



# 0.5°C Digital Out Temperature Sensor

## FEATURES

- 8 ADDRESSES
- DIGITAL OUTPUT: Two-Wire Serial Interface
- RESOLUTION: 9- to 12-Bits, User-Selectable
- ACCURACY:  
±0.5°C (max) from +10°C to +85°C  
±0.75°C (max) from +0°C to +100°C
- LOW QUIESCENT CURRENT:  
50µA, 0.1µA Standby
- WIDE SUPPLY RANGE: 2.7V to 5.5V
- SMALL MSOP-8 PACKAGE

## APPLICATIONS

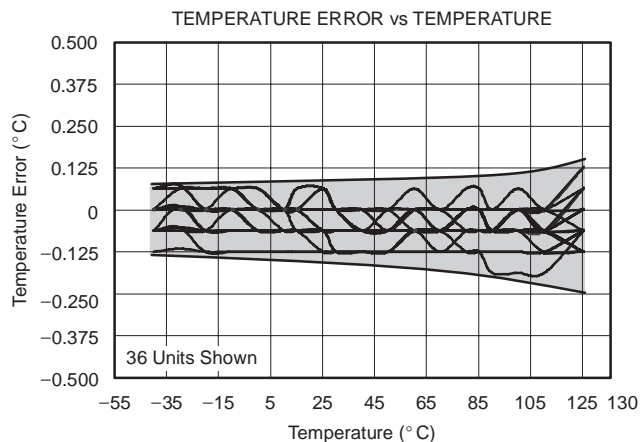
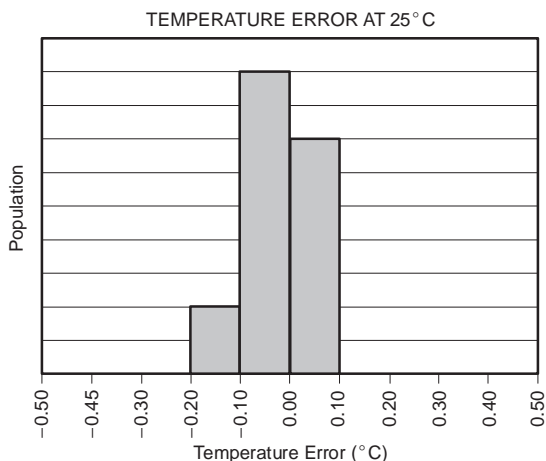
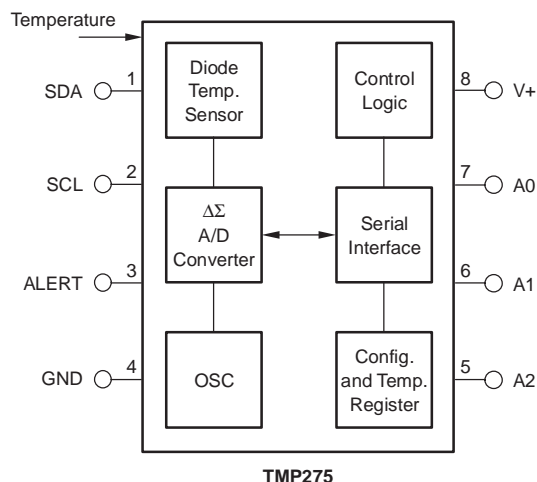
- POWER-SUPPLY TEMPERATURE MONITORING
- COMPUTER PERIPHERAL THERMAL PROTECTION
- NOTEBOOK COMPUTERS
- CELL PHONES
- BATTERY MANAGEMENT
- OFFICE MACHINES
- THERMOSTAT CONTROLS
- ENVIRONMENTAL MONITORING AND HVAC
- ELECTROMECHANICAL DEVICE TEMPERATURE

## DESCRIPTION

The TMP275 is a 0.5°C accurate, two-wire, serial output temperature sensor available in the MSOP-8 package. The TMP275 is capable of reading temperatures with a resolution of 0.0625°C.

The TMP275 is SMBus-compatible and allows up to eight devices on one bus. It is ideal for extended temperature measurement in a variety of communication, computer, consumer, environmental, industrial, and instrumentation applications.

The TMP275 is specified for operation over a temperature range of -40°C to +125°C.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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### ABSOLUTE MAXIMUM RATINGS(1)

Power Supply, V+ .....	7.0V
Input Voltage(2) .....	-0.5V to 7.0V
Input Current .....	10mA
Operating Temperature Range .....	-55°C to +127°C
Storage Temperature Range .....	-60°C to +130°C
Junction Temperature (T <sub>J</sub> max) .....	+150°C
ESD Rating:	
Human Body Model (HBM) .....	4000V
Charged Device Model (CDM) .....	1000V
Machine Model (MM) .....	300V



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

- (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not supported.
- (2) Input voltage rating applies to all TMP275 input voltages.

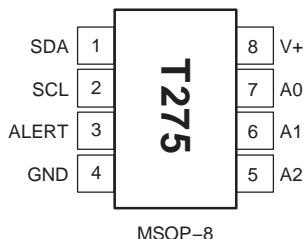
### ORDERING INFORMATION(1)

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR	PACKAGE MARKING
TMP275	MSOP-8	DGK	T275

- (1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at [www.ti.com](http://www.ti.com).

### PIN ASSIGNMENTS

Top View



NOTE: Pin 1 is determined by orienting the package marking as indicated in the diagram.

**ELECTRICAL CHARACTERISTICS**

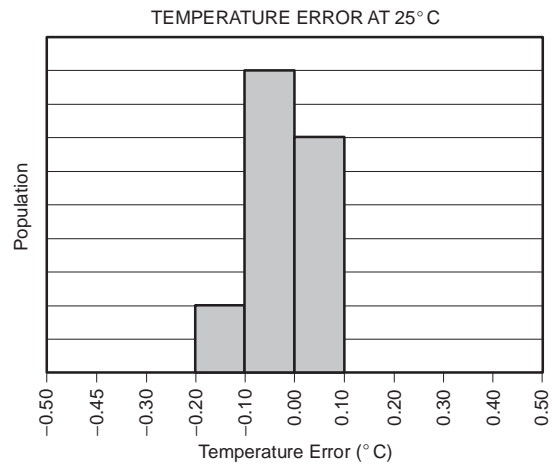
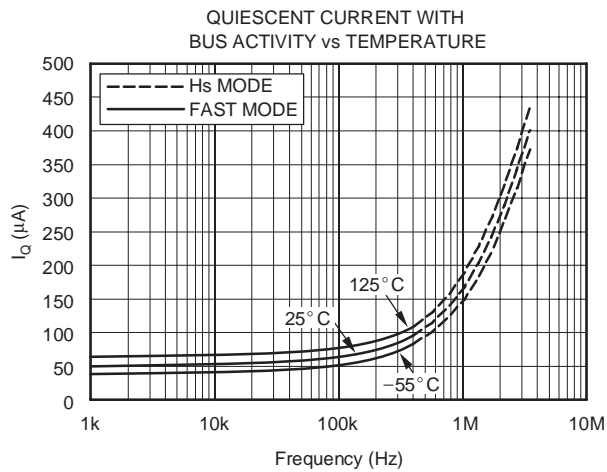
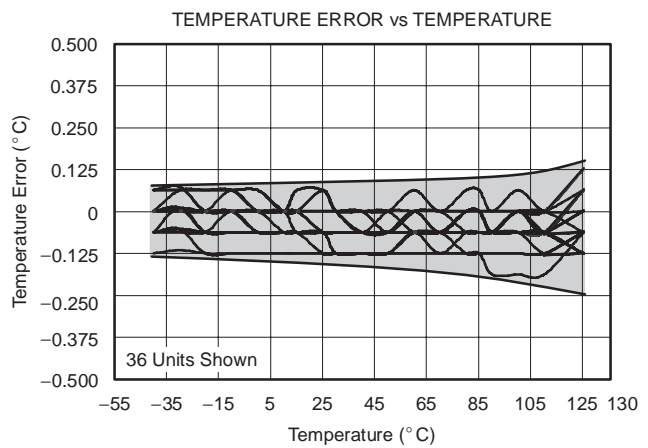
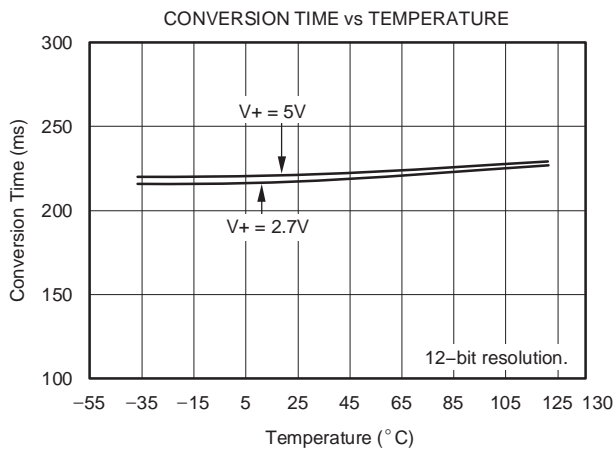
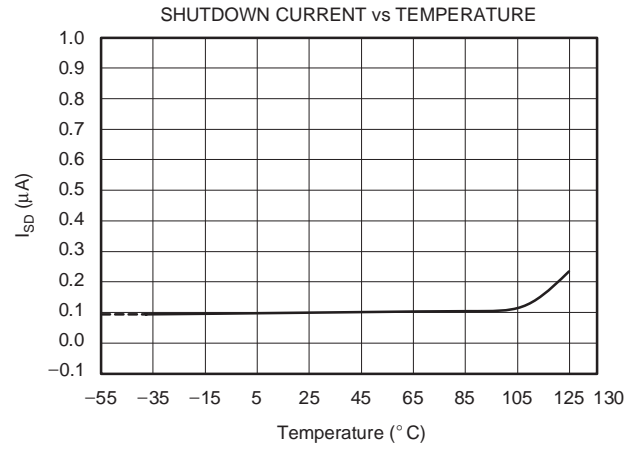
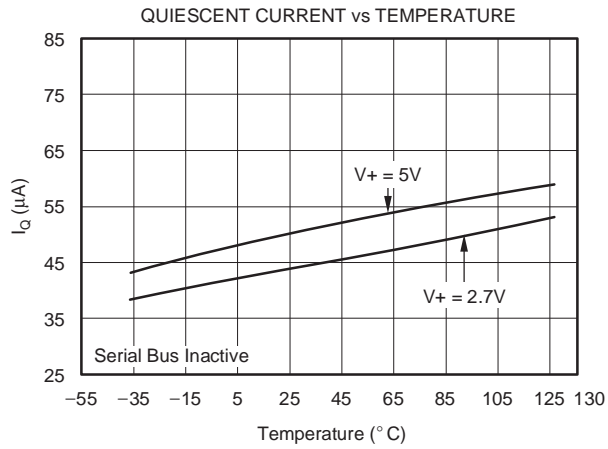
 At  $T_A = -40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ , and  $V_+ = 2.7\text{V}$  to  $5.5\text{V}$ , unless otherwise noted.

PARAMETER	CONDITION	TMP275			UNITS
		MIN	TYP	MAX	
<b>TEMPERATURE INPUT</b>					
Range		-40		+125	$^{\circ}\text{C}$
Accuracy (Temperature Error)	+10 $^{\circ}\text{C}$ to +85 $^{\circ}\text{C}$ , $V_+ = 3.3\text{V}$		$\pm 0.0625$	$\pm 0.5$	$^{\circ}\text{C}$
	0 $^{\circ}\text{C}$ to +100 $^{\circ}\text{C}$ , $V_+ = 3.0\text{V}$ to $3.6\text{V}$		$\pm 0.0625$	$\pm 0.75$	$^{\circ}\text{C}$
	-40 $^{\circ}\text{C}$ to +125 $^{\circ}\text{C}$ , $V_+ = 3.0\text{V}$ to $3.6\text{V}$		$\pm 0.0625$	$\pm 1$	$^{\circ}\text{C}$
	+25 $^{\circ}\text{C}$ to +100 $^{\circ}\text{C}$ , $V_+ = 3.3\text{V}$ to $5.5\text{V}$		0.2	$\pm 1.5$	$^{\circ}\text{C}$
Resolution <sup>(1)</sup>	Selectable		+0.0625		$^{\circ}\text{C}$
<b>DIGITAL INPUT/OUTPUT</b>					
Input Capacitance			3		pF
Input Logic Levels:					
$V_{IH}$		0.7(V <sub>+</sub> )		6.0	V
$V_{IL}$		-0.5		0.3(V <sub>+</sub> )	V
Leakage Input Current, $I_{IN}$	0V $\leq V_{IN} \leq 6\text{V}$			1	$\mu\text{A}$
Input Voltage Hysteresis	SCL and SDA Pins		500		mV
Output Logic Levels:					
$V_{OL\_SDA}$	$I_{OL} = 3\text{mA}$	0	0.15	0.4	V
$V_{OL\_ALERT}$	$I_{OL} = 4\text{mA}$	0	0.15	0.4	V
Resolution	Selectable		9 to 12		Bits
Conversion Time	9-Bit		27.5	37.5	ms
	10-Bit		55	75	ms
	11-Bit		110	150	ms
	12-Bit		220	300	ms
Timeout Time		25	54	74	ms
<b>POWER SUPPLY</b>					
Operating Range		2.7		5.5	V
Quiescent Current	$I_Q$				
	Serial Bus Inactive		50	85	$\mu\text{A}$
	Serial Bus Active, SCL Freq = 400kHz		100		$\mu\text{A}$
	Serial Bus Active, SCL Freq = 3.4MHz		410		$\mu\text{A}$
Shutdown Current	$I_{SD}$				
	Serial Bus Inactive		0.1	3	$\mu\text{A}$
	Serial Bus Active, SCL Freq = 400kHz		60		$\mu\text{A}$
	Serial Bus Active, SCL Freq = 3.4MHz		380		$\mu\text{A}$
<b>TEMPERATURE RANGE</b>					
Specified Range		-40		+125	$^{\circ}\text{C}$
Operating Range		-55		+127	$^{\circ}\text{C}$
Thermal Resistance	$\theta_{JA}$				
MSOP-8			250		$^{\circ}\text{C}/\text{W}$

(1) Specified for 12-bit resolution.

## TYPICAL CHARACTERISTICS

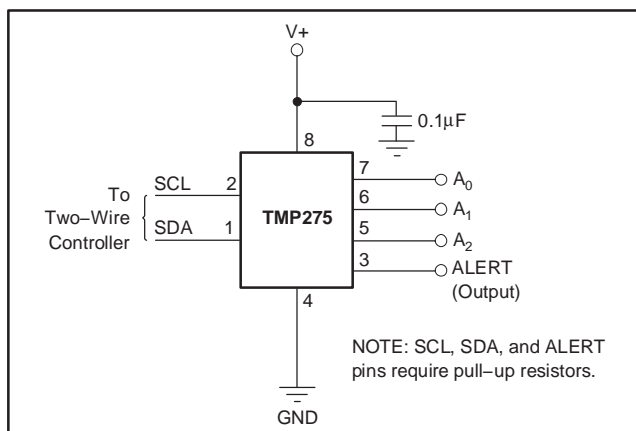
At  $T_A = +25^\circ\text{C}$  and  $V_+ = 5.0\text{V}$ , unless otherwise noted.



## APPLICATIONS INFORMATION

The TMP275 is a digital temperature sensor that is optimal for thermal management and thermal protection applications. The TMP275 is Two-Wire and SMBus interface-compatible, and is specified over a temperature range of  $-40^{\circ}\text{C}$  to  $+125^{\circ}\text{C}$ .

The TMP275 requires no external components for operation except for pull-up resistors on SCL, SDA, and ALERT, although a  $0.1\mu\text{F}$  bypass capacitor is recommended, as shown in Figure 1.



**Figure 1. Typical Connections of the TMP275**

The sensing device of the TMP275 is the chip itself. Thermal paths run through the package leads as well as the plastic package. The lower thermal resistance of metal causes the leads to provide the primary thermal path.

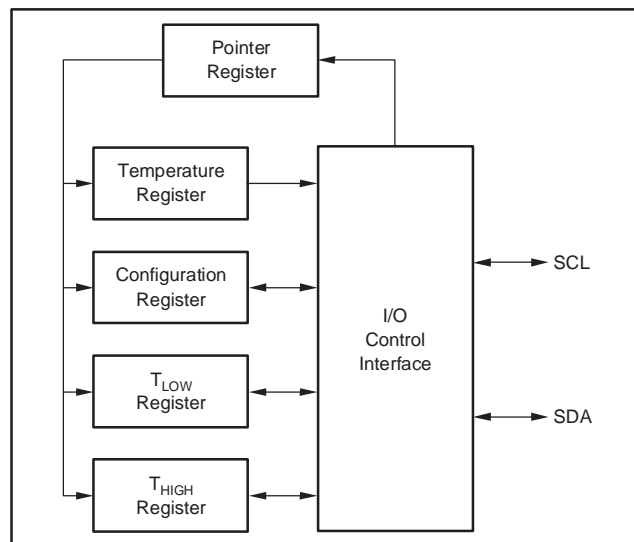
To maintain accuracy in applications requiring air or surface temperature measurement, care should be taken to isolate the package and leads from ambient air temperature. A thermally-conductive adhesive will assist in achieving accurate surface temperature measurement.

### POINTER REGISTER

Figure 2 shows the internal register structure of the TMP275. The 8-bit Pointer Register of the devices is used to address a given data register. The Pointer Register uses the two LSBs to identify which of the data registers should respond to a read or write command. Table 1 identifies the bits of the Pointer Register byte. Table 2 describes the pointer address of the registers available in the TMP275. Power-up reset value of P1/P0 is 00.

P7	P6	P5	P4	P3	P2	P1	P0
0	0	0	0	0	0	0	Register Bits

**Table 1. Pointer Register Byte**



**Figure 2. Internal Register Structure of the TMP275**

P1	P0	REGISTER
0	0	Temperature Register (READ Only)
0	1	Configuration Register (READ/WRITE)
1	0	T <sub>LOW</sub> Register (READ/WRITE)
1	1	T <sub>HIGH</sub> Register (READ/WRITE)

**Table 2. Pointer Addresses of the TMP275**

### TEMPERATURE REGISTER

The Temperature Register of the TMP275 is a 12-bit, read-only register that stores the output of the most recent conversion. Two bytes must be read to obtain data, and are described in Table 3 and Table 4. Note that byte 1 is the most significant byte, followed by byte 2, the least significant byte. The first 12 bits are used to indicate temperature, with all remaining bits equal to zero. The least significant byte does not have to be read if that information is not needed. Data format for temperature is summarized in Table 5. Following power-up or reset, the Temperature Register will read  $0^{\circ}\text{C}$  until the first conversion is complete.

D7	D6	D5	D4	D3	D2	D1	D0
T11	T10	T9	T8	T7	T6	T5	T4

**Table 3. Byte 1 of Temperature Register**

D7	D6	D5	D4	D3	D2	D1	D0
T3	T2	T1	T0	0	0	0	0

**Table 4. Byte 2 of Temperature Register**

TEMPERATURE (°C)	DIGITAL OUTPUT (BINARY)	HEX
128	0111 1111 1111	7FF
127.9375	0111 1111 1111	7FF
100	0110 0100 0000	640
80	0101 0000 0000	500
75	0100 1011 0000	4B0
50	0011 0010 0000	320
25	0001 1001 0000	190
0.25	0000 0000 0100	004
0	0000 0000 0000	000
-0.25	1111 1111 1100	FFC
-25	1110 0111 0000	E70
-55	1100 1001 0000	C90

Table 5. Temperature Data Format

The user can obtain 9, 10, 11, or 12 bits of resolution by addressing the Configuration Register and setting the resolution bits accordingly. For 9-, 10-, or 11-bit resolution, the most significant bits in the Temperature Register are used with the unused LSBs set to zero.

**CONFIGURATION REGISTER**

The Configuration Register is an 8-bit read/write register used to store bits that control the operational modes of the temperature sensor. Read/write operations are performed MSB first. The format of the Configuration Register for the TMP275 is shown in Table 6, followed by a breakdown of the register bits. The power-up/reset value of the Configuration Register is all bits equal to 0.

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
1	OS	R1	R0	F1	F0	POL	TM	SD

Table 6. Configuration Register Format

**SHUTDOWN MODE (SD)**

The Shutdown Mode of the TMP275 allows the user to save maximum power by shutting down all device circuitry other than the serial interface, which reduces current consumption to typically less than 0.1µA. Shutdown Mode is enabled when the SD bit is 1; the device will shut down once the current conversion is completed. When SD is equal to 0, the device will maintain a continuous conversion state.

**THERMOSTAT MODE (TM)**

The Thermostat Mode bit of the TMP275 indicates to the device whether to operate in Comparator Mode (TM = 0) or Interrupt Mode (TM = 1). For more information on comparator and interrupt modes, see the *High and Low Limit Registers* section.

**POLARITY (POL)**

The Polarity Bit of the TMP275 allows the user to adjust the polarity of the ALERT pin output. If POL = 0, the ALERT pin will be active LOW, as shown in Figure 3. For POL = 1, the ALERT pin will be active HIGH, and the state of the ALERT pin is inverted.

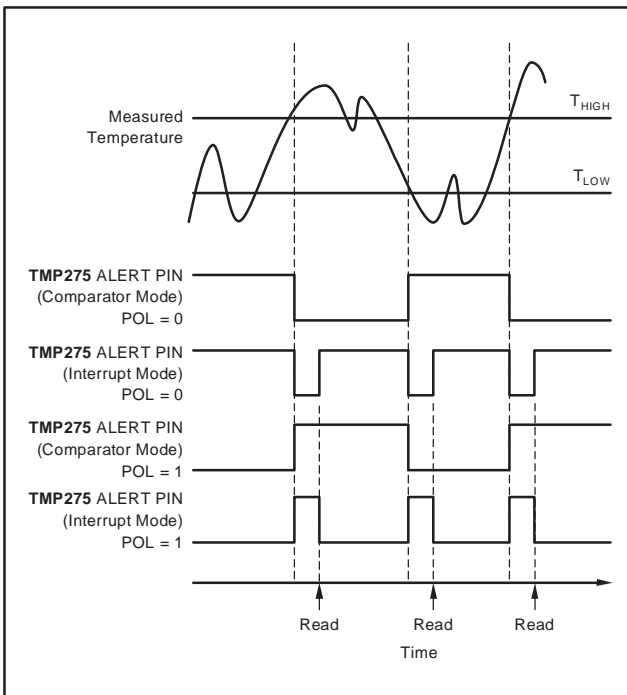


Figure 3. Output Transfer Function Diagrams

**FAULT QUEUE (F1/F0)**

A fault condition is defined as when the measured temperature exceeds the user-defined limits set in the T<sub>HIGH</sub> and T<sub>LOW</sub> Registers. Additionally, the number of fault conditions required to generate an alert may be programmed using the fault queue. The fault queue is provided to prevent a false alert as a result of environmental noise. The fault queue requires consecutive fault measurements in order to trigger the alert function. Table 7 defines the number of measured faults that may be programmed to trigger an alert condition in the device. For T<sub>HIGH</sub> and T<sub>LOW</sub> register format and byte order, see section *High and Low Limit Registers*.

F1	F0	CONSECUTIVE FAULTS
0	0	1
0	1	2
1	0	4
1	1	6

Table 7. Fault Settings of the TMP275

## CONVERTER RESOLUTION (R1/R0)

The Converter Resolution Bits control the resolution of the internal Analog-to-Digital (A/D) converter. This control allows the user to maximize efficiency by programming for higher resolution or faster conversion time. Table 8 identifies the Resolution Bits and the relationship between resolution and conversion time.

R1	R0	RESOLUTION	CONVERSION TIME (typical)
0	0	9 Bits (0.5°C)	27.5ms
0	1	10 Bits (0.25°C)	55ms
1	0	11 Bits (0.125°C)	110ms
1	1	12 Bits (0.0625°C)	220ms

**Table 8. Resolution of the TMP275**

## ONE-SHOT (OS)

The TMP275 features a One-Shot Temperature Measurement Mode. When the device is in Shutdown Mode, writing a '1' to the OS bit starts a single temperature conversion. The device returns to the shutdown state at the completion of the single conversion. This mode is useful for reducing power consumption in the TMP275 when continuous temperature monitoring is not required. When the configuration register is read, the OS always reads zero.

## HIGH AND LOW LIMIT REGISTERS

In Comparator Mode (TM = 0), the ALERT pin of the TMP275 becomes active when the temperature equals or exceeds the value in T<sub>HIGH</sub> and generates a consecutive number of faults according to fault bits F1 and F0. The ALERT pin remains active until the temperature falls below the indicated T<sub>LOW</sub> value for the same number of faults.

In Interrupt Mode (TM = 1), the ALERT pin becomes active when the temperature equals or exceeds T<sub>HIGH</sub> for a consecutive number of fault conditions. The ALERT pin remains active until a read operation of any register occurs, or the device successfully responds to the SMBus Alert Response Address. The ALERT pin is also cleared if the device is placed in Shutdown Mode. Once the ALERT pin is cleared, it only becomes active again by the temperature falling below T<sub>LOW</sub>. When the temperature falls below T<sub>LOW</sub>, the ALERT pin becomes active and remain active until cleared by a read operation of any register or a successful response to the SMBus Alert Response Address. Once the ALERT pin is cleared, the above cycle repeats, with the ALERT pin becoming active when the temperature equals or exceeds T<sub>HIGH</sub>. The ALERT pin can also be cleared by resetting the device with the General Call Reset command. This command also clears the state of the internal registers in the device, returning the device to Comparator Mode (TM = 0).

Both operational modes are represented in Figure 3. Table 9 and Table 10 describe the format for the T<sub>HIGH</sub> and T<sub>LOW</sub> registers. Note that the most significant byte is sent first, followed by the least significant byte. Power-up reset values for T<sub>HIGH</sub> and T<sub>LOW</sub> are:

$$T_{HIGH} = 80^{\circ}\text{C} \text{ and } T_{LOW} = 75^{\circ}\text{C}$$

The format of the data for T<sub>HIGH</sub> and T<sub>LOW</sub> is the same as for the Temperature Register.

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
1	H11	H10	H9	H8	H7	H6	H5	H4

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
2	H3	H2	H1	H0	0	0	0	0

**Table 9. Bytes 1 and 2 of T<sub>HIGH</sub> Register**

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
1	L11	L10	L9	L8	L7	L6	L5	L4

BYTE	D7	D6	D5	D4	D3	D2	D1	D0
2	L3	L2	L1	L0	0	0	0	0

**Table 10. Bytes 1 and 2 of T<sub>LOW</sub> Register**

All 12 bits for the Temperature, T<sub>HIGH</sub>, and T<sub>LOW</sub> registers are used in the comparisons for the ALERT function for all converter resolutions. The three LSBs in T<sub>HIGH</sub> and T<sub>LOW</sub> can affect the ALERT output even if the converter is configured for 9-bit resolution.

## SERIAL INTERFACE

The TMP275 operates only as a slave device on the Two-Wire bus and SMBus. Connections to the bus are made via the open-drain I/O lines SDA and SCL. The SDA and SCL pins feature integrated spike suppression filters and Schmitt triggers to minimize the effects of input spikes and bus noise. The TMP275 supports the transmission protocol for fast (1kHz to 400kHz) and high-speed (1kHz to 3.4MHz) modes. All data bytes are transmitted MSB first.

## SERIAL BUS ADDRESS

To communicate with the TMP275, the master must first address slave devices via a slave address byte. The slave address byte consists of seven address bits, and a direction bit indicating the intent of executing a read or write operation.

The TMP275 features three address pins allowing up to eight devices to be connected per bus. Pin logic levels are described in Table 11. The address pins of the TMP275 are read after reset, at start of communication, or in response to a Two-Wire address acquire request. Following reading the state of the pins the address is latched to minimize power dissipation associated with detection.



A2	A1	A0	SLAVE ADDRESS
0	0	0	1001000
0	0	1	1001001
0	1	0	1001010
0	1	1	1001011
1	0	0	1001100
1	0	1	1001101
1	1	0	1001110
1	1	1	1001111

**Table 11. Address Pins and Slave Addresses for the TMP275**

## BUS OVERVIEW

The device that initiates the transfer is called a *master*, and the devices controlled by the master are *slaves*. The bus must be controlled by a master device that generates the serial clock (SCL), controls the bus access, and generates the START and STOP conditions.

To address a specific device, a START condition is initiated, indicated by pulling the data-line (SDA) from a HIGH to LOW logic level while SCL is HIGH. All slaves on the bus shift in the slave address byte, with the last bit indicating whether a read or write operation is intended. During the ninth clock pulse, the slave being addressed responds to the master by generating an Acknowledge and pulling SDA LOW.

Data transfer is then initiated and sent over eight clock pulses followed by an Acknowledge Bit. During data transfer SDA must remain stable while SCL is HIGH, as any change in SDA while SCL is HIGH is interpreted as a control signal.

Once all data has been transferred, the master generates a STOP condition indicated by pulling SDA from LOW to HIGH, while SCL is HIGH.

## WRITING/READING TO THE TMP275

Accessing a particular register on the TMP275 is accomplished by writing the appropriate value to the Pointer Register. The value for the Pointer Register is the first byte transferred after the slave address byte with the R/W bit LOW. Every write operation to the TMP275 requires a value for the Pointer Register. (Refer to Figure 5.)

When reading from the TMP275, the last value stored in the Pointer Register by a write operation is used to determine which register is read by a read operation. To change the register pointer for a read operation, a new value must be written to the Pointer Register. This is accomplished by issuing a slave address byte with the R/W bit LOW, followed by the Pointer Register Byte. No additional data is required. The master can then generate a START condition and send the slave address byte with the R/W bit HIGH to initiate the read command. See

Figure 6 for details of this sequence. If repeated reads from the same register are desired, it is not necessary to continually send the Pointer Register bytes, as the TMP275 remembers the Pointer Register value until it is changed by the next write operation.

Note that register bytes are sent most-significant byte first, followed by the least significant byte.

## SLAVE MODE OPERATIONS

The TMP275 can operate as a slave receiver or slave transmitter.

### Slave Receiver Mode:

The first byte transmitted by the master is the slave address, with the R/W bit LOW. The TMP275 then acknowledges reception of a valid address. The next byte transmitted by the master is the Pointer Register. The TMP275 then acknowledges reception of the Pointer Register byte. The next byte or bytes are written to the register addressed by the Pointer Register. The TMP275 acknowledges reception of each data byte. The master may terminate data transfer by generating a START or STOP condition.

### Slave Transmitter Mode:

The first byte is transmitted by the master and is the slave address, with the R/W bit HIGH. The slave acknowledges reception of a valid slave address. The next byte is transmitted by the slave and is the most significant byte of the register indicated by the Pointer Register. The master acknowledges reception of the data byte. The next byte transmitted by the slave is the least significant byte. The master acknowledges reception of the data byte. The master may terminate data transfer by generating a Not-Acknowledge on reception of any data byte, or generating a START or STOP condition.

## SMBus ALERT FUNCTION

The TMP275 supports the SMBus Alert function. When the TMP275 is operating in Interrupt Mode (TM = 1), the ALERT pin of the TMP275 may be connected as an SMBus Alert signal. When a master senses that an ALERT condition is present on the ALERT line, the master sends an SMBus Alert command (00011001) on the bus. If the ALERT pin of the TMP275 is active, the device acknowledges the SMBus Alert command and responds by returning its slave address on the SDA line. The eighth bit (LSB) of the slave address byte indicates if the temperature exceeding T<sub>HIGH</sub> or falling below T<sub>LOW</sub> caused the ALERT condition. This bit will be HIGH if the temperature is greater than or equal to T<sub>HIGH</sub>. This bit will be LOW if the temperature is less than T<sub>LOW</sub>. Refer to Figure 7 for details of this sequence.

If multiple devices on the bus respond to the SMBus Alert command, arbitration during the slave address portion of the SMBus Alert command determines which device will clear its ALERT status. If the TMP275 wins the arbitration,



its ALERT pin will become inactive at the completion of the SMBus Alert command. If the TMP275 loses the arbitration, its ALERT pin will remain active.

### GENERAL CALL

The TMP275 responds to a Two-Wire General Call address (0000000) if the eighth bit is 0. The device acknowledges the General Call address and responds to commands in the second byte. If the second byte is 00000100, the TMP275 latches the status of the address pins, but does not reset. If the second byte is 00000110, the TMP275 latches the status of the address pins and resets the internal registers to the power-up values.

### HIGH-SPEED MODE

In order for the Two-Wire bus to operate at frequencies above 400kHz, the master device must issue an Hs-mode master code (00001XXX) as the first byte after a START condition to switch the bus to high-speed operation. The TMP275 will not acknowledge this byte, but will switch its input filters on SDA and SCL and its output filters on SDA to operate in Hs-mode, allowing transfers at up to 3.4MHz. After the Hs-mode master code has been issued, the master transmits a Two-Wire slave address to initiate a data transfer operation. The bus continues to operate in Hs-mode until a STOP condition occurs on the bus. Upon receiving the STOP condition, the TMP275 switches the input and output filters back to fast-mode operation.

### TIMEOUT FUNCTION

The TMP275 resets the serial interface if either SCL or SDA is held LOW for 54ms (typ) between a START and STOP condition. The TMP275 releases the bus if it is pulled LOW and waits for a START condition. To avoid activating the timeout function, it is necessary to maintain a communication speed of at least 1kHz for SCL operating frequency.

### TIMING DIAGRAMS

The TMP275 is Two-Wire and SMBus-compatible. Figure 4 to Figure 7 describe the various operations on the TMP275. Bus definitions are given below. Parameters for Figure 4 are defined in Table 12.

**Bus Idle:** Both SDA and SCL lines remain HIGH.

**Start Data Transfer:** A change in the state of the SDA line, from HIGH to LOW, while the SCL line is HIGH, defines a START condition. Each data transfer is initiated with a START condition.

**Stop Data Transfer:** A change in the state of the SDA line from LOW to HIGH while the SCL line is HIGH defines a STOP condition. Each data transfer is terminated with a repeated START or STOP condition.

**Data Transfer:** The number of data bytes transferred between a START and a STOP condition is not limited and is determined by the master device. The receiver acknowledges the transfer of data.

**Acknowledge:** Each receiving device, when addressed, is obliged to generate an Acknowledge bit. A device that acknowledges must pull down the SDA line during the Acknowledge clock pulse in such a way that the SDA line is stable LOW during the HIGH period of the Acknowledge clock pulse. Setup and hold times must be taken into account. On a master receive, the termination of the data transfer can be signaled by the master generating a Not-Acknowledge on the last byte that has been transmitted by the slave.

PARAMETER		FAST MODE		HIGH-SPEED MODE		UNITS
		MIN	MAX	MIN	MAX	
SCL Operating Frequency	$f(SCL)$	0.001	0.4	0.001	3.4	MHz
Bus Free Time Between STOP and START Condition	$t(BUF)$	600		160		ns
Hold time after repeated START condition. After this period, the first clock is generated.	$t(HDSTA)$	100		100		ns
Repeated START Condition Setup Time	$t(SUSTA)$	100		100		ns
STOP Condition Setup Time	$t(SUSTO)$	100		100		ns
Data Hold Time	$t(HDDAT)$	0		0		ns
Data Setup Time	$t(SUDAT)$	100		10		ns
SCL Clock LOW Period	$t(LOW)$	1300		160		ns
SCL Clock HIGH Period	$t(HIGH)$	600		60		ns
Clock/Data Fall Time	$t_F$		300		160	ns
Clock/Data Rise Time	$t_R$		300		160	ns
for $SCLK \leq 100kHz$	$t_R$		1000			ns

**Table 12. Timing Diagram Definitions for the TMP275**

## TWO-WIRE TIMING DIAGRAMS

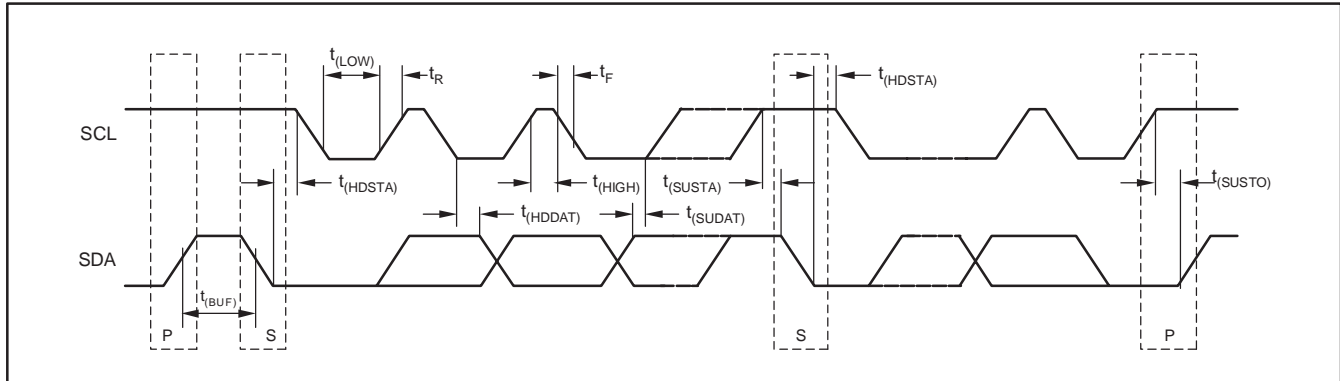


Figure 4. Two-Wire Timing Diagram

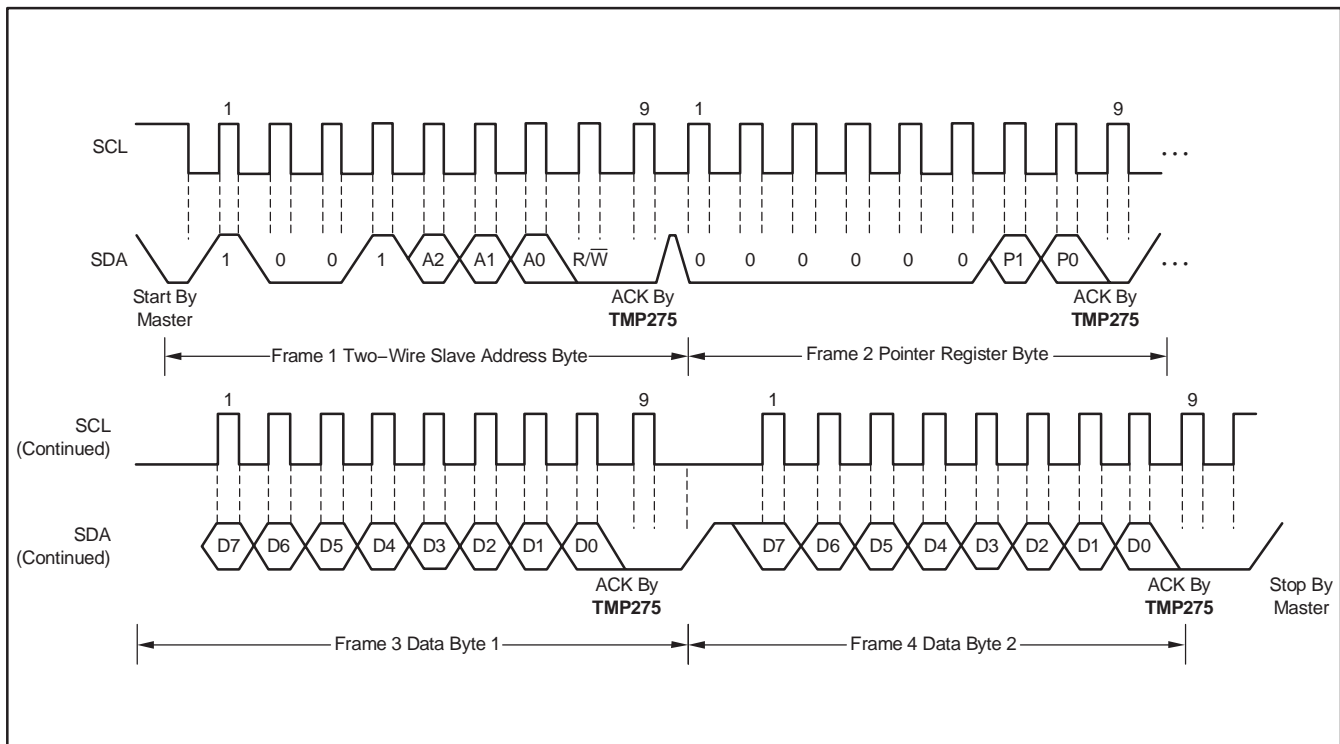
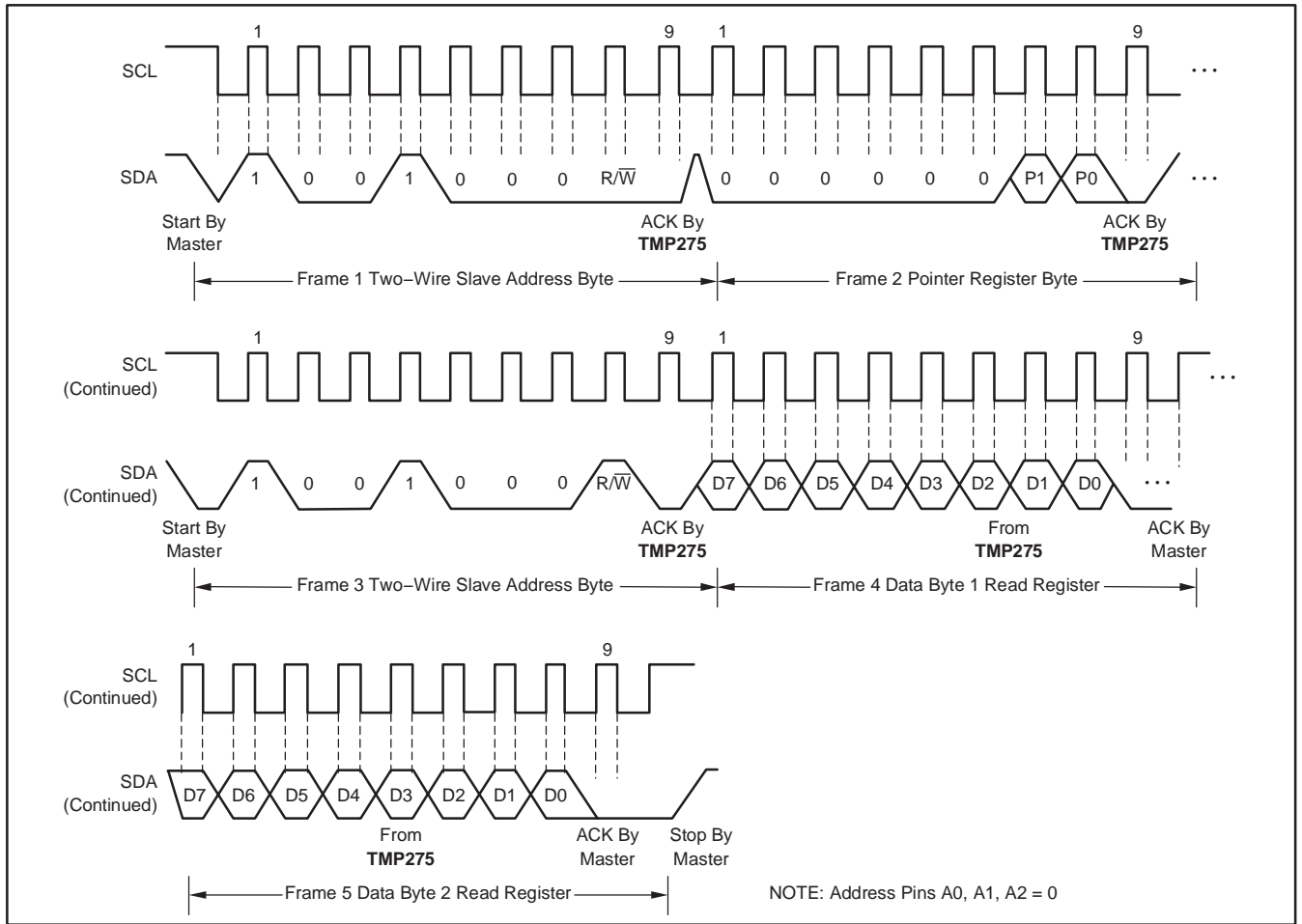
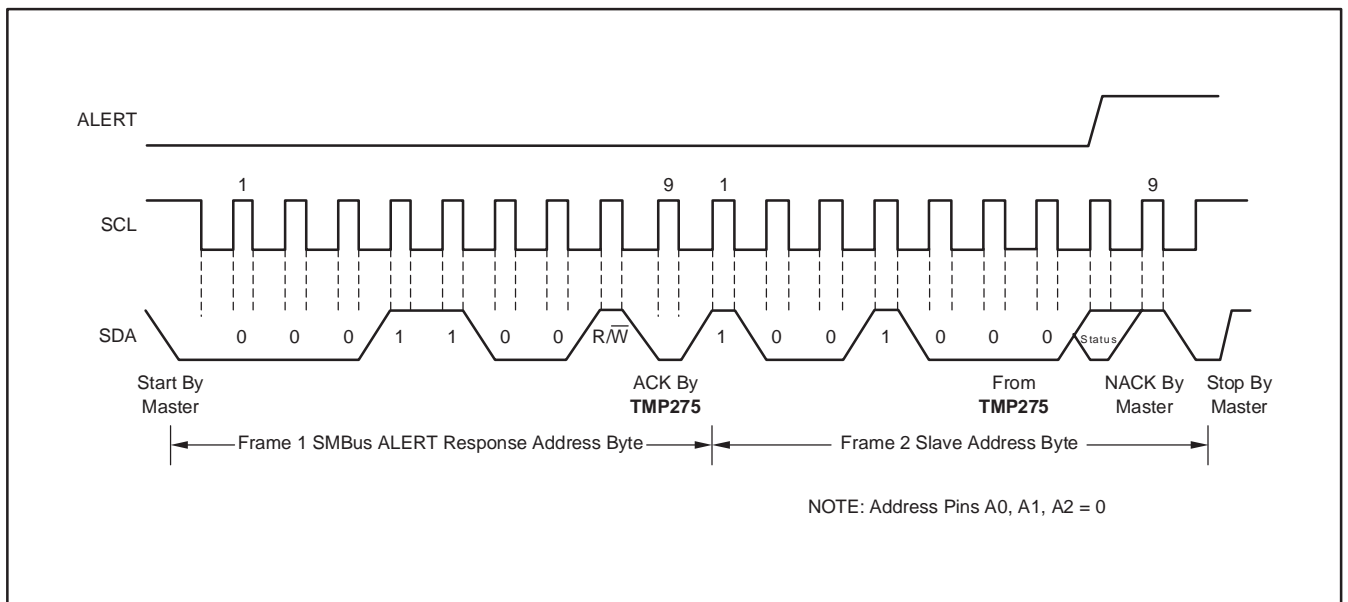


Figure 5. Two-Wire Timing Diagram for TMP275 Write Word Format



**Figure 6. Two-Wire Timing Diagram for Read Word Format**



**Figure 7. Timing Diagram for SMBus ALERT**

**PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
TMP275AIDGKR	ACTIVE	MSOP	DGK	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
TMP275AIDGKRG4	ACTIVE	MSOP	DGK	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
TMP275AIDGKT	ACTIVE	MSOP	DGK	8	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
TMP275AIDGKTG4	ACTIVE	MSOP	DGK	8	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR

<sup>(1)</sup> The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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DGK (S-PDSO-G8)

PLASTIC SMALL-OUTLINE PACKAGE



- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 per end.
  - D. Body width does not include interlead flash. Interlead flash shall not exceed 0.50 per side.
  - E. Falls within JEDEC MO-187 variation AA, except interlead flash.

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Mailing Address: Texas Instruments  
Post Office Box 655303 Dallas, Texas 75265