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**[LMK00804B-Q1](http://www.ti.com/product/lmk00804b-q1?qgpn=lmk00804b-q1)** SNAS784A –MARCH 2019–REVISED JUNE 2019

# **LMK00804B-Q1 1.5-V to 3.3-V, 1-to-4 High-Performance LVCMOS Fan-Out Buffer and Level Translator**

### <span id="page-0-1"></span>**1 Features**

- AEC-Q100 qualified with the following results:
	- Device temperature grade 1:  $-40^{\circ}$ C to  $+125^{\circ}$ C, TA
- <span id="page-0-2"></span>• Four LVCMOS/LVTTL outputs supporting 1.5-V to 3.3-V levels
	- Additive jitter: 0.1-ps RMS (typical) at 40 MHz
	- Noise floor: –168 dBc/Hz (typical) at 40 MHz
	- Output frequency: 350 MHz (maximum)
	- Output skew: 35 ps (maximum)
	- Part-to-part skew: 700 ps (maximum)
- Two selectable inputs
	- CLK\_P, CLK\_N pair accepts LVPECL, LVDS, HCSL, SSTL, LVHSTL, or LVCMOS/LVTTL
	- LVCMOS\_CLK accepts LVCMOS/LVTTL
- Synchronous clock enable
- Core/output power supplies:
	- $-$  3.3 V/3.3 V
	- $-$  3.3 V/2.5 V
	- $-$  3.3 V/1.8 V
	- $-$  3.3 V/1.5 V
- <span id="page-0-0"></span>Package: 16-pin VQFN

### **2 Applications**

- Advanced Driver Assistance Systems (ADAS)
	- Front long range radar
	- Medium/short range radar
	- Ultra short range radar

#### **3 Description**

The LMK00804B-Q1 is a high-performance clock fanout buffer and level translator that can distribute up to four LVCMOS/LVTTL outputs (3.3-V, 2.5-V, 1.8-V, or 1.5-V levels) from one of two selectable inputs that can accept differential or single-ended inputs. The clock enable input is synchronized internally to eliminate runt or glitch pulses on the outputs when the clock enable terminal is asserted or deasserted. The outputs are held in logic low state when the clock is disabled. The LMK00804B-Q1 can also distrbute a low-jitter clock across four transceivers and can improve the overall target detection and resolution in a cascaded mmWave radar system.

#### **Device Information[\(1\)](#page-0-0)**



(1) For all available packages, see the orderable addendum at the end of the data sheet.

#### **Simplified Schematic**



(1) PU = 51-k $\Omega$  pullup, PD = 51-k $\Omega$  pulldown. See [Figure](#page-15-0) 11.

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#### <span id="page-1-0"></span>**4 Revision History**

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

#### **Changes from Original (March 2019) to Revision A Page**





#### <span id="page-2-0"></span>**5 Pin Configuration and Functions**



#### **Pin Functions(1)**



(1) See *[Recommendations](#page-17-0) for Unused Input and Output Pins*, if applicable.

 $(2)$  The definitions below define the functionality of the I/O cells for each pin.

TYPE:

 $(a)$  G = Ground,

- $(b)$  I = Input,
- $(c)$  O = Output,
- $(d)$  P = Power,
- (e)  $PU = 51 k\Omega$  pullup,
- (f)  $PD = 51 k\Omega$  pulldown.
- (g) NC = No connect

#### <span id="page-3-0"></span>**6 Specifications**

### <span id="page-3-1"></span>**6.1 Absolute Maximum Ratings(1)(2)**

Over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>



(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *[Recommended](#page-3-3) Operating [Conditions](#page-3-3)* is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) If Military/Aerospace specified devices are required, contact the Texas Instruments Sales Office/Distributors for availability and

specifications.

(3) This value is limited to 4.6 V maximum.

#### <span id="page-3-2"></span>**6.2 ESD Ratings**



(1) AEC Q100-002 indicates that HBM stressing shall be in accordance with the ANSI/ESDA/JEDEC JS-001 specification.

#### <span id="page-3-3"></span>**6.3 Recommended Operating Conditions**

Over operating free-air temperature range (unless otherwise noted)



(1) There is no minimum input / output frequency provided the input slew rate is sufficiently fast. Refer to *Input Slew Rate [Considerations](#page-17-1)*.



#### <span id="page-4-0"></span>**6.4 Thermal Information**



(1) For more information about traditional and new thermal metrics, see the *[Semiconductor](http://www.ti.com/lit/pdf/spra953) and IC Package Thermal Metrics* application report (SPRA953).

(2) The package thermal impedance is calculated in accordance with JESD 51 and JEDEC2S2P (high-K board).

#### <span id="page-4-1"></span>**6.5 Power Supply Characteristics**

Over recommended operating supply and temperature ranges unless otherwise specified.



#### <span id="page-4-2"></span>**6.6 LVCMOS / LVTTL DC Electrical Characteristics**

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and T<sub>A</sub> =  $-40^{\circ}$ C to 125 $^{\circ}$ C



(1) Outputs terminated with 50  $\Omega$  to V<sub>DDO</sub>/2.

### <span id="page-5-0"></span>**6.7 Differential Input DC Electrical Characteristics**

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and T<sub>A</sub> = –40°C to 125°C



(1)  $V_{IL}$  should not be less than –0.3 V.<br>(2) Input common-mode voltage is def

 $(2)$  Input common-mode voltage is defined as  $V_{\text{H}}$ .<br>(3) For  $I_{\text{H}}$  and  $I_{\text{II}}$  measurements on CLK\_Por CLK

For I<sub>IH</sub> and I<sub>IL</sub> measurements on CLK\_Por CLK\_N, one must comply with V<sub>ID</sub> and V<sub>IC</sub> specifications by using the appropriate bias on CLK\_N or CLK.

#### <span id="page-5-1"></span>**6.8 Timing Characteristics (** $V_{DDO}$  **= 3.3 V**  $\pm$  **5%)**

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and -40°C to 125°C



(1) Measured from the  $V_{DD}/2$  of the input to the  $V_{DDO}/2$  of the output.

(2) Measured from the differential input crossing point to  $V_{DDO}/2$  of the output.<br>(3) Defined as skew between outputs at the same supply voltage and with equ

(3) Defined as skew between outputs at the same supply voltage and with equal loading conditions. Measured at  $V_{DDO}/2$  of the output.<br>(4) Parameter is defined in accordance with JEDEC Standard 65.

Parameter is defined in accordance with JEDEC Standard 65.

(6) Buffer additive jitter:  $t_{\text{JIT}} = \overline{\text{SQRT}}(t_{\text{JIT\_SVS}}^2 - t_{\text{JIT\_SOLRCE}}^2)$ , where  $t_{\text{JIT\_SYS}}$  is the RMS jitter of the system output (source+buffer) and t<sub>JIT</sub> source is the RMS jitter of the input source, and system output noise is not correlated to the input source noise. Additive jitter should be considered only when the input source noise floor is 3 dB or better than the buffer noise floor ( $PN<sub>FLOOR</sub>$ ). This is usually the case for high-quality, ultra-low-noise oscillators. Refer to *System-Level Phase Noise and Additive Jitter [Measurement](#page-14-0)* for input source and measurement details.

<sup>(5)</sup> Calculation for part-to-part skew is the difference between the fastest and slowest t<sub>PD</sub> across multiple devices, various supply voltages, operating at the same frequency, same temperature, with equal load conditions, and using the same type of inputs on each device.



#### **Timing Characteristics (V**<sub>DDO</sub> = 3.3 V  $\pm$  5%) (continued)

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and -40°C to 125°C



(7) Buffer phase noise floor: PN<sub>FLOOR</sub> (dBc/Hz) = 10 x log10[10^(PN<sub>SYSTEM</sub>/10) – 10^(PN<sub>SOURCE</sub>/10)], where PN<sub>SYSTEM</sub> is the phase noise floor of the system output (source+buffer) and PN<sub>SOURCE</sub> is the phase noise floor of the input source. Buffer Phase Noise Floor should be considered only when the input source noise floor is 3 dB or better than the buffer noise floor  $(PN_{F\text{LOOR}})$ . This is usually the case for high-quality, ultra-low-noise oscillators. Refer to *System-Level Phase Noise and Additive Jitter [Measurement](#page-14-0)* for input source and measurement details.

#### <span id="page-6-0"></span>**6.9 Timing Characteristics (** $V_{DDO}$  **= 2.5 V**  $\pm$  **5%)**

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and T<sub>A</sub> = –40°C to 125°C



(1) Measured from the  $V_{DD}/2$  of the input to the  $V_{DDO}/2$  of the output.

(2) Defined as skew between outputs at the same supply voltage and with equal loading conditions. Measured at  $V_{DDO}/2$  of the output.<br>(3) Parameter is defined in accordance with JEDEC Standard 65.

Parameter is defined in accordance with JEDEC Standard 65.

(4) Calculation for part-to-part skew is the difference between the fastest and slowest  $t_{PD}$  across multiple devices, various supply voltages, operating at the same frequency, same temperature, with equal load conditions, and using the same type of inputs on each device.

(5) Buffer additive jitter: t<sub>JIT</sub> = SQRT(t<sub>JIT\_SYS</sub> <sup>2</sup> – t<sub>JIT\_SOURCE</sub><sup>2</sup>), where J<sub>SYS</sub> is the RMS jitter of the system output (source+buffer) and  $t_{\text{JIT}}$  source is the RMS jitter of the input source, and system output noise is not correlated to the input source noise. Additive jitter should be considered only when the input source noise floor is 3 dB or better than the buffer noise floor ( $PN<sub>FLOOR</sub>$ ). This is usually the case for high-quality, ultra-low-noise oscillators. Refer to *System-Level Phase Noise and Additive Jitter [Measurement](#page-14-0)* for input source and measurement details.

#### <span id="page-6-1"></span>**6.10 Timing Characteristics (** $V_{DDO}$  **= 1.8 V**  $\pm$  **5%)**

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and T<sub>A</sub> = –40°C to 125°C



(1) Measured from the  $V_{DD}/2$  of the input to the  $V_{DDO}/2$  of the output.

### **Timing Characteristics (V**<sub>DDO</sub> = 1.8 V  $\pm$  5%) (continued)

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and T<sub>A</sub> = –40°C to 125°C



(2) Defined as skew between outputs at the same supply voltage and with equal loading conditions. Measured at  $V_{DDO}/2$  of the output.<br>(3) Parameter is defined in accordance with JEDEC Standard 65.

Parameter is defined in accordance with JEDEC Standard 65.

(4) Calculation for part-to-part skew is the difference between the fastest and slowest  $t_{PD}$  across multiple devices, various supply voltages, operating at the same frequency, same temperature, with equal load conditions, and using the same type of inputs on each device.

(5) Buffer additive jitter: t<sub>JIT</sub> = SQRT(t<sub>JIT\_SYS</sub><sup>2</sup> – t<sub>JIT\_SOURCE</sub><sup>2</sup>), where J<sub>SYS</sub> is the RMS jitter of the system output (source+buffer) and t<sub>JIT\_SOURCE</sub> is the RMS jitter of the input source, and system output noise is not correlated to the input source noise. Additive jitter should be considered only when the input source noise floor is 3 dB or better than the buffer noise floor (PN<sub>FLOOR</sub>). This is usually the case for high-quality, ultra-low-noise oscillators. Refer to *System-Level Phase Noise and Additive Jitter [Measurement](#page-14-0)* for input source and measurement details.



#### <span id="page-8-0"></span>**6.11 Timing Characteristics (** $V_{DDO}$  **= 1.5 V**  $\pm$  **5%)**

 $V_{DD}$  = 3.135 V to 3.465 V,  $V_{DDO}$  = 1.425 V to 1.575 V, 1.71 V to 1.89 V, 2.375 V to 2.625 V, 3.135 V to 3.465 V and T<sub>A</sub> = –40°C to 125°C



(1) Measured from the  $V_{DD}/2$  of the input to the  $V_{DDO}/2$  of the output.

(2) Defined as skew between outputs at the same supply voltage and with equal loading conditions. Measured at  $V_{DDO}/2$  of the output.

(3) Parameter is defined in accordance with JEDEC Standard 65.

(4) Calculation for part-to-part skew is the difference between the fastest and slowest t<sub>PD</sub> across multiple devices, various supply voltages, operating at the same frequency, same temperature, with equal load conditions

#### <span id="page-8-1"></span>**6.12 Pin Characteristics**



<sup>(5)</sup> Buffer additive jitter: t<sub>JIT</sub> = SQRT(t<sub>JIT\_SYS</sub><sup>2</sup> – t<sub>JIT\_SOURCE</sub><sup>2</sup>), where t<sub>JIT\_SYS</sub> is the RMS jitter of the system output (source+buffer) and t<sub>JIT\_SOURCE</sub> is the RMS jitter of the input source, and system output noise is not correlated to the input source noise. Additive jitter should be considered only when the input source noise floor is 3 dB or better than the buffer noise floor ( $PN<sub>FLOOR</sub>$ ). This is usually the case for high-quality, ultra-low-noise oscillators. Refer to *System-Level Phase Noise and Additive Jitter [Measurement](#page-14-0)* for input source and measurement details.

#### <span id="page-9-0"></span>**7 Parameter Measurement Information**









#### <span id="page-10-0"></span>**8 Detailed Description**

#### <span id="page-10-1"></span>**8.1 Overview**

The LMK00804B-Q1 is a clock fan-out buffer with two selectable clock inputs and four LVCMOS outputs. The LVCMOS\_CLK input accepts a single-ended clock input, and the CLK\_P/CLK\_N input accepts a differential or single-ended clock input. The LMK00804B-Q1 has a synchronous clock enable feature allows the device to drive the outputs to a logic low using the CLK\_EN pin.

#### <span id="page-10-2"></span>**8.2 Functional Block Diagram**



**[LMK00804B-Q1](http://www.ti.com/product/lmk00804b-q1?qgpn=lmk00804b-q1)** SNAS784A –MARCH 2019–REVISED JUNE 2019 **[www.ti.com](http://www.ti.com)**



#### <span id="page-11-0"></span>**8.3 Feature Description**

#### **8.3.1 Clock Enable Timing**

After CLK\_EN switches, the clock outputs are disabled or enabled following a rising and falling input clock edge as shown in [Figure](#page-11-2) 4.



**Figure 4. Clock Enable Timing Diagram**

#### <span id="page-11-2"></span><span id="page-11-1"></span>**8.4 Device Functional Modes**

The device can provide fan-out and level translation from a differential or single-ended input to a LVCMOS/LVTTL output where the output  $V_{OH}$  and  $V_{OL}$  levels are applied to the  $V_{DDO}$  pin and output load condition.



#### <span id="page-12-0"></span>**9 Applications and Implementation**

#### **NOTE**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### <span id="page-12-1"></span>**9.1 Application Information**

The LMK00804B-Q1 enables the distribution of up to four LVCMOS copies of a low-noise source designed for general-purpose and high-performance applications. For best jitter performance, TI recommends to use the appropriate matching networks for the clock driver and receiver format, as detailed in the *Typical [Applications](#page-12-2)* section. Practice good high-speed layout design outlined in the *[High-speed](http://www.ti.com/lit/pdf/SCAA082) Layout Guidelines* application report (SCAA082).

The LMK00804B-Q1 is designed to drive 50-Ω controlled-impedance traces. TI recommends to design these clock traces as 50-Ω, single-ended controlled impedance traces. Use a series 43-Ω resistor at the clock outputs Q[3:0] to match the driver impedance and series resistance to the trace impedance.

#### <span id="page-12-2"></span>**9.2 Typical Applications**

Refer to the following sections for output clock and input clock interface circuits.

#### **9.2.1 Output Clock Interface Circuit**



#### **Figure 5. LVCMOS Output Configuration**

#### *9.2.1.1 Design Requirements*

For high-performance devices, limitations of the equipment can affect phase-noise measurements. The noise floor of the equipment is often higher than the noise floor of the device. The real noise floor of the device is probably lower. It is important to understand that system-level phase noise measured at the DUT output is influenced by the input source and the measurement equipment.

For [Figure](#page-14-1) 6 and system-level phase noise plots, a Rohde & Schwarz SMA100A low-noise signal generator was cascaded with an Agilent 70429A K95 single-ended-to-differential converter block with ultra-low phase noise and fast-edge slew rate (>3 V/ns) to provide a low-noise clock input source to the LMK00804B-Q1. An Agilent E5052 source signal analyzer with an ultra-low measurement noise floor was used to measure the phase noise of the input source (SMA100A + 70429A K95) and system output (input source + LMK00804B-Q1). The light blue trace shows the input source phase noise, and the dark blue trace in [Figure](#page-14-1) 6 shows the system output phase noise.



#### **Typical Applications (continued)**

#### *9.2.1.2 Detailed Design Procedure*

<span id="page-13-0"></span>Use [Equation](#page-13-0) 1 to calculate the additive phase noise or noise floor of the buffer (PN $_{FLOOR}$ ):

 $PN_{FLOOR}$  (dBc/Hz) = 10 x  $log_{10}[10^{\circ}$ (PN<sub>SYSTEM</sub>/10) – 10<sup> $\circ$ </sup>(PN<sub>SOURCE</sub>/10)]

where

- PN<sub>SYSTEM</sub> is the phase noise of the system output (source+buffer)
- $PN_{\text{SOLRCE}}$  is the phase noise of the input source (1)  $(1)$

<span id="page-13-1"></span>Use [Equation](#page-13-1) 2 to calculate the additive jitter of the buffer  $(t_{JIT})$ :

 $t_{\text{JIT}} = \text{SGRT}(t_{\text{JIT}_\text{SYS}}^2 - t_{\text{JIT}_\text{-SOURCE}}^2)$ 

where:

- $\bullet$   $t_{\text{JIT\_SYS}}$  is the RMS jitter of the system output (source+buffer), integrated from 10 kHz to 20 MHz
- $t_{\text{JIT SOURCE}}$  is the RMS jitter of the input source, integrated from 10 kHz to 20 MHz (2)



#### **Typical Applications (continued)**

#### *9.2.1.3 Application Curve*

#### **9.2.1.3.1 System-Level Phase Noise and Additive Jitter Measurement**

<span id="page-14-0"></span>

<span id="page-14-1"></span>**Figure 6. 40-MHz Input Phase Noise (181 fs rms, Light Blue), and Output Phase Noise (196 fs rms, Dark Blue), Additive Jitter = 77 fs rms**



#### **Typical Applications (continued)**

#### **9.2.2 Input Detail**





#### <span id="page-15-0"></span>**9.2.3 Input Clock Interface Circuits**







<span id="page-15-1"></span>(1) The Thevenin/split termination values (R = 100  $\Omega$ ) at the CLK\_P input may be adjusted to provide a small differential offset voltage (50 mV, for example) between the CLK\_P and CLK\_N inputs to prevent input chatter if the LVCMOS driver in a tri-state condition. For example, the engineer can use 105  $\Omega$  1% to the 3.3-V rail and 97.6  $\Omega$  1% to GND to receive a –60-mV offset voltage ( $V_{CLK\_N}$  –  $V_{CLK\_P}$ ). Ensure a logic low state if the LVCMOS driver enters a tri-state condition.

#### **Figure 9. Single-Ended/LVCMOS Input DC Configuration**



#### <span id="page-16-0"></span>**9.3 Do's and Don'ts**

#### <span id="page-16-3"></span>**9.3.1 Power Considerations**

The following power considerations refer to the device-consumed power consumption only. The device power consumption is the sum of static and dynamic power. The dynamic power usage consists of two components:

- Power used by the device as it switches states
- Power required to charge any output load

The output load can be capacitive-only or capacitive and resistive. Use [Equation](#page-16-1) 3 through [Equation](#page-16-2) 5 to calculate the power consumption of the device:

<span id="page-16-2"></span><span id="page-16-1"></span>

 $P_{dyn}$  +  $P_{Cloud}$  = (2.8 mA + 6.9 mA)  $\times$  3.465 V = 34 mW (8)  $I_{DD,dyn} = 2 pF \times 3.465 V \times 100 MHz \times 4 = 2.8 mA$  (9)  $I_{DD,Cloud} = 5 pF \times 3.465 V \times 100 MHz \times 4 = 6.9 mA$  (10)

#### **NOTE**

For dimensioning the power supply, consider the total power consumption. The total power consumption is the sum of device power consumption and the power consumption of the load.



#### **Do's and Don'ts (continued)**

#### <span id="page-17-0"></span>**9.3.2 Recommendations for Unused Input and Output Pins**

**CLK SEL and CLK EN:** CLK EN must be held low until a valid reference clock is provided before the engineer can use the pin to enable the outputs. These inputs both have an internal pullup (PU) according to [Table](#page-17-2) 1. [Table](#page-17-2) 1 shows the default floating state of these inputs:

#### **Table 1. Input Floating Default States**

<span id="page-17-2"></span>

- **CLK\_P/CLK\_N Inputs:** See [Figure](#page-15-0) 7 for the internal connections. When using a single-ended input, take note of the internal pullup and pulldown to make sure the unused input is properly biased. To interface a single-ended input to the CLK\_P/CLK\_N input, the configuration shown in [Figure](#page-15-1) 9 is recommended.
- **LVCMOS** CLK Input: See [Figure](#page-15-0) 7 for the internal connection. The internal pulldown (PD) resistor ensures a low state when this input is left floating.
- **Outputs:** Connect the outputs to the receivers with a 43-Ω series resistor. Any unused output must be left floating.

#### <span id="page-17-1"></span>**9.3.3 Input Slew Rate Considerations**

LMK00804B-Q1 employs high-speed and low-latency circuit topology to allow ultra-low additive jitter/phase noise and high-frequency operation. To take advantage of these benefits in the system application, it is optimal for the input signal to have a high slew rate of 3 V/ns or greater. Driving the input with a slower slew rate can degrade the additive jitter and noise floor performance. For this reason, a differential signal input is recommended over a single-ended signal, because a differential signal typically provides a higher slew rate and common-moderejection. Refer to and . Remember that using an input signal with a slow input slew rate less than 0.05 V/ns can cause output switching noise to feed back to the input stage and cause the output to chatter. This is especially true when driving either input single-ended fashion with a very slow slew rate, such as a sine-wave input signal.



### <span id="page-18-0"></span>**10 Power Supply Recommendations**

#### <span id="page-18-1"></span>**10.1 Power Supply Considerations**

While there is no strict power supply sequencing requirement, it is generally best practice to sequence the supply input voltage ( $V_{DD}$ ) before the supply output voltage ( $V_{DDO}$ ).

#### <span id="page-18-3"></span>**10.1.1 Power-Supply Filtering**

High-performance clock buffers are sensitive to noise on the power supply, which can dramatically increase the additive jitter of the buffer. Thus, it is essential to reduce noise from the system power supply, especially when jitter or phase noise is critical to applications.

The use of bypass capacitors eliminates the low-frequency noise from power supply, because they can provide a very low-impedance path for high-frequency noise and guard the power-supply system against induced fluctuations. The bypass capacitors also provide instantaneous current surges as required by the device, and should have low ESR. To use the bypass capacitors properly, place them close to the power supply terminals and lay out traces with short loops to minimize inductance. TI recommends that the engineer add as many highfrequency (for example, 0.1-µF) bypass capacitors as there are supply terminals in the package. TI recommends that the engineer insert a ferrite bead between the board power supply and the chip power supply to isolate the high-frequency switching noises generated by the clock driver. This would prevent leakage into the board supply. It is important to choose an appropriate ferrite bead with low DC resistance, because the bead must provide adequate isolation between the board supply and the chip supply. It is also important to maintain a voltage at the supply terminals that is greater than the minimum voltage required for proper operation.



**Figure 10. Power-Supply Decoupling**

#### **10.1.2 Thermal Management**

For reliability and performance reasons, limit the die temperature to a maximum of 125°C. That is, as an estimate,  $T_A$  (ambient temperature) plus device power consumption times  $R_{AJA}$  should not exceed 125°C.

Assuming the conditions in the *Power [Considerations](#page-16-3)* section and operating at an ambient temperature of 70°C with all outputs loaded, [Equation](#page-18-2) 11 shows the estimate of the LMK00804B-Q1 junction temperature:

$$
T_J = T_A + P_{Total} \times R_{\theta JA} = 70^{\circ}\text{C} + (124 \text{ mW} \times 48^{\circ}\text{C/W}) = 70^{\circ}\text{C} + 6.0^{\circ}\text{C} = 76.0^{\circ}\text{C}
$$
 (11)

<span id="page-18-2"></span>Here are some recommendations to improve heat flow away from the die:

- Use multi-layer boards
- Specify a higher copper thickness for the board
- Increase the number of vias from the top level ground plane under and around the device to internal layers and to the bottom layer with as much copper area flow on each level as possible
- Apply air flow
- Leave unused outputs floating



#### <span id="page-19-0"></span>**11 Layout**

#### <span id="page-19-1"></span>**11.1 Layout Guidelines**

#### **11.1.1 Ground Planes**

Solid ground planes are recommended because these planes provide a low-impedance return paths between the device and bypass capacitors, along with the clock source and destination devices.

Avoid return paths of other system circuitry (for example, high-speed/digital logic, switching power supplies, and so forth) from passing through the local ground of the device to minimize noise coupling. Remember that noise coupling can lead to added jitter and spurious noise.

#### **11.1.2 Power Supply Pins**

Follow the power supply schematic and layout example described in *[Power-Supply](#page-18-3) Filtering*.

#### **11.1.3 Differential Input Termination**

- Place input termination or biasing resistors as close to the CLK P/CLK N pins as possible.
- Avoid or minimize vias in the 50-Ω input traces to minimize impedance discontinuities. Intra-pair skew should also be minimized on the differential input traces.
- If not used, CLK\_P/CLK\_N inputs may be left as no connect.

#### **11.1.4 LVCMOS Input Termination**

- Input termination is not necessary when the LVCMOS\_CLK input is driven from a LVCMOS driver that is series-terminated to match the characteristic impedance of the trace. Otherwise, place the input termination resistor as close to the LVCMOS\_CLK input as possible.
- Avoid or minimize vias in the 50- $Ω$  input trace to minimize impedance discontinuities.
- If not used, LVCMOS CLK input may be left as no connect.

#### **11.1.5 Output Termination**

- Place 43-Ω series termination resistors close to the Qx outputs at the launch of the 50-Ω traces.
- Avoid or minimize vias in the  $50-\Omega$  input traces to minimize impedance discontinuities.
- If not used, any Qx output should be left as no connect.



#### <span id="page-20-0"></span>**11.2 Layout Example**

[Figure](#page-20-1) 11 shows the recommended PCB design for good electrical and thermal performance.



<span id="page-20-1"></span>

**STRUMENTS** 

#### <span id="page-21-0"></span>**12 Device and Documentation Support**

#### <span id="page-21-1"></span>**12.1 Documentation Support**

#### **12.1.1 Related Documentation**

For related documentation, see the following:

• *High-Speed Layout Guidelines,*

#### <span id="page-21-2"></span>**12.2 Receiving Notification of Documentation Updates**

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### <span id="page-21-3"></span>**12.3 Community Resources**

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of [Use.](http://www.ti.com/corp/docs/legal/termsofuse.shtml)

**TI E2E™ Online [Community](http://e2e.ti.com)** *TI's Engineer-to-Engineer (E2E) Community.* Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design [Support](http://support.ti.com/)** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### <span id="page-21-4"></span>**12.4 Trademarks**

E2E is a trademark of Texas Instruments. All other trademarks are the property of their respective owners.

#### <span id="page-21-5"></span>**12.5 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### <span id="page-21-6"></span>**12.6 Glossary**

[SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

#### <span id="page-21-7"></span>**13 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



www.ti.com 2-Jul-2019

### **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead/Ball Finish - Orderable Devices mav have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE OPTION ADDENDUM**

#### **OTHER QUALIFIED VERSIONS OF LMK00804B-Q1 :**

• Catalog: [LMK00804B](http://focus.ti.com/docs/prod/folders/print/lmk00804b.html)

NOTE: Qualified Version Definitions:

• Catalog - TI's standard catalog product

# **PACKAGE MATERIALS INFORMATION**

Texas<br>Instruments

#### **TAPE AND REEL INFORMATION**





### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





TEXAS<br>INSTRUMENTS

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 29-Jun-2019



\*All dimensions are nominal



# **GENERIC PACKAGE VIEW**

# **VQFN - 1 mm max height**<br>PLASTIC QUAD FLATPACK - NO LEAD



Images above are just a representation of the package family, actual package may vary.<br>Refer to the product data sheet for package details.





# **PACKAGE OUTLINE**

# **RGT0016J VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



#### NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. The package thermal pad must be soldered to the printed circuit board for thermal and mechanical performance.



# **EXAMPLE BOARD LAYOUT**

# **RGT0016J VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.



# **EXAMPLE STENCIL DESIGN**

# **RGT0016J VQFN - 1 mm max height**

PLASTIC QUAD FLATPACK - NO LEAD



6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



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