j = 25^{\circ}\text{C}$; $V_{IN} = V_{OUT} = V_{SENSE} = 0\text{ V}$ | | 2 ⁽²⁾ | 5 ⁽²⁾ | μA |
| | | On-state: $V_{CC} = 24\text{ V}$; $V_{IN} = 5\text{ V}$; $I_{OUT} = 0\text{ A}$ | | 4.2 | 6 | mA |
| $I_{L(off)}$ | Off-state output current | $V_{IN} = V_{OUT} = 0\text{ V}$; $V_{CC} = 24\text{ V}$; $T_j = 25^{\circ}\text{C}$ | 0 | 0.01 | 3 | μA |
| | | $V_{IN} = V_{OUT} = 0\text{ V}$; $V_{CC} = 24\text{ V}$; $T_j = 125^{\circ}\text{C}$ | 0 | | 5 | |
| V_F | Output - V_{CC} diode voltage | $-I_{OUT} = 1.5\text{ A}$; $T_j = 150^{\circ}\text{C}$ | | | 0.7 | V |

1. For each channel.

2. PowerMos leakage included

Table 6. Switching ($V_{CC} = 24\text{ V}$; $T_j = 25^{\circ}\text{C}$)

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|-----------------------|---|--------------------|------|------|------|------------------|
| $t_{d(on)}$ | Turn-on delay time | $R_L = 16\ \Omega$ | | 27 | | μs |
| $t_{d(off)}$ | Turn-off delay time | $R_L = 16\ \Omega$ | | 38 | | μs |
| $dV_{OUT}/dt_{(on)}$ | Turn-on voltage slope | $R_L = 16\ \Omega$ | | 1 | | V/ μs |
| $dV_{OUT}/dt_{(off)}$ | Turn-off voltage slope | $R_L = 16\ \Omega$ | | 0.65 | | V/ μs |
| W_{ON} | Switching energy losses during t_{won} | $R_L = 16\ \Omega$ | | 0.23 | | mJ |
| W_{OFF} | Switching energy losses during t_{woff} | $R_L = 16\ \Omega$ | | 0.26 | | mJ |

Table 7. Logic inputs

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|----------|--------------------------|-------------------------|------|------|------|---------------|
| V_{IL} | Input low level voltage | | | | 0.9 | V |
| I_{IL} | Low level input current | $V_{IN} = 0.9\text{ V}$ | 1 | | | μA |
| V_{IH} | Input high level voltage | | 2.1 | | | V |

Table 7. Logic inputs (continued)

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|----------------------|--|---|------|------|------|---------------|
| I_{IH} | High level input current | $V_{IN} = 2.1\text{ V}$ | | | 10 | μA |
| $V_{I(hyst)}$ | Input hysteresis voltage | | 0.25 | | | V |
| V_{ICL} | Input clamp voltage | $I_{IN} = 1\text{ mA}$ | 5.5 | | 7 | V |
| | | $I_{IN} = -1\text{ mA}$ | | -0.7 | | V |
| $V_{FR_Stby_L}$ | Fault_reset_standby low level voltage | | | | 0.9 | V |
| $I_{FR_Stby_L}$ | Low level fault_reset_standby current | $V_{FR_Stby} = 0.9\text{ V}$ | 1 | | | μA |
| $V_{FR_Stby_H}$ | Fault_reset_standby high level voltage | | 2.1 | | | V |
| $I_{FR_Stby_H}$ | High level fault_reset_standby current | $V_{FR_Stby} = 2.1\text{ V}$ | | | 10 | μA |
| $V_{FR_Stby(hyst)}$ | Fault_reset_standby hysteresis voltage | | 0.25 | | | V |
| $V_{FR_Stby_CL}$ | Fault_reset_standby clamp voltage | $I_{FR_Stby} = 15\text{ mA}$ ($t < 10\text{ ms}$) | 11 | | 15 | V |
| | | $I_{FR_Stby} = -1\text{ mA}$ | | -0.7 | | V |
| t_{reset} | Overload latch-off reset time | See Figure 5 | 2 | | 24 | μs |
| t_{stby} | Standby delay | See Figure 6 | 120 | | 1200 | μs |

Figure 5. $T_{standby}$ definition

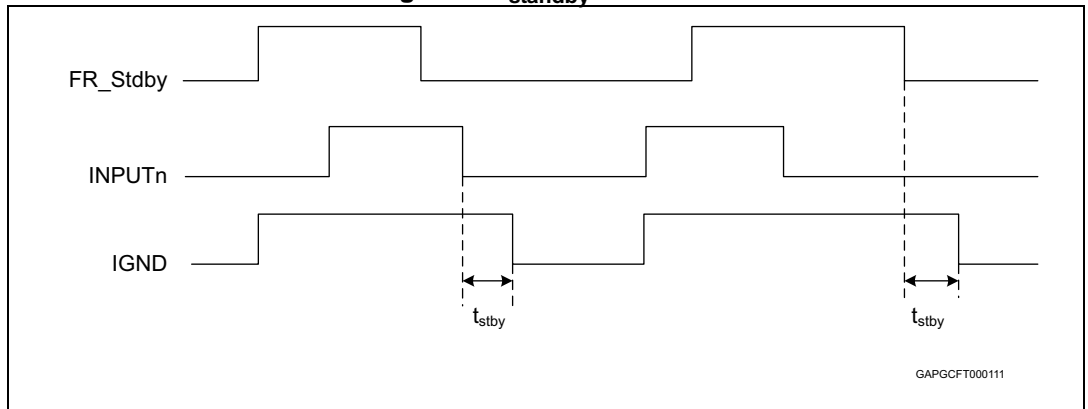


Figure 6. T_{reset} definition

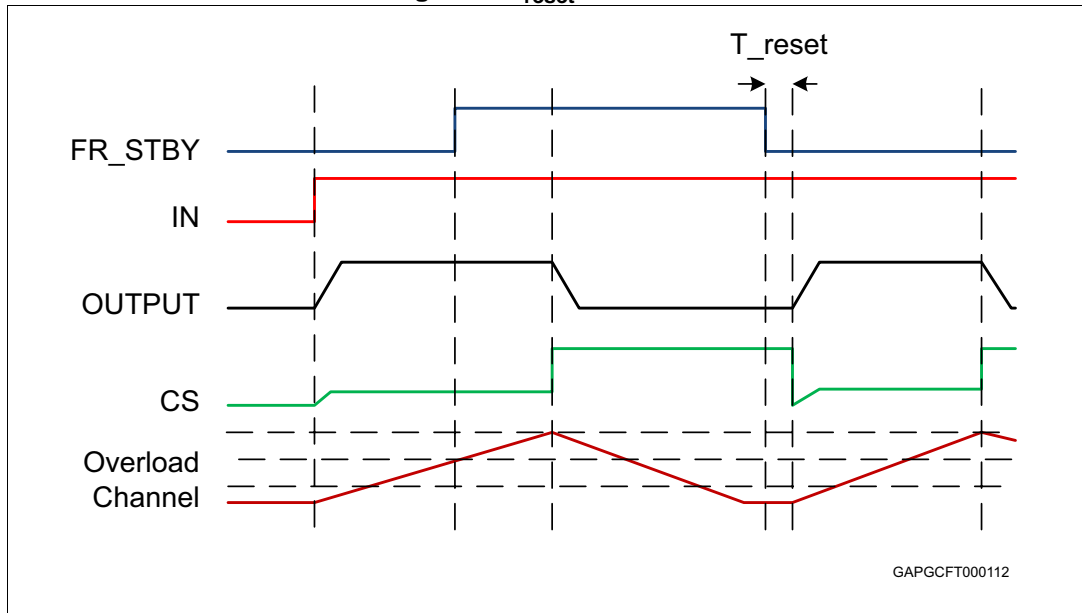


Table 8. Protections and diagnostics

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|-------------|--|--|---------------|---------------|---------------|--------------------|
| I_{limH} | DC short circuit current | $V_{CC} = 24\text{ V}$ | 16 | 22 | 30 | A |
| | | $5\text{ V} < V_{CC} < 36\text{ V}$ | | | 30 | A |
| I_{limL} | Short circuit current during thermal cycling | $V_{CC} = 24\text{ V};$ $T_R < T_j < T_{TSD}$ | | 6 | | A |
| T_{TSD} | Shutdown temperature | | 150 | 175 | 200 | $^{\circ}\text{C}$ |
| T_R | Reset temperature | | $T_{RS} + 1$ | $T_{RS} + 5$ | | $^{\circ}\text{C}$ |
| T_{RS} | Thermal reset of status | | 135 | | | $^{\circ}\text{C}$ |
| T_{HYST} | Thermal hysteresis ($T_{TSD} - T_R$) | | | 7 | | $^{\circ}\text{C}$ |
| V_{DEMAG} | Turn-off output voltage clamp | $I_{OUT} = 1.5\text{ A}; V_{IN} = 0;$ $L = 6\text{ mH}$ | $V_{CC} - 58$ | $V_{CC} - 64$ | $V_{CC} - 70$ | V |
| V_{ON} | Output voltage drop limitation | $I_{OUT} = 50\text{ mA};$ $T_j = -40^{\circ}\text{C to } 150^{\circ}\text{C}$ | | 25 | | mV |

Table 9. Current sense (8 V < V_{CC} < 36 V)

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|---|---|---|------|------|------|------|
| K _{OL} | I _{OUT} /I _{SENSE} | I _{OUT} = 12 mA; V _{SENSE} = 0.5 V; T _j = -40°C to 150°C | 833 | | | |
| K _{LED} | I _{OUT} /I _{SENSE} | I _{OUT} = 50 mA; V _{SENSE} = 0.5 V; T _j = -40°C to 150°C | 1328 | 2190 | 3332 | |
| dK _{LED} /K _{LED(TOT)} ⁽¹⁾ | Current sense ratio drift | I _{OUT} = 12 mA to 25 mA; I _{CAL} = 18 mA; V _{SENSE} = 0.5 V; T _j = -40°C to 150°C | -30 | | 30 | % |
| K ₀ | I _{OUT} /I _{SENSE} | I _{OUT} = 100 mA; V _{SENSE} = 0.5 V; T _j = -40°C to 150°C | 1170 | 1950 | 2730 | |
| dK ₀ /K ₀ ⁽¹⁾ | Current sense ratio drift | I _{OUT} = 100 mA; V _{SENSE} = 0.5 V; T _j = -40°C to 150°C | -18 | | 18 | % |
| K ₁ | I _{OUT} /I _{SENSE} | I _{OUT} = 0.4 A; V _{SENSE} = 1 V; T _j = -40°C to 150°C | 1259 | 1740 | 2191 | |
| dK ₁ /K ₁ ⁽¹⁾ | Current sense ratio drift | I _{OUT} = 0.4 A; V _{SENSE} = 1 V; T _j = -40°C to 150°C | -15 | | 15 | % |
| K ₂ | I _{OUT} /I _{SENSE} | I _{OUT} = 0.8 A; V _{SENSE} = 2 V; T _j = -40°C to 150°C | 1372 | 1730 | 2058 | |
| dK ₂ /K ₂ ⁽¹⁾ | Current sense ratio drift | I _{OUT} = 0.8 A; V _{SENSE} = 2 V; T _j = -40°C to 150°C | -12 | | 12 | % |
| K ₃ | I _{OUT} /I _{SENSE} | I _{OUT} = 1.6 A; V _{SENSE} = 2 V; T _j = -40°C to 150°C | 1509 | 1720 | 1921 | |
| dK ₃ /K ₃ ⁽¹⁾ | Current sense ratio drift | I _{OUT} = 1.6 A; V _{SENSE} = 2 V; T _j = -40°C to 150°C | -8 | | 8 | % |
| K ₄ | I _{OUT} /I _{SENSE} | I _{OUT} = 6 A; V _{SENSE} = 4 V; T _j = -40°C to 150°C | 1646 | 1720 | 1784 | |
| dK ₄ /K ₄ ⁽¹⁾ | Current sense ratio drift | I _{OUT} = 6 A; V _{SENSE} = 4 V; T _j = -40°C to 150°C | -4 | | 4 | % |
| I _{SENSE0} | Analog sense leakage current | I _{OUT} = 0 A; V _{SENSE} = 0 V; V _{IN} = 0 V; T _j = -40 °C to 150 °C | 0 | | 1 | μA |
| | | I _{OUT} = 0 A; V _{SENSE} = 0 V; V _{IN} = 5 V; T _j = -40 °C to 150 °C | 0 | | 2 | μA |
| V _{SENSE} | Max analog sense output voltage | I _{OUT} = 6 A; R _{SENSE} = 3.9 KΩ | 5 | | | V |
| V _{SENSEH} | Analog sense output voltage in fault condition ⁽²⁾ | V _{CC} = 24 V; R _{SENSE} = 3.9 KΩ | 7.5 | 8.5 | 9.5 | V |
| I _{SENSEH} | Analog sense output current in fault condition ⁽²⁾ | V _{CC} = 24 V; V _{SENSE} = 5 V | 4.9 | 9 | 12 | mA |
| t _{DSENSE2H} | Delay response time from rising edge of INPUT pin | V _{SENSE} < 4 V; 0.07 A < I _{OUT} < 6 A; I _{SENSE} = 90 % of I _{SENSE} max (see Figure 7) | | 100 | 200 | μs |

Table 9. Current sense (8 V < V_{CC} < 36 V) (continued)

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|------------------------------|--|---|------|------|------|---------------|
| $\Delta t_{\text{DSENSE2H}}$ | Delay response time between rising edge of output current and rising edge of current sense | $V_{\text{SENSE}} < 4 \text{ V};$ $I_{\text{SENSE}} = 90 \% \text{ of } I_{\text{SENSEMAX}};$ $I_{\text{OUT}} = 90 \% \text{ of } I_{\text{OUTMAX}};$ $I_{\text{OUTMAX}} = 1.5 \text{ A}$ (see Figure 12) | | | 150 | μs |
| t_{DSENSE2L} | Delay response time from falling edge of INPUT pin | $V_{\text{SENSE}} < 4 \text{ V};$ $0.07 \text{ A} < I_{\text{OUT}} < 6 \text{ A};$ $I_{\text{SENSE}} = 10 \% \text{ of } I_{\text{SENSE max}}$ (see Figure 7) | | 5 | 20 | μs |

1. Parameter guaranteed by design; it is not tested.
2. Fault condition includes: power limitation, overtemperature and open-load in OFF-state condition.

Table 10. Open-load detection

| Symbol | Parameter | Test conditions | Min. | Typ. | Max. | Unit |
|-------------------------|---|--|------|------|------|---------------|
| V_{OL} | Open-load off-state voltage detection threshold | $V_{\text{IN}} = 0 \text{ V}; 8 \text{ V} < V_{\text{CC}} < 36 \text{ V};$ $F_{\text{R_STBY}} = 5 \text{ V}$ | 2 | — | 4 | V |
| t_{DSTKON} | Output short circuit to V _{CC} detection delay at turn off | See Figure 7 ; $F_{\text{R_STBY}} = 5 \text{ V}$ | 180 | — | 1800 | μs |
| $t_{\text{DFRSTK_ON}}$ | Output short circuit to V _{CC} detection delay at FRSTBY activation | See Figure 10 ; Input _{1,2} = low | | — | 50 | μs |
| $I_{\text{L(off2)}}$ | Off-state output current at V _{OUT} = 4V | $V_{\text{IN}} = 0 \text{ V}; V_{\text{SENSE}} = 0 \text{ V};$ V_{OUT} rising from 0 V to 4 V; $F_{\text{R_STBY}} = 5 \text{ V}$ | -120 | — | 0 | μA |
| $t_{\text{d_vol}}$ | Delay response from output rising edge to V _{SENSE} rising edge in open-load | $V_{\text{OUT}} = 4 \text{ V}; V_{\text{IN}} = 0 \text{ V};$ $V_{\text{SENSE}} = 90 \% \text{ of } V_{\text{SENSEH}};$ $R_{\text{SENSE}} = 3.9 \text{ K}\Omega;$ $F_{\text{R_STBY}} = 5 \text{ V}$ | | — | 20 | μs |

Figure 7. Current sense delay characteristics

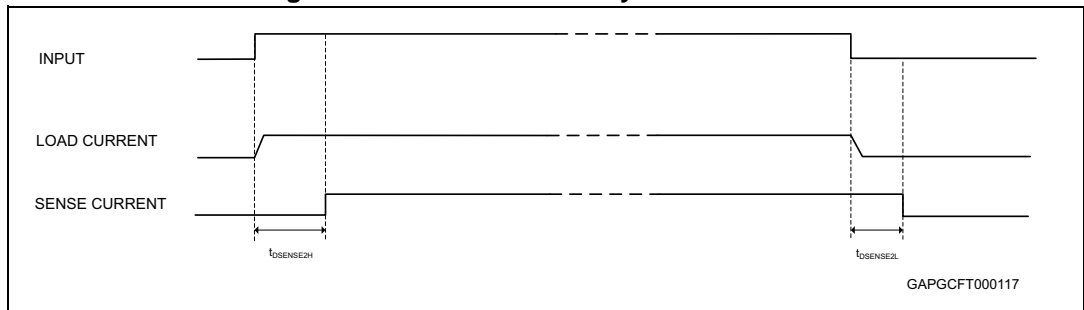


Figure 8. Open-load off-state delay timing

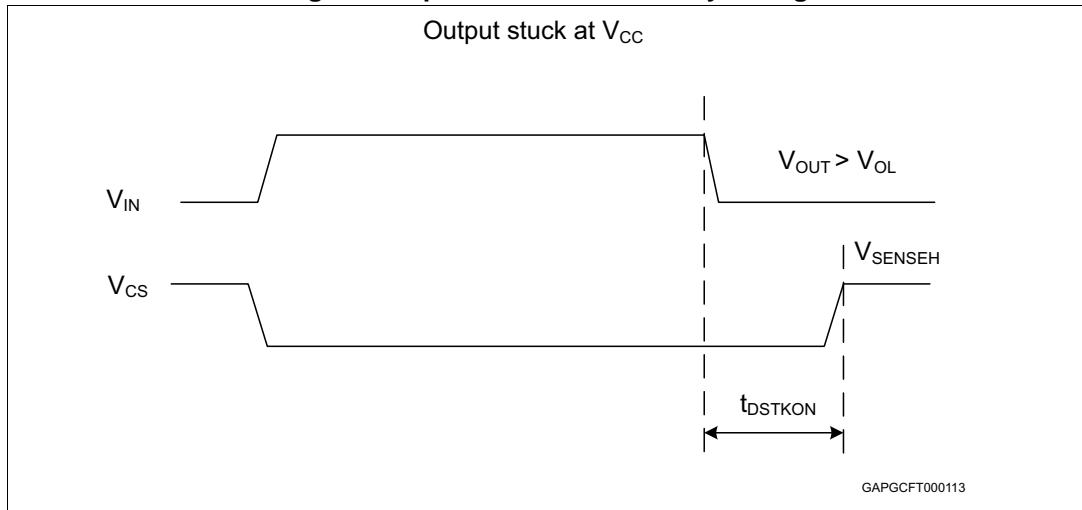


Figure 9. Switching characteristics

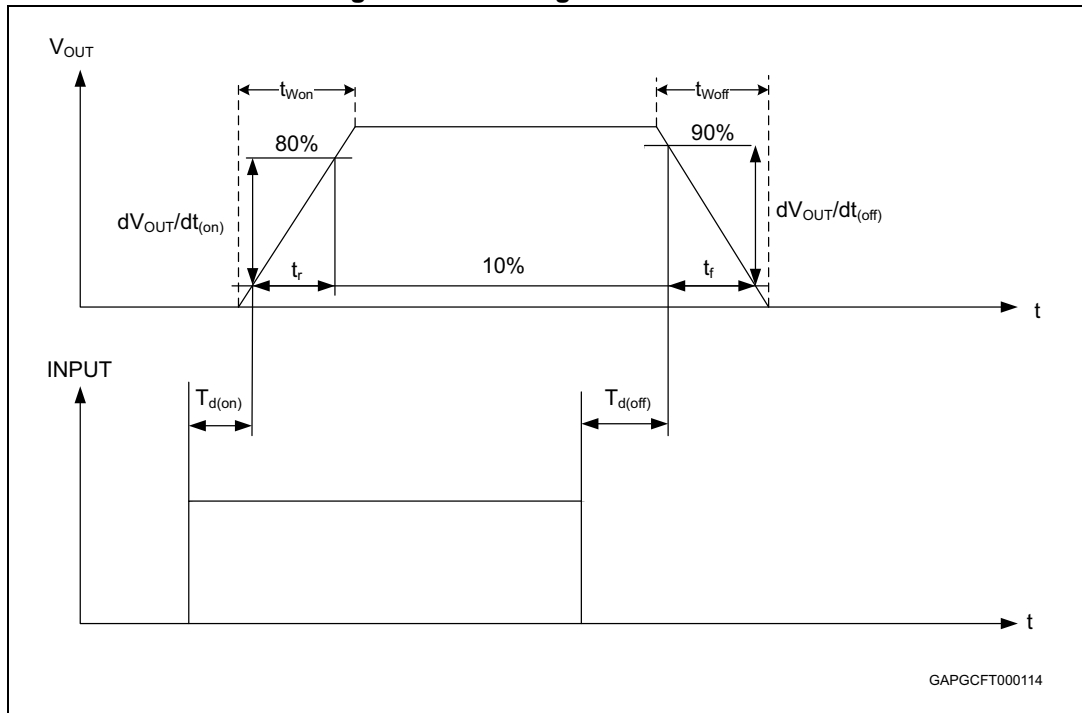


Figure 10. Output stuck to V_{CC} detection delay time at FR_{STBY} activation

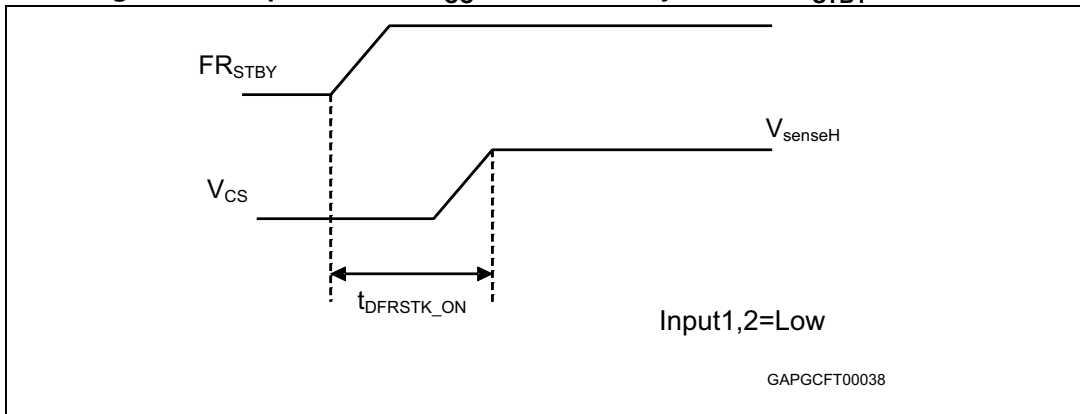


Figure 11. Delay response time between rising edge of output current and rising edge of current sense

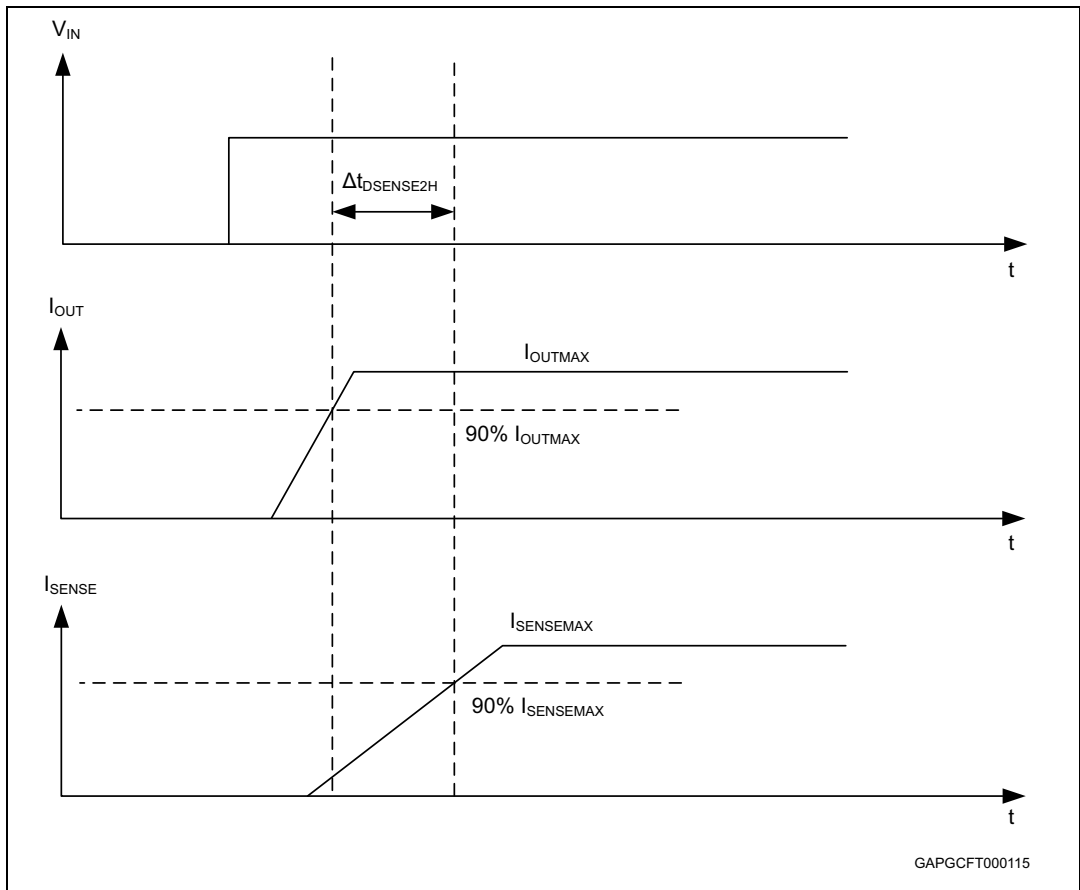


Figure 12. Output voltage drop limitation

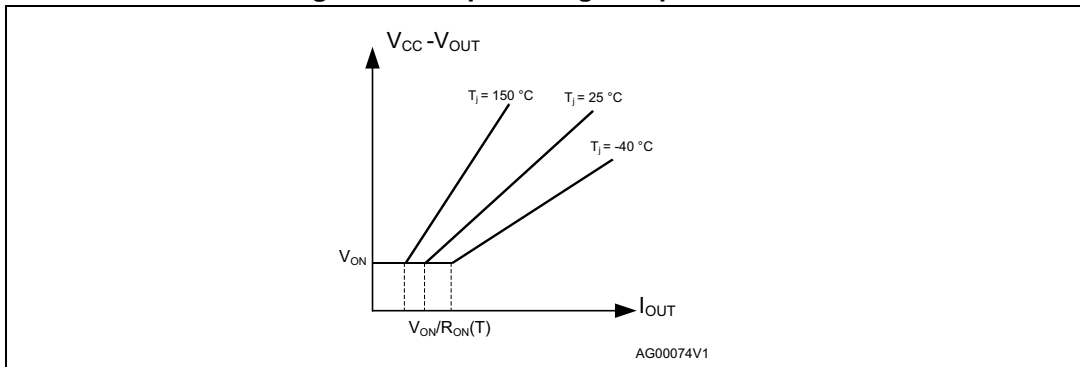


Figure 13. Device behavior in overload condition

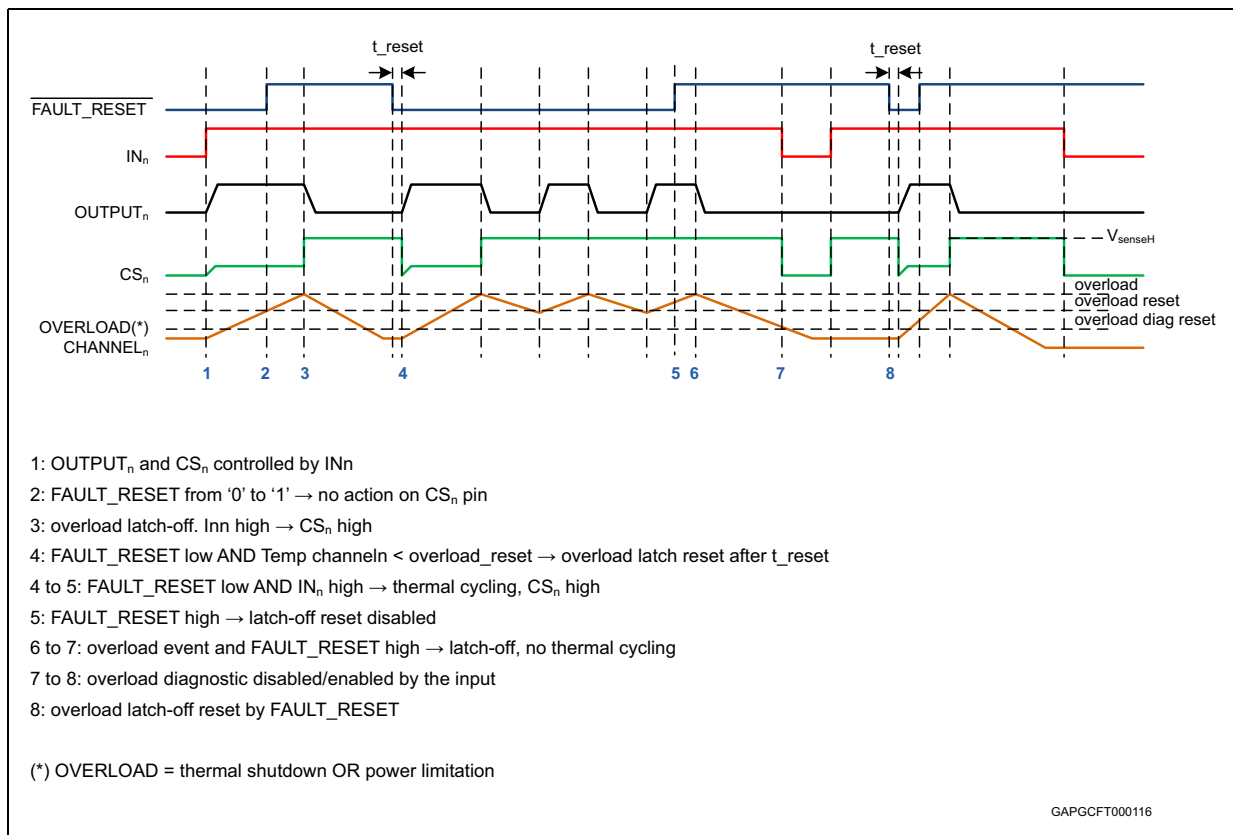


Table 11. Truth table

| Conditions | Fault reset standby | Input | Output | Sense |
|------------------------------------|---------------------|-------|----------|--------------|
| Standby | L | L | L | 0 |
| Normal operation | X | L | L | 0 |
| | X | H | H | Nominal |
| Overload | X | L | L | 0 |
| | X | H | H | > Nominal |
| Overtemperature / short to ground | X | L | L | 0 |
| | L | H | Cycling | V_{SENSEH} |
| | H | H | Latched | V_{SENSEH} |
| Undervoltage | X | X | L | 0 |
| Short to V_{BAT} | L | L | H | 0 |
| | H | L | H | V_{SENSEH} |
| | X | H | H | < Nominal |
| Open-load off-state (with pull-up) | L | L | H | 0 |
| | H | L | H | V_{SENSEH} |
| | X | H | H | 0 |
| Negative output voltage clamp | X | L | Negative | 0 |

Table 12. Electrical transient requirements (part 1)

| ISO 7637-2: 2004(E) Test pulse | Test levels ⁽¹⁾ | | Number of pulses or test times | Burst cycle/pulse repetition time | | Delays and impedance |
|--------------------------------------|----------------------------|---------|--------------------------------|-----------------------------------|--------|----------------------|
| | III | IV | | | | |
| 1 | - 450 V | - 600 V | 5000 pulses | 0.5 s | 5 s | 1 ms, 50 Ω |
| 2a | + 37 V | + 50 V | 5000 pulses | 0.2 s | 5 s | 50 μs, 2 Ω |
| 3a | - 150 V | - 200 V | 1h | 90 ms | 100 ms | 0.1 μs, 50 Ω |
| 3b | + 150 V | + 200 V | 1h | 90 ms | 100 ms | 0.1 μs, 50 Ω |
| 4 | - 12 V | - 16 V | 1 pulse | | | 100 ms, 0.01 Ω |
| 5b ⁽²⁾ | + 123 V | + 174 V | 1 pulse | | | 350 ms, 1 Ω |

Table 13. Electrical transient requirements (part 2)

| ISO 7637-2: 2004(E) Test pulse | Test level results | |
|--------------------------------------|--------------------|----|
| | III | IV |
| 1 | C | C |
| 2a | C | C |
| 3a | C | C |
| 3b ⁽¹⁾ | E | E |
| 3b ⁽²⁾ | C | C |
| 4 | C | C |
| 5b ⁽³⁾ | C | C |

1. Without capacitor between V_{CC} and GND.
2. With 10 nF between V_{CC} and GND.
3. External load dump clamp, 58 V maximum, referred to ground.

Table 14. Electrical transient requirements (part 3)

| Class | Contents |
|-------|--|
| C | All functions of the device are performed as designed after exposure to disturbance. |
| E | One or more functions of the device are not performed as designed after exposure to disturbance and cannot be returned to proper operation without replacing the |

2.4 Electrical characteristics curves

Figure 14. Off-state output current

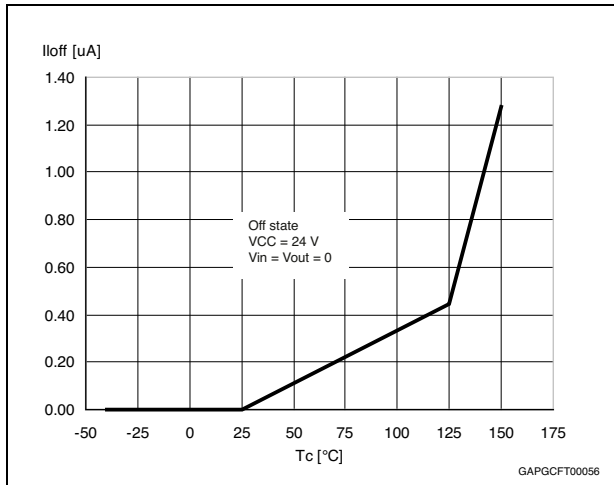


Figure 15. High level input current

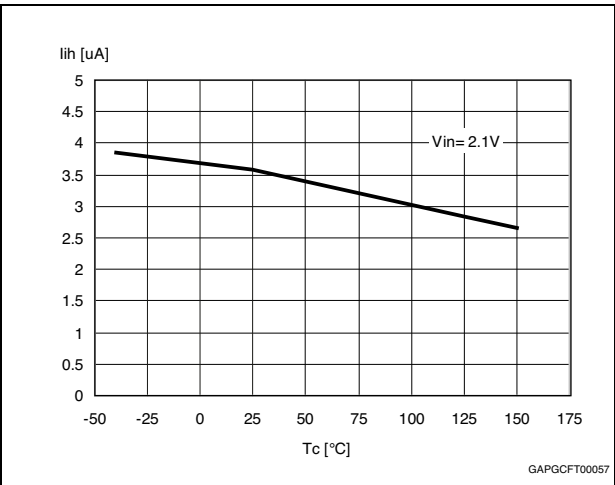


Figure 16. Input clamp voltage

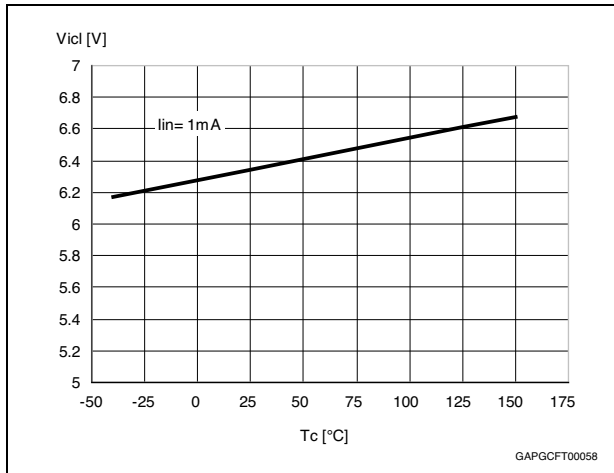


Figure 17. Input high level voltage

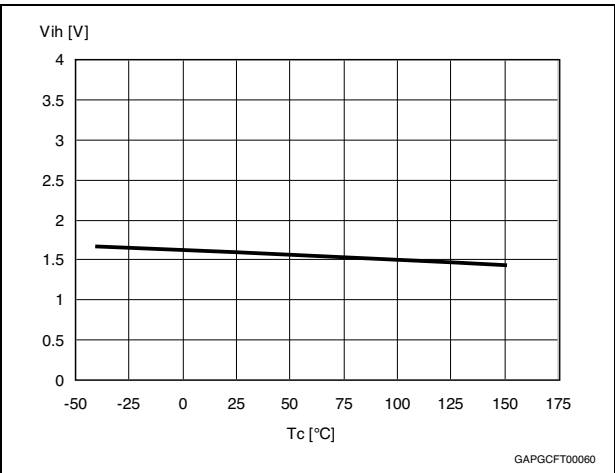


Figure 18. Input low level voltage

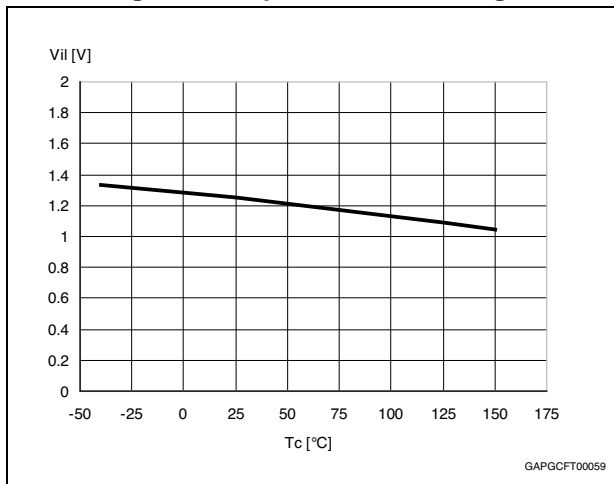


Figure 19. Input hysteresis voltage

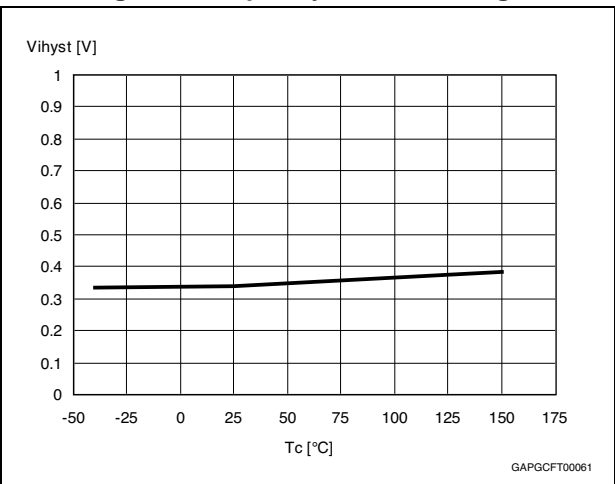


Figure 20. On-state resistance vs T_{case}

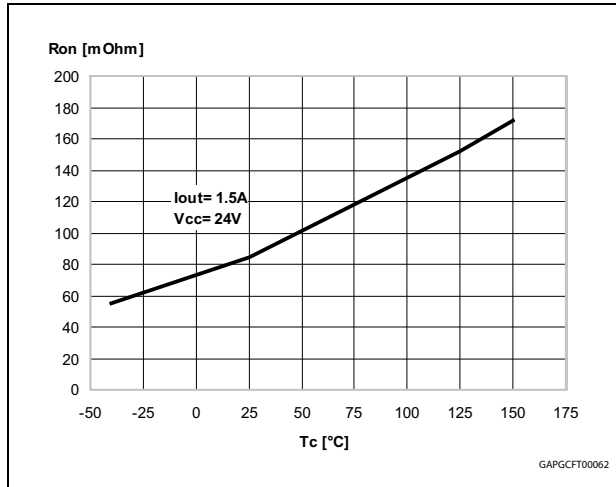


Figure 21. On-state resistance vs V_{CC}

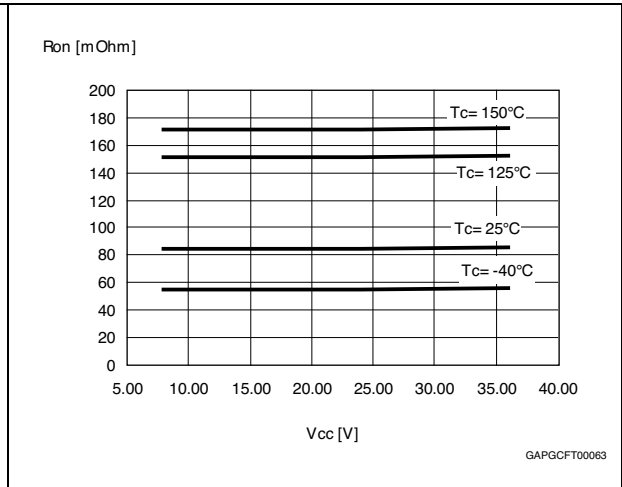


Figure 22. I_{LIMH} vs T_{case}

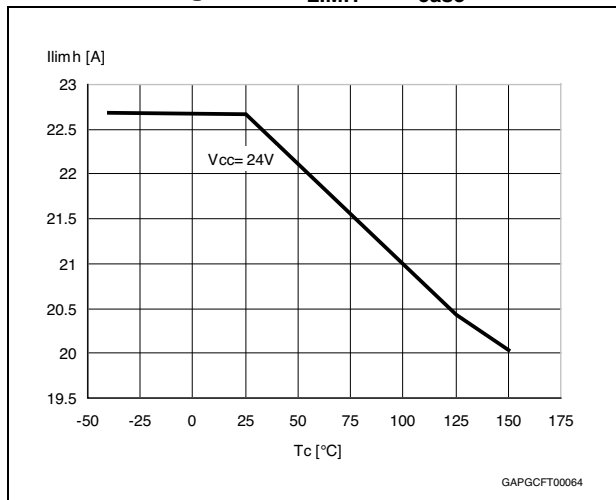


Figure 23. Turn-on voltage slope

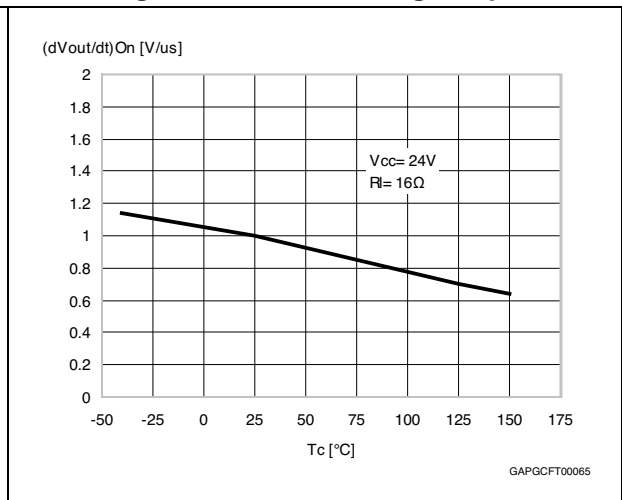
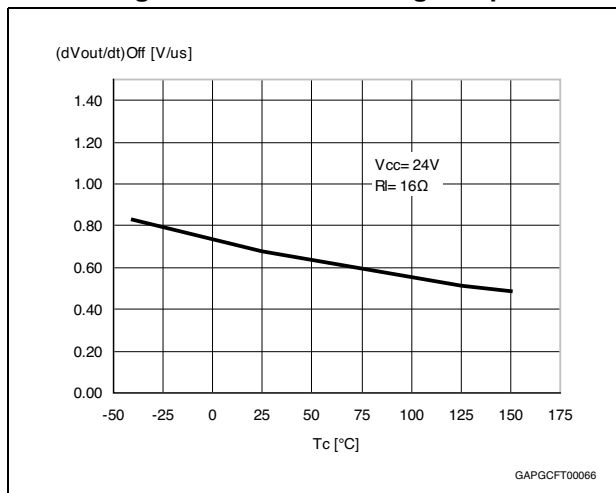
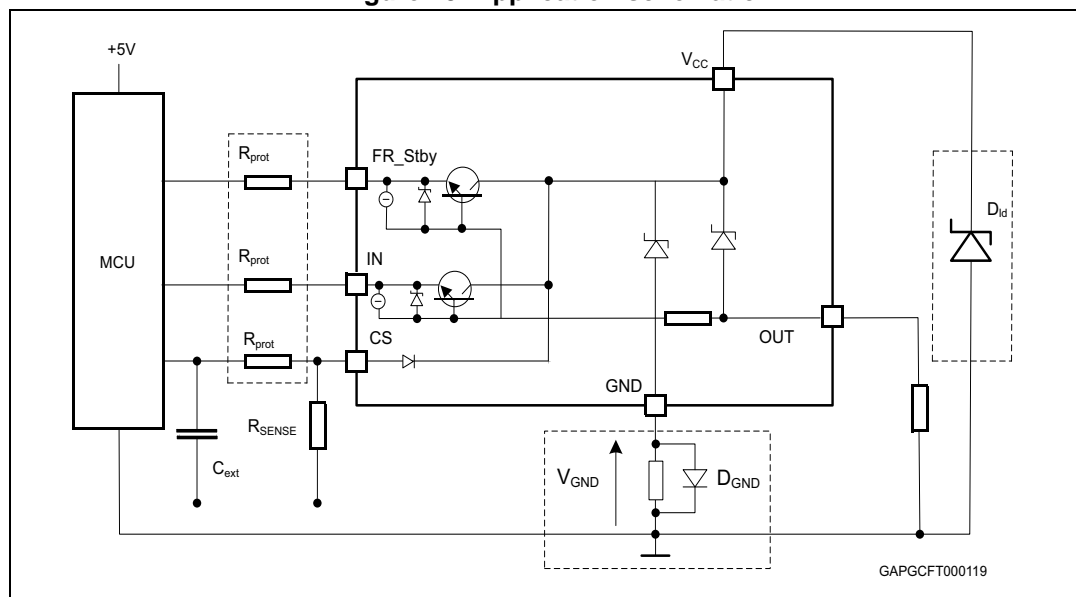


Figure 24. Turn-off voltage slope



3 Application information

Figure 25. Application schematic



3.1 GND protection network against reverse battery

3.1.1 Solution 1: resistor in the ground line (R_{GND} only)

This solution can be used with any type of load.

The following is an indication on how to select the R_{GND} resistor.

1. $R_{GND} \leq 600 \text{ mV} / (I_{S(on)max})$.
2. $R_{GND} \geq (-V_{CC}) / (-I_{GND})$

where $-I_{GND}$ is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device datasheet.

Power dissipation in R_{GND} (when $V_{CC} < 0$: during reverse battery situations) is:

$$P_D = (-V_{CC})^2 / R_{GND}$$

This resistor can be shared amongst several different HSDs. Please note that the value of this resistor should be calculated with formula (1) where $I_{S(on)max}$ becomes the sum of the maximum on-state currents of the different devices.

Please note that if the microprocessor ground is not shared by the device ground then the R_{GND} produces a shift ($I_{S(on)max} * R_{GND}$) in the input thresholds and the status output values. This shift varies depending on how many devices are ON in case of several high side drivers sharing the same R_{GND} .

If the calculated power dissipation leads to a large resistor or several devices have to share the same resistor then ST suggests Solution 2 is used (see below).

3.1.2 Solution 2: diode (D_{GND}) in the ground line

A resistor ($R_{GND} = 4.7 \text{ k}\Omega$) should be inserted in parallel to D_{GND} if the device drives an inductive load.

This small signal diode can be safely shared amongst several different HSDs. Also in this case, the presence of the ground network produces a shift ($\approx 600 \text{ mV}$) in the input threshold and in the status output values, if the microprocessor ground is not common to the device ground. This shift does not vary if more than one HSD shares the same diode/resistor network.

3.2 Load dump protection

D_{ld} is necessary (Voltage Transient Suppressor) if the load dump peak voltage exceeds to V_{CC} max DC rating. The same applies if the device is subject to transients on the V_{CC} line that are greater than the ones shown in the ISO T/R 7637/2 table.

3.3 MCU I/Os protection

If a ground protection network is used and negative transient are present on the V_{CC} line, the control pins are pulled negative. ST suggests that a resistor (R_{prot}) be inserted in line to prevent the microcontroller I/O pins from latching-up.

The value of these resistors is a compromise between the leakage current of microcontroller and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of microcontroller I/Os.

$$-V_{CCpeak}/I_{latchup} \leq R_{prot} \leq (V_{OH\mu C} - V_{IH} - V_{GND}) / I_{IHmax}$$

Calculation example:

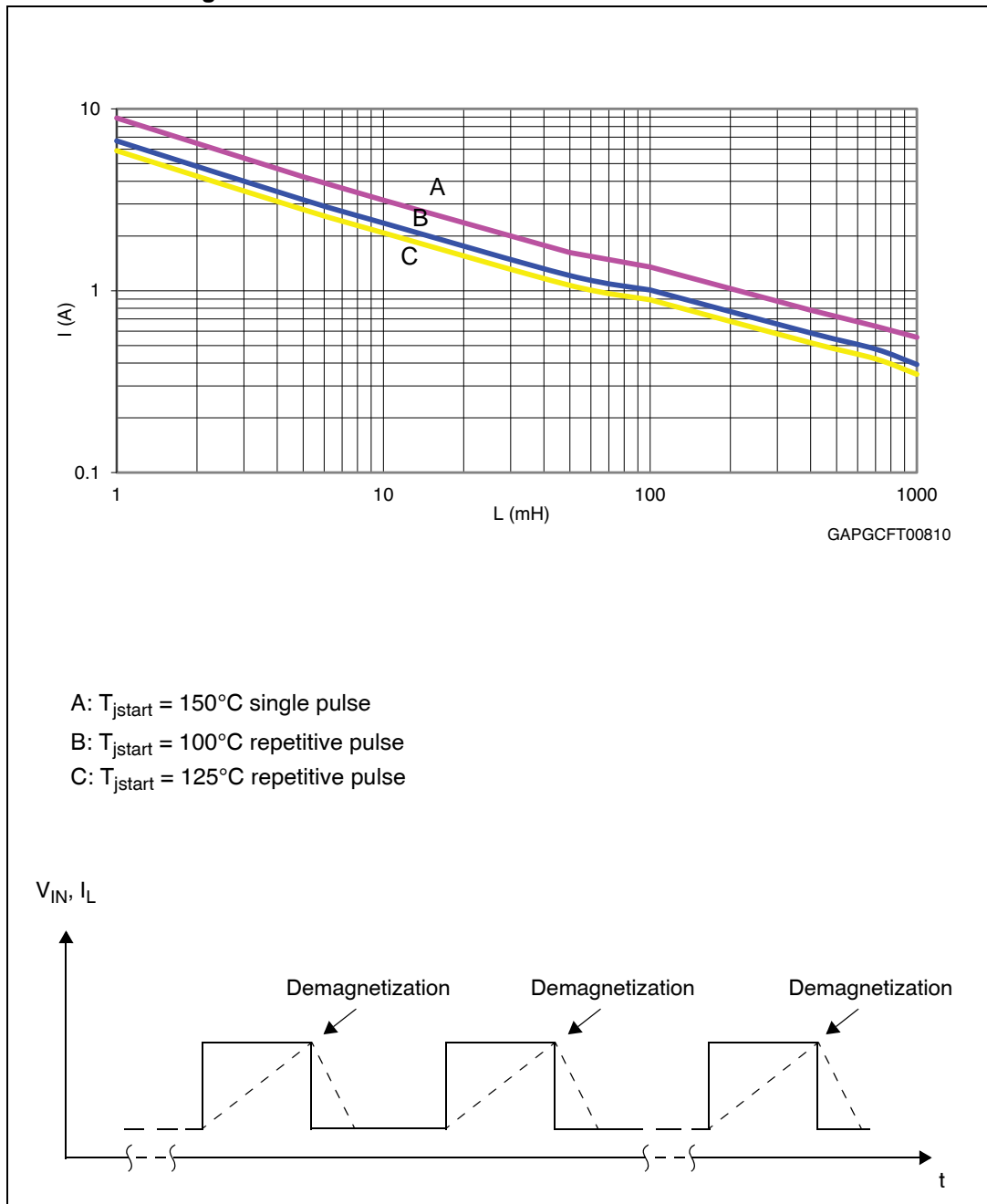
For $V_{CCpeak} = -600 \text{ V}$ and $I_{latchup} \geq 20 \text{ mA}$; $V_{OH\mu C} \geq 4.5 \text{ V}$

$$30 \text{ k}\Omega \leq R_{prot} \leq 180 \text{ k}\Omega.$$

Recommended R_{prot} value is $60 \text{ k}\Omega$.

3.4 Maximum demagnetization energy ($V_{CC} = 24\text{ V}$)

Figure 26. Maximum turn-off current versus inductance

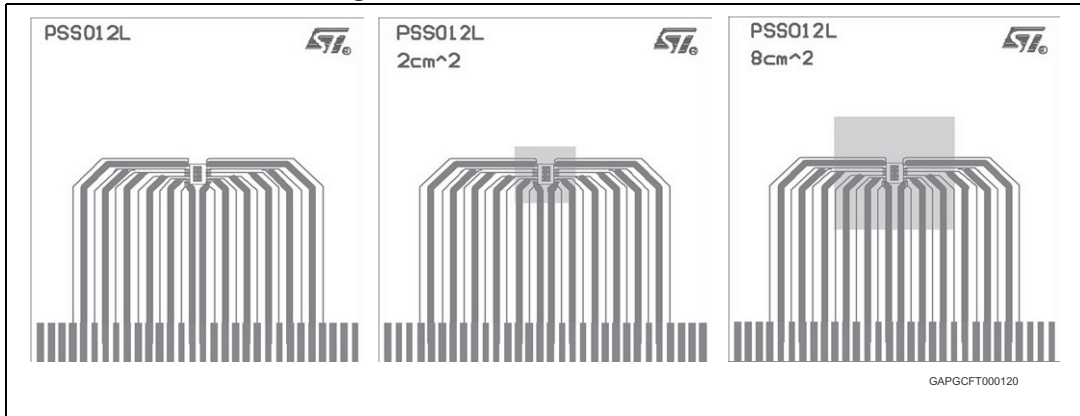


1. Values are generated with $R_L = 0\ \Omega$.
 In case of repetitive pulses, T_{jstart} (at the beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves A and B.

4 Package and PCB thermal data

4.1 PowerSSO-12 thermal data

Figure 27. PowerSSO-12 PC board



1. Layout condition of R_{th} and Z_{th} measurements (Board finish thickness 1.6 mm +/- 10 %; Board double layer; Board dimension 77 mm x 86 mm; Board Material FR4; Cu thickness 0.070 mm (front and back side); Thermal vias separation 1.2 mm; Thermal via diameter 0.3 mm +/- 0.08 mm; Cu thickness on vias 0.025 mm; Footprint dimension 4.1 mm x 6.5 mm)

Figure 28. $R_{thj-amb}$ vs PCB copper area in open box free air condition (one channel ON)

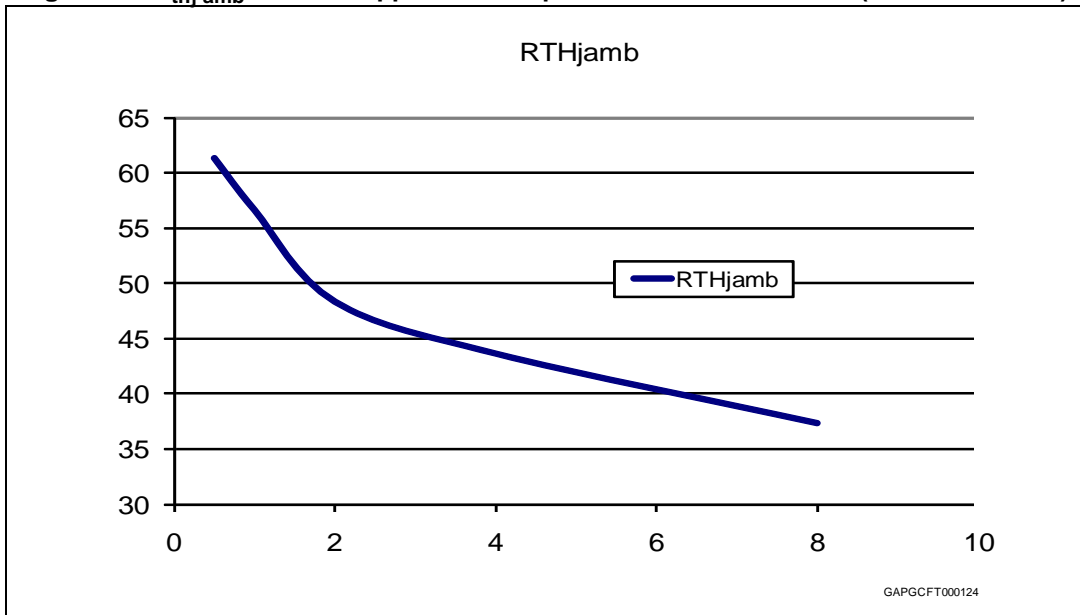


Figure 29. PowerSSO-12 thermal impedance junction ambient single pulse (one channel ON)

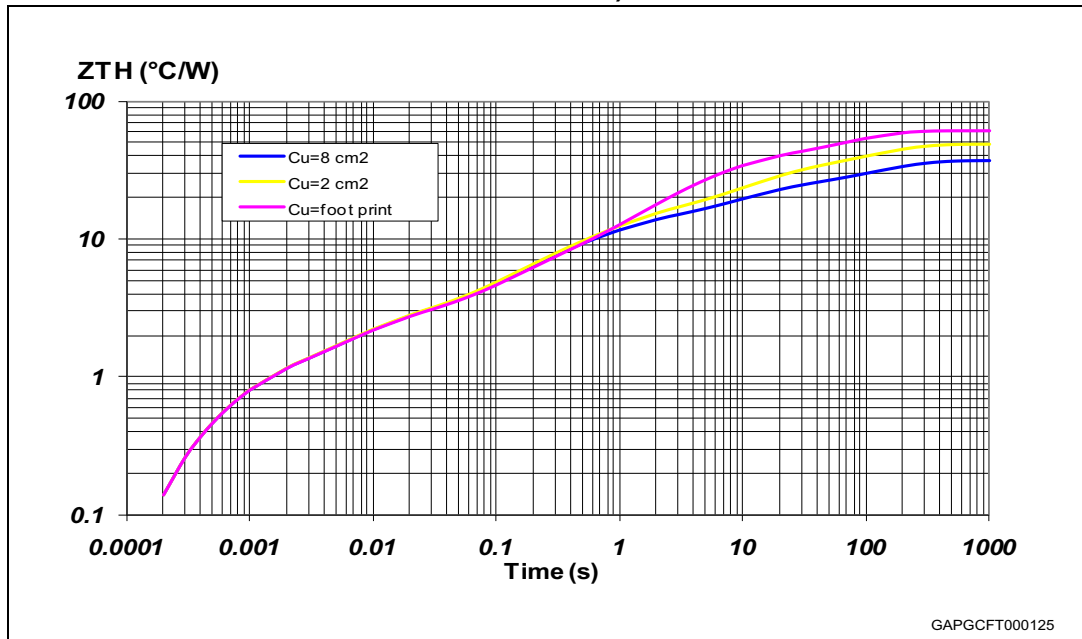
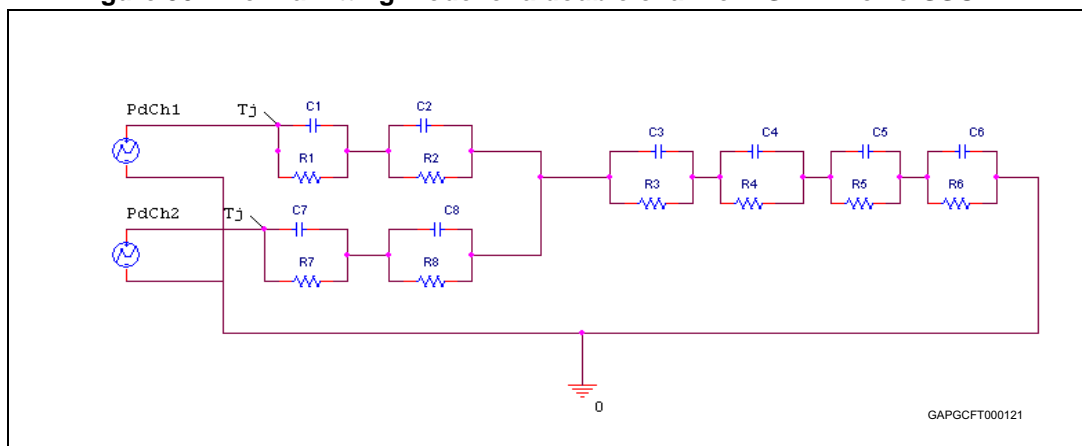


Figure 30. Thermal fitting model of a double channel HSD in PowerSSO-12



1. The fitting model is a simplified thermal tool and is valid for transient evolutions where the embedded protections (power limitation or thermal cycling during thermal shutdown) are not triggered.

Equation 1: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

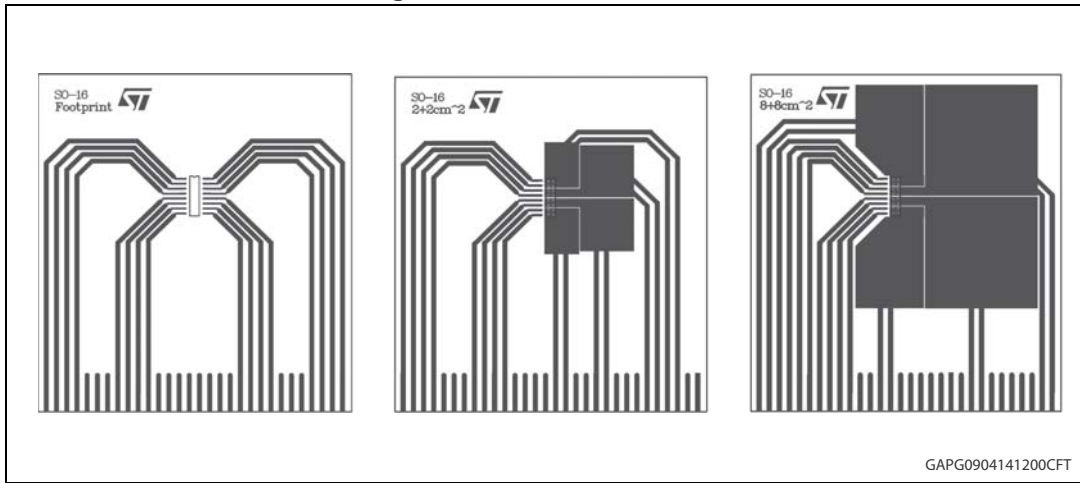
where $\delta = t_p/T$

Table 15. Thermal parameters

| Area/island (cm ²) | Footprint | 2 | 8 |
|--------------------------------|-----------|-----|-----|
| R1 = R7 (°C/W) | 0.8 | | |
| R2 = R8 (°C/W) | 1.5 | | |
| R3 (°C/W) | 3 | | |
| R4 (°C/W) | 8 | 8 | 7 |
| R5 (°C/W) | 22 | 15 | 10 |
| R6 (°C/W) | 26 | 20 | 15 |
| C1 = C7 (W.s/°C) | 0.0008 | | |
| C2 = C8 (W.s/°C) | 0.005 | | |
| C3 (W.s/°C) | 0.05 | | |
| C4 (W.s/°C) | 0.2 | 0.1 | 0.1 |
| C5 (W.s/°C) | 0.27 | 0.8 | 1 |
| C6 (W.s/°C) | 3 | 6 | 9 |

4.2 SO-16N thermal data

Figure 31. SO-16N PC board



1. Layout condition of Rth and Zth measurements (Board finish thickness 1.6 mm +/- 10%; Board double layer; Board dimension 129 x 60; Board Material FR4; Cu thickness 0.070mm (front and back side), Thermal vias separation 1.2 mm; Thermal via diameter 0.3 mm +/- 0.08 mm; Cu thickness on vias 0.025 mm).

Figure 32. $R_{thj-amb}$ vs PCB copper area in open box free air condition (one channel ON)

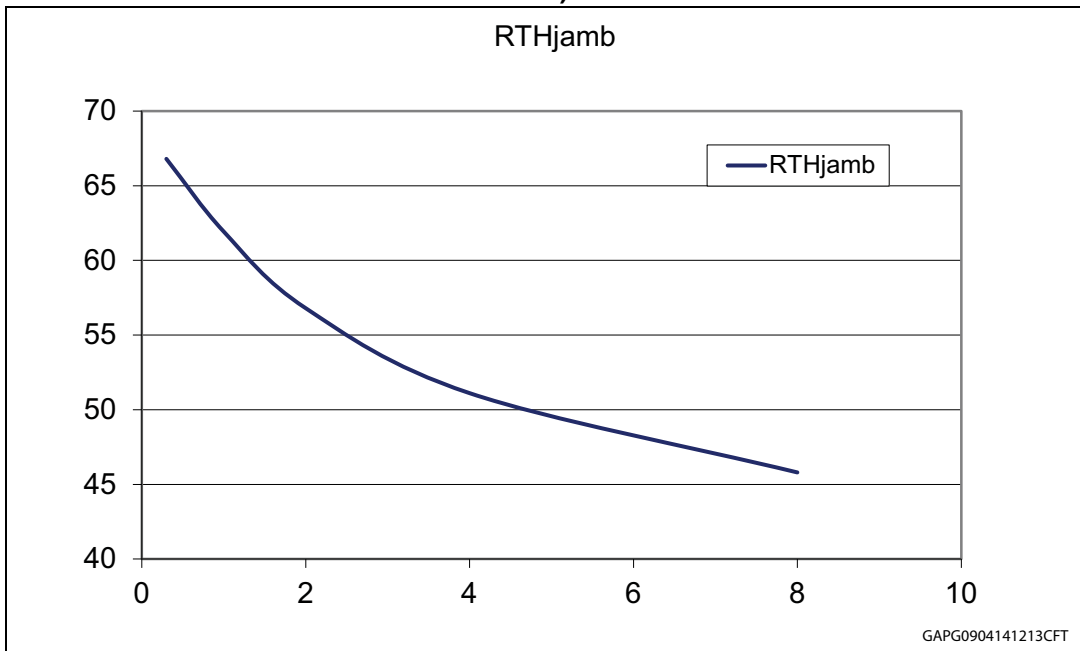


Figure 33. SO-16N thermal impedance junction ambient single pulse (one channel on)

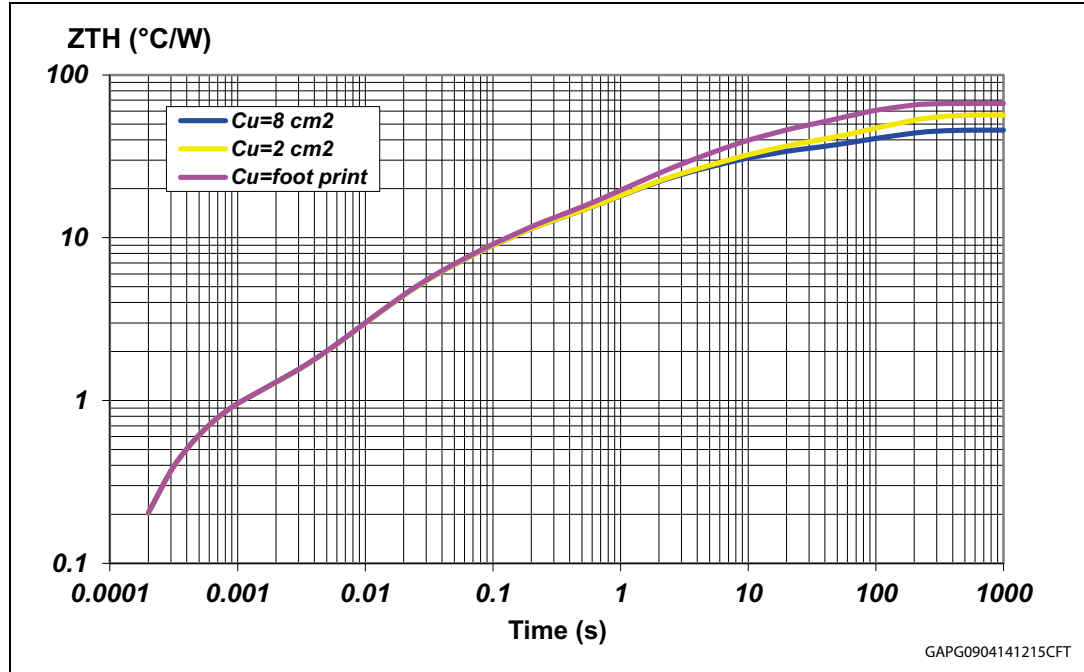
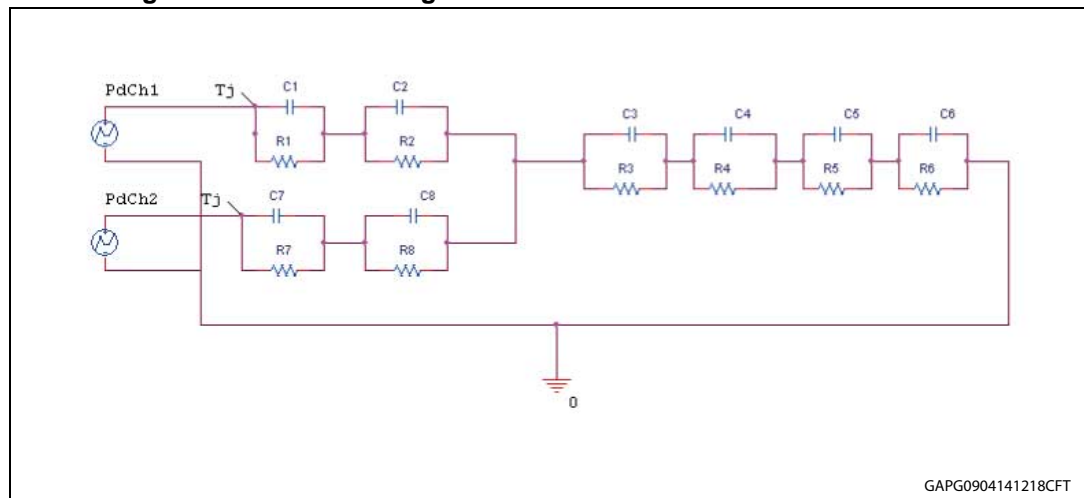


Figure 34. Thermal fitting model of a double channel HSD in SO-16N



Equation 2: pulse calculation formula

$$Z_{TH\delta} = R_{TH} \cdot \delta + Z_{THtp}(1 - \delta)$$

where $\delta = t_p/T$

Table 16. Thermal parameters

| Area/island (cm ²) | Footprint | 2 | 8 |
|--------------------------------|-----------|-----|-----|
| R1 = R7 (°C/W) | 0.8 | | |
| R2 = R8(°C/W) | 3 | | |
| R3 (°C/W) | 6 | | |
| R4 (°C/W) | 10 | | |
| R5 (°C/W) | 20 | 14 | 12 |
| R6 (°C/W) | 27 | 23 | 14 |
| C1 = C7(W.s/°C) | 0.0005 | | |
| C2 = C8 (W.s/°C) | 0.005 | | |
| C3 (W.s/°C) | 0.015 | | |
| C4 (W.s/°C) | 0.1 | | |
| C5 (W.s/°C) | 0.3 | 0.5 | 0.5 |
| C6 (W.s/°C) | 2.5 | 5 | 7 |

5 Package and packing information

5.1 ECOPACK®

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com.

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5.2 PowerSSO-12 mechanical data

Figure 35. PowerSSO-12 package dimensions

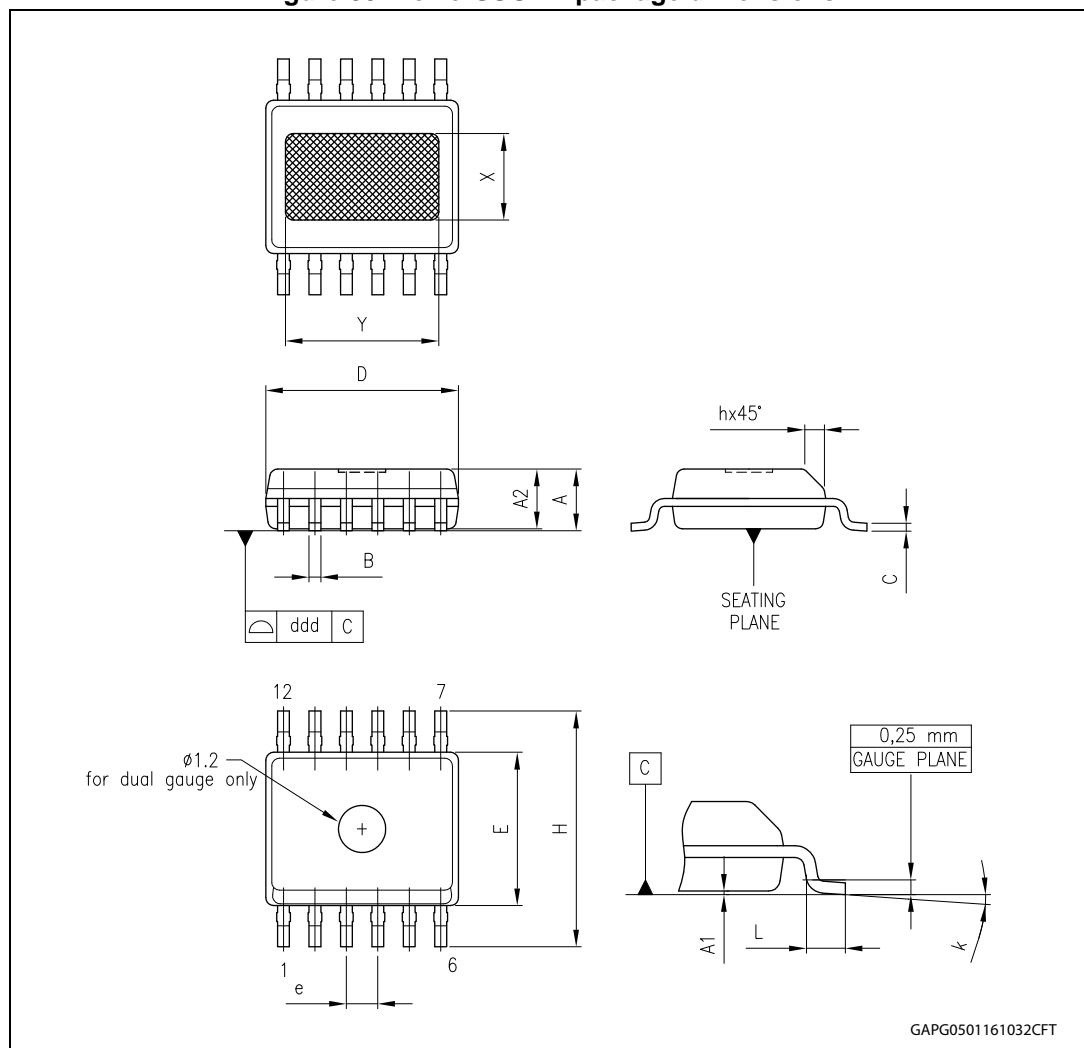


Table 17. PowerSSO-12 mechanical data

| Symbol | Millimeters | | |
|--------|-------------|-------|-------|
| | Min. | Typ. | Max. |
| A | 1.250 | | 1.700 |
| A1 | 0.000 | | 0.100 |
| A2 | 1.100 | | 1.600 |
| B | 0.230 | | 0.410 |
| C | 0.190 | | 0.250 |
| D | 4.800 | | 5.000 |
| E | 3.800 | | 4.000 |
| e | | 0.800 | |
| H | 5.800 | | 6.200 |
| h | 0.250 | | 0.550 |
| L | 0.400 | | 1.270 |
| k | 0° | | 8° |
| X | 1.900 | | 2.500 |
| Y | 3.600 | | 4.200 |
| ddd | | | 0.100 |

5.3 SO-16N package information

Figure 36. SO-16N package dimensions

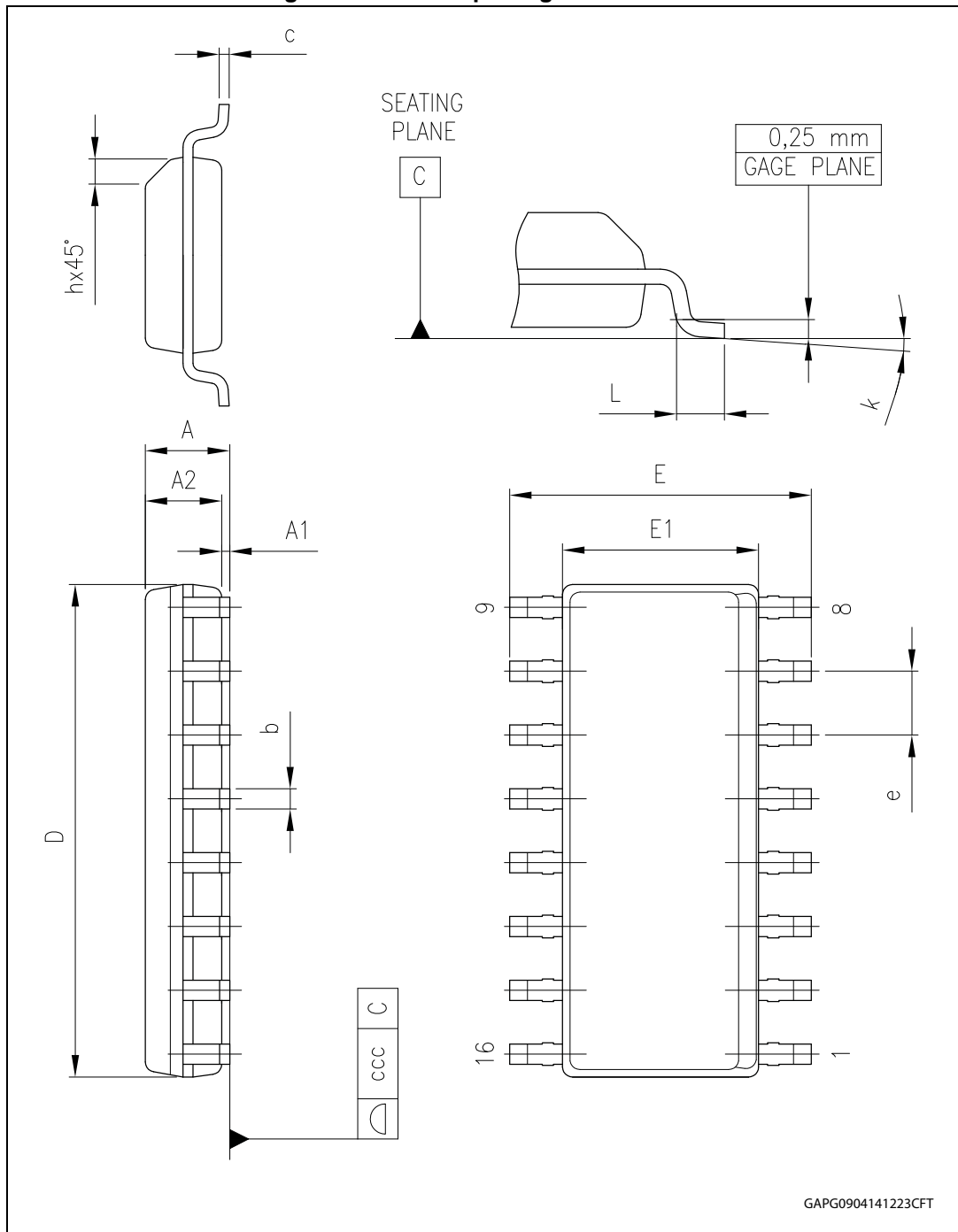


Table 18. SO-16N mechanical data

| Symbol | Millimeters | | |
|--------|-------------|------|-------|
| | Min. | Typ. | Max. |
| A | | | 1.75 |
| A1 | 0.10 | | 0.25 |
| A2 | 1.25 | | |
| b | 0.31 | | 0.51 |
| c | 0.17 | | 0.25 |
| D | 9.80 | 9.90 | 10.00 |
| E | 5.80 | 6.00 | 6.20 |
| E1 | 3.80 | 3.90 | 4.00 |
| e | | 1.27 | |
| h | 0.25 | | 0.50 |
| L | 0.40 | | 1.27 |
| k | 0° | | 8° |
| ccc | | | 0.10 |

6 Packing information

6.1 PowerSSO-12 packing information

Figure 37. PowerSSO-12 tube shipment (no suffix)

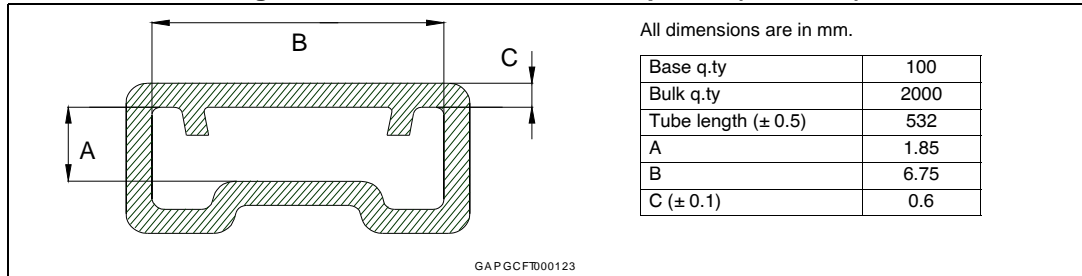
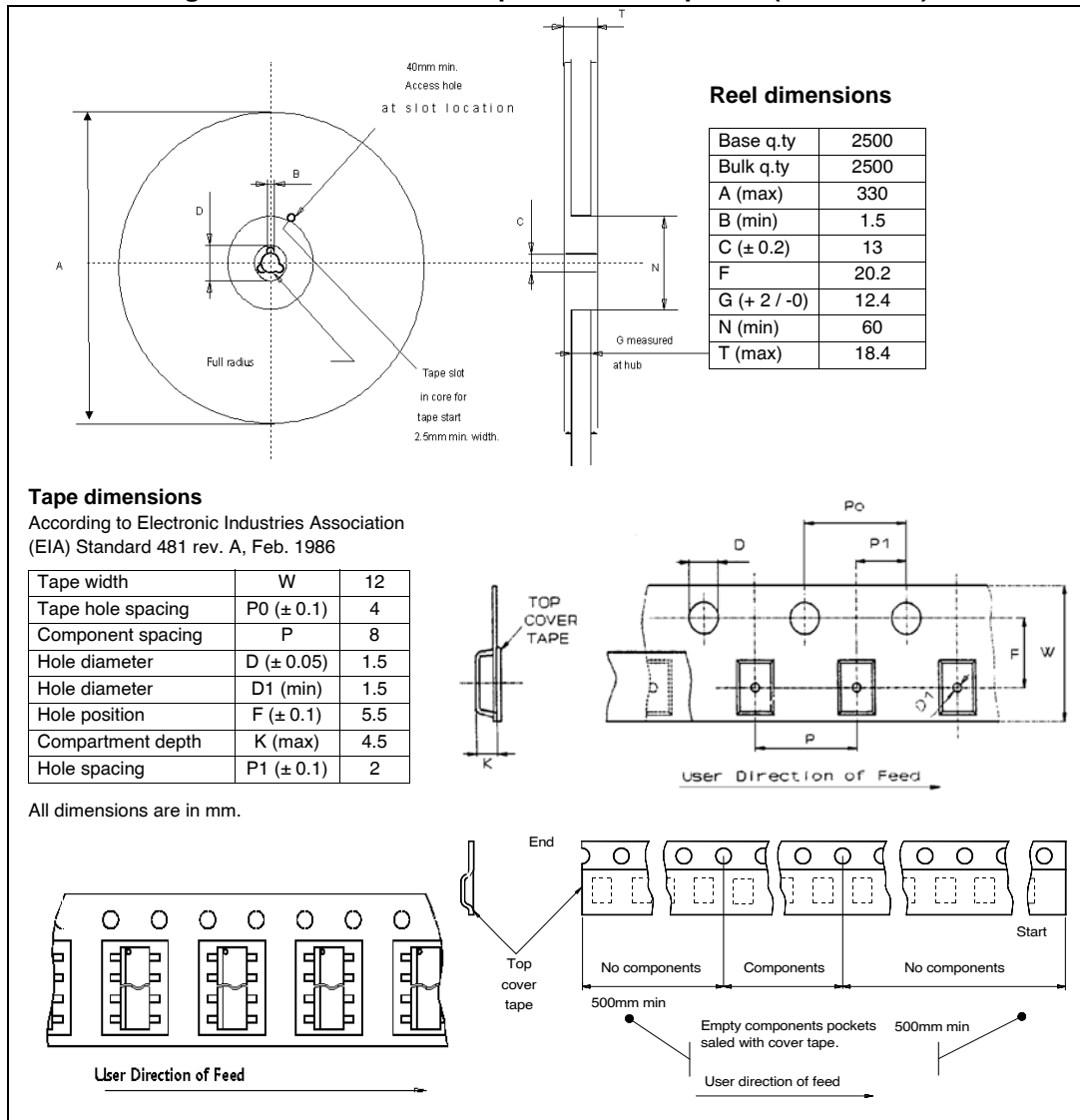


Figure 38. PowerSSO-12 tape and reel shipment (suffix "TR")



6.2 SO-16N packing information

Figure 39. SO-16N tube shipment (no suffix)

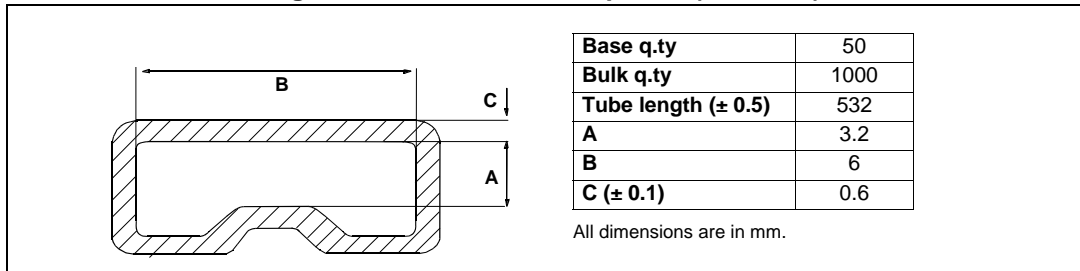
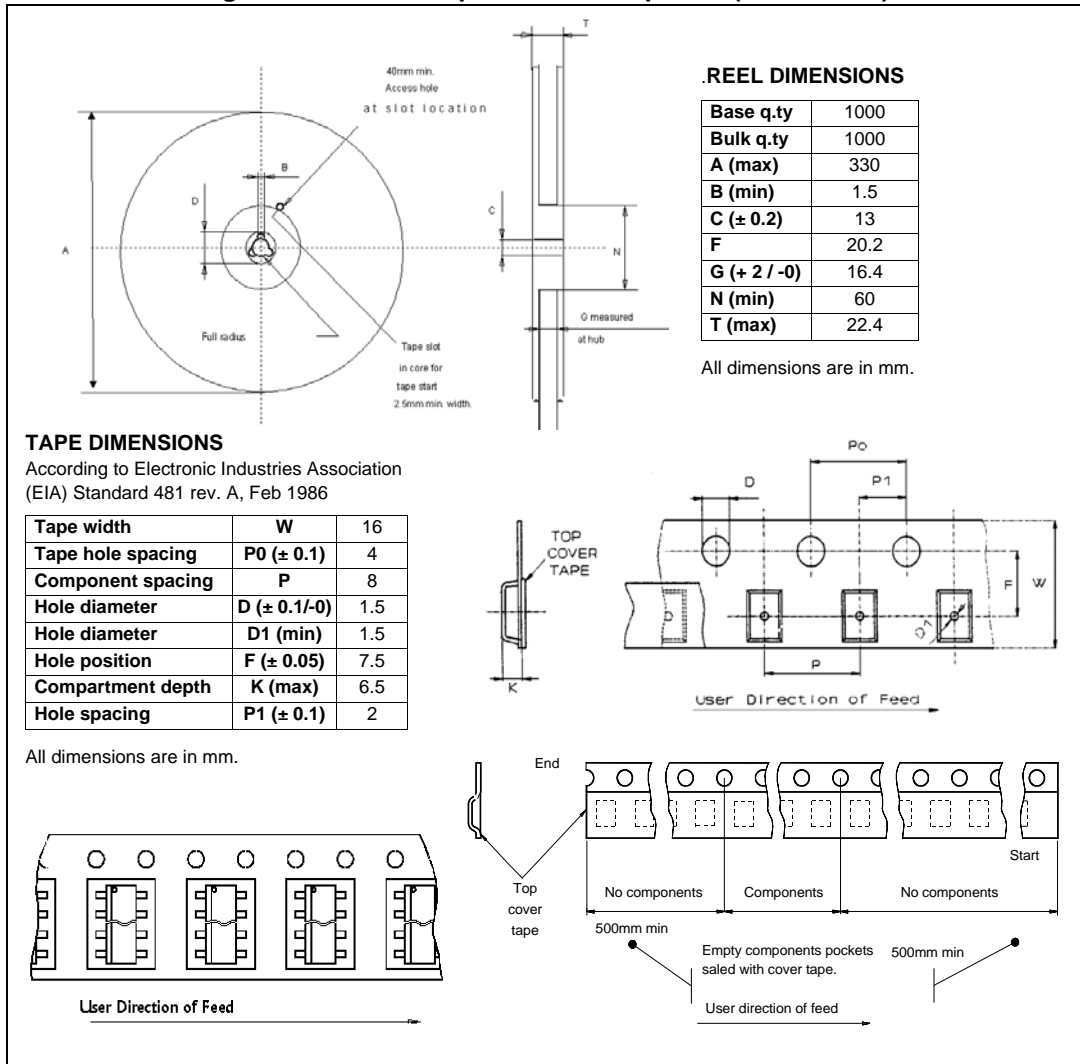


Figure 40. SO-16N tape and reel shipment (suffix "TR")



7 Order code

Table 19. Device summary

| Package | Order codes | |
|-------------|---------------|-----------------|
| | Tube | Tape and reel |
| PowerSSO-12 | VND5T100LAJ-E | VND5T100LAJTR-E |
| SO-16N | VND5T100LAS-E | VND5T100LASTR-E |

8 Revision history

Table 20. Document revision history

| Date | Revision | Changes |
|-------------|----------|---|
| 25-Jun-2012 | 1 | Initial release. |
| 18-Sep-2013 | 2 | Updated disclaimer. |
| 30-Apr-2014 | 3 | Added SO-16N package and related details. |
| 08-Feb-2016 | 4 | <i>Table 4: Thermal data:</i> – $R_{thj-case}$: updated values – $R_{thj-pin}$: added row Updated <i>Section 5.2: PowerSSO-12 mechanical data</i> and <i>Section 5.3: SO-16N package information</i> |
| 23-Aug-2016 | 5 | Added indication of AEC-Q100 qualification in <i>Features</i> . Updated <i>Figure 3: Configuration diagram SO-16N (top view)</i> . |

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