

## OCTAL SIMULTANEOUS-SAMPLING 24-BIT ANALOG-TO-DIGITAL CONVERTER

Check for Samples: [ADS1278-EP](#)

### FEATURES

- Simultaneously Measure Eight Channels
- Up to 128-kSPS Data Rate
- AC Performance:
  - 62-kHz Bandwidth
  - 111-dB SNR (High-Resolution Mode)
  - 108-dB THD
- DC Accuracy:
  - 0.8- $\mu$ V/ $^{\circ}$ C Offset Drift
  - 1.3-ppm/ $^{\circ}$ C Gain Drift
- Selectable Operating Modes:
  - High-Speed: 128 kSPS, 106 dB SNR
  - High-Resolution: 52 kSPS, 111 dB SNR
  - Low-Power: 52 kSPS, 31 mW/ch
  - Low-Speed: 10 kSPS, 7 mW/ch
- Linear Phase Digital Filter
- SPI™ or Frame-Sync Serial Interface
- Low Sampling Aperture Error
- Modulator Output Option (digital filter bypass)
- Analog Supply: 5 V
- Digital Core: 1.8 V
- I/O Supply: 1.8 V to 3.3 V
- Currently Available in an HTQFP-64 PowerPAD™ package

### SUPPORTS DEFENSE, AEROSPACE, AND MEDICAL APPLICATIONS

- Controlled Baseline
- One Assembly/Test Site
- One Fabrication Site
- Available in Military (–55°C/125°C) Temperature Range <sup>(1)</sup>
- Extended Product Life Cycle
- Extended Product-Change Notification
- Product Traceability

(1) Additional temperature ranges are available - contact factory

### APPLICATIONS

- Vibration/Modal Analysis
- Multi-Channel Data Acquisition
- Acoustics/Dynamic Strain Gauges
- Pressure Sensors

### DESCRIPTION

Based on the single-channel [ADS1271](#), the ADS1278 (octal) is a 24-bit, delta-sigma ( $\Delta\Sigma$ ) analog-to-digital converter (ADC) with data rates up to 128 k samples per second (SPS), allowing simultaneous sampling of eight channels.

Traditionally, industrial delta-sigma ADCs offering good drift performance use digital filters with large passband droop. As a result, they have limited signal bandwidth and are mostly suited for dc measurements. High-resolution ADCs in audio applications offer larger usable bandwidths, but the offset and drift specifications are significantly weaker than respective industrial counterparts. The ADS1278 combines these types of converters, allowing high-precision industrial measurement with excellent dc and ac specifications.

The high-order, chopper-stabilized modulator achieves very low drift with low in-band noise. The onboard decimation filter suppresses modulator and signal out-of-band noise. These ADCs provide a usable signal bandwidth up to 90% of the Nyquist rate with less than 0.005 dB of ripple.

Four operating modes allow for optimization of speed, resolution, and power. All operations are controlled directly by pins; there are no registers to program. The device is fully specified over the military temperature range (–55°C to 125°C) and is available in an HTQFP-64 PowerPAD package.

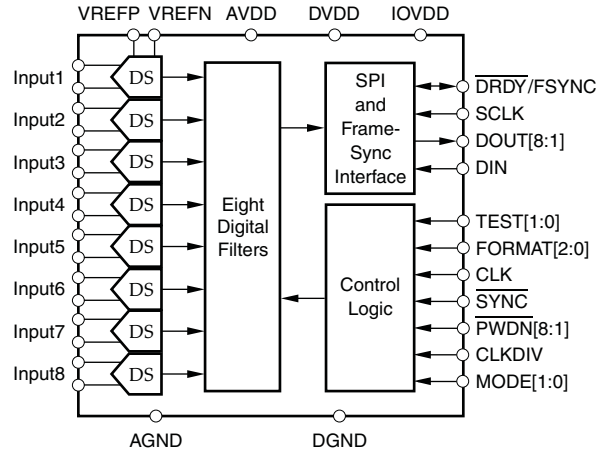


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ADS1278



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

**ORDERING INFORMATION<sup>(1)</sup>**

T <sub>A</sub>	PACKAGE		ORDERABLE PART NUMBER	TOP-SIDE MARKING	VID NUMBER
-55°C to 125°C	TQFP - PAP	Reel of 250	ADS1278MPAPTEP	ADS1278EP	V62/12611-01XE

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at [www.ti.com](http://www.ti.com).

PIN ASSIGNMENTS

PAP PACKAGE  
TQFP-64  
(TOP VIEW)

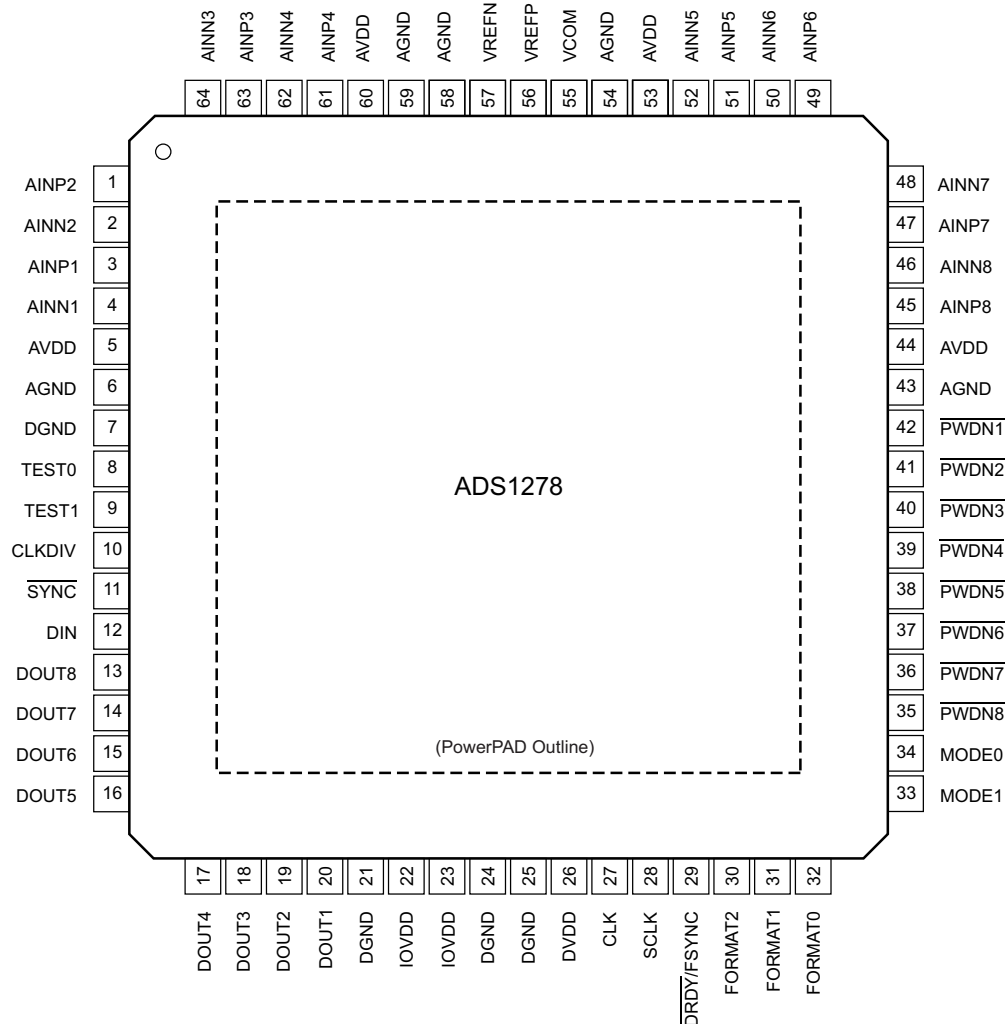


Table 1. PIN DESCRIPTIONS

PIN		FUNCTION	DESCRIPTION
NAME	NO.		
AGND	6, 43, 54, 58, 59	Analog ground	Analog ground; connect to DGND using a single plane.
AINP1	3	Analog input	AINP[8:1] Positive analog input, channels 8 through 1.
AINP2	1	Analog input	
AINP3	63	Analog input	
AINP4	61	Analog input	
AINP5	51	Analog input	
AINP6	49	Analog input	
AINP7	47	Analog input	
AINP8	45	Analog input	

**Table 1. PIN DESCRIPTIONS (continued)**

PIN		FUNCTION	DESCRIPTION
NAME	NO.		
AINN1	4	Analog input	AINN[8:1] Negative analog input, channels 8 through 1.
AINN2	2	Analog input	
AINN3	64	Analog input	
AINN4	62	Analog input	
AINN5	52	Analog input	
AINN6	50	Analog input	
AINN7	48	Analog input	
AINN8	46	Analog input	
AVDD	5, 44, 53, 60	Analog power supply	Analog power supply (4.75V to 5.25V).
VCOM	55	Analog output	AVDD/2 Unbuffered voltage output.
VREFN	57	Analog input	Negative reference input.
VREFP	56	Analog input	Positive reference input.
CLK	27	Digital input	Master clock input ( $f_{CLK}$ ).
CLKDIV	10	Digital input	CLK input divider control: 1 = 37MHz (High-Speed mode)/otherwise 27MHz 0 = 13.5MHz (low-power)/5.4MHz (low-speed)
DGND	7, 21, 24, 25	Digital ground	Digital ground power supply.
DIN	12	Digital input	Daisy-chain data input.
DOUT1	20	Digital output	DOUT[8:1] Data output for channels 8 through 1.
DOUT2	19	Digital output	
DOUT3	18	Digital output	
DOUT4	17	Digital output	
DOUT5	16	Digital output	
DOUT6	15	Digital output	
DOUT7	14	Digital output	
DOUT8	13	Digital output	
$\overline{DRDY}/FSYNC$	29	Digital input/output	Frame-Sync protocol: frame clock input; SPI protocol: data ready output.
DVDD	26	Digital power supply	Digital core power supply.
FORMAT0	32	Digital input	FORMAT[2:0] Selects Frame-Sync/SPI protocol, TDM/discrete data outputs, fixed/dynamic position TDM data, and modulator mode/normal operating mode.
FORMAT1	31	Digital input	
FORMAT2	30	Digital input	
IOVDD	22, 23	Digital power supply	I/O power supply (+1.65V to +3.6V).
MODE0	34	Digital input	MODE[1:0] Selects High-Speed, High-Resolution, Low-Power, or Low-Speed mode operation.
MODE1	33	Digital input	
$\overline{PWDN1}$	42	Digital input	$\overline{PWDN}$ [8:1] Power-down control for channels 8 through 1.
$\overline{PWDN2}$	41	Digital input	
$\overline{PWDN3}$	40	Digital input	
$\overline{PWDN4}$	39	Digital input	
$\overline{PWDN5}$	38	Digital input	
$\overline{PWDN6}$	37	Digital input	
$\overline{PWDN7}$	36	Digital input	
$\overline{PWDN8}$	35	Digital input	
SCLK	28	Digital input/output	Serial clock input, Modulator clock output.
$\overline{SYNC}$	11	Digital input	Synchronize input (all channels).
TEST0	8	Digital input	TEST[1:0] Test mode select: 00 = Normal operation 01 = Do not use 11 = Test mode 10 = Do not use
TEST1	9	Digital input	

## ABSOLUTE MAXIMUM RATINGS

Over operating free-air temperature range, unless otherwise noted<sup>(1)</sup>

			UNIT
AVDD to AGND		–0.3 to 6.0	V
DVDD, IOVDD to DGND		–0.3 to 3.6	V
AGND to DGND		–0.3 to 0.3	V
Input current	Momentary	100	mA
	Continuous	10	mA
Analog input to AGND		–0.3 to AVDD + 0.3	V
Digital input or output to DGND		–0.3 to DVDD + 0.3	V
Maximum junction temperature, T <sub>J</sub>		150	°C
Storage temperature range		–60 to 150	°C

- (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those specified is not implied.

## THERMAL INFORMATION

THERMAL METRIC <sup>(1)</sup>		ADS1278	UNITS
		PAP	
		64 PINS	
$\theta_{JA}$	Junction-to-ambient thermal resistance <sup>(2)</sup>	33.1	°C/W
$\theta_{JC}$	Junction-to-case thermal resistance	6.2	
$\theta_{JB}$	Junction-to-board thermal resistance <sup>(3)</sup>	7.9	
$\psi_{JT}$	Junction-to-top characterization parameter <sup>(4)</sup>	0.2	
$\psi_{JB}$	Junction-to-board characterization parameter <sup>(5)</sup>	7.8	

- (1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, [SPRA953](#).
- (2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
- (3) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
- (4) The junction-to-top characterization parameter,  $\psi_{JT}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).
- (5) The junction-to-board characterization parameter,  $\psi_{JB}$ , estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining  $\theta_{JA}$ , using a procedure described in JESD51-2a (sections 6 and 7).

## ELECTRICAL CHARACTERISTICS

All specifications at  $T_A = -55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $\text{AVDD} = 5\text{ V}$ ,  $\text{DVDD} = 1.8\text{ V}$ ,  $\text{IOVDD} = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $\text{VREFP} = 2.5\text{ V}$ ,  $\text{VREFN} = 0\text{ V}$ , and all channels active, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Operating temperature range, $T_A$			-55		125	$^{\circ}\text{C}$
<b>Analog Inputs</b>						
Full-scale input voltage (FSR <sup>(1)</sup> )		$V_{\text{IN}} = (\text{AINP} - \text{AINN})$		$\pm V_{\text{REF}}$		V
Absolute input voltage		AINP or AINN to AGND	AGND - 0.1		AVDD + 0.1	V
Common-mode input voltage ( $V_{\text{CM}}$ )		$V_{\text{CM}} = (\text{AINP} + \text{AINN})/2$		2.5		V
Differential input impedance	High-Speed mode			14		k $\Omega$
	High-Resolution mode			14		k $\Omega$
	Low-Power mode			28		k $\Omega$
	Low-Speed mode			140		k $\Omega$
<b>DC Performance</b>						
Resolution		No missing codes	24			Bits
Data rate ( $f_{\text{DATA}}$ )	High-Speed mode	$f_{\text{CLK}} = 32.768\text{MHz}^{(2)}$		128,000		SPS
		$f_{\text{CLK}} = 27\text{MHz}$		105,469		SPS <sup>(3)</sup>
	High-Resolution mode			52,734		SPS
	Low-Power mode			52,734		SPS
	Low-Speed mode			10,547		SPS
Integral nonlinearity (INL) <sup>(4)</sup>		Differential input, $V_{\text{CM}} = 2.5\text{V}$		$\pm 0.0003$	$\pm 0.0014$	% FSR <sup>(1)</sup>
Offset error				0.25	2	mV
Offset drift				0.8		$\mu\text{V}/^{\circ}\text{C}$
Gain error				0.1	0.5	% FSR
Gain drift				1.3		ppm/ $^{\circ}\text{C}$
Noise	High-Speed mode	Shorted input		8.5	68	$\mu\text{V}$ , rms
	High-Resolution mode	Shorted input		5.5	13	$\mu\text{V}$ , rms
	Low-Power mode	Shorted input		8.5	21	$\mu\text{V}$ , rms
	Low-Speed mode	Shorted input		8.0	21	$\mu\text{V}$ , rms
Common-mode rejection		$f_{\text{CM}} = 60\text{Hz}$	90	108		dB
Power-supply rejection	AVDD	$f_{\text{PS}} = 60\text{Hz}$		80		dB
	DVDD			85		dB
	IOVDD			105		dB
$V_{\text{COM}}$ output voltage		No load		AVDD/2		V
<b>AC Performance</b>						
Crosstalk		$f = 1\text{kHz}$ , $-0.5\text{dBFS}^{(5)}$		-107		dB
Signal-to-noise ratio (SNR) <sup>(6)</sup> (unweighted)	High-Speed mode		88.3	106		dB
	High-Resolution mode	$V_{\text{REF}} = 2.5\text{V}$	101	110		dB
		$V_{\text{REF}} = 3\text{V}$		111		dB
	Low-Power mode		98	106		dB
	Low-Speed mode		98	107		dB
Total harmonic distortion (THD) <sup>(7)</sup>		$V_{\text{IN}} = 1\text{kHz}$ , $-0.5\text{dBFS}$		-108	-96	dB
Spurious-free dynamic range				109		dB
Passband ripple				$\pm 0.005$		dB
Passband				$0.453 f_{\text{DATA}}$		Hz
-3dB Bandwidth				$0.49 f_{\text{DATA}}$		Hz

(1) FSR = full-scale range =  $2V_{\text{REF}}$ .

(2)  $f_{\text{CLK}} = 32.768\text{MHz}$  max for High-Speed mode, and  $27\text{MHz}$  max for all other modes. When  $f_{\text{CLK}} > 27\text{MHz}$ , operation is limited to Frame-Sync mode and  $V_{\text{REF}} \leq 2.6\text{V}$ .

(3) SPS = samples per second.

(4) Best fit method.

(5) Worst-case channel crosstalk between one or more channels.

(6) Minimum SNR is ensured by the limit of the DC noise specification.

(7) THD includes the first nine harmonics of the input signal; Low-Speed mode includes the first five harmonics.

**ELECTRICAL CHARACTERISTICS (continued)**

All specifications at  $T_A = -55^\circ\text{C}$  to  $125^\circ\text{C}$ ,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ ,  $V_{\text{REFN}} = 0\text{ V}$ , and all channels active, unless otherwise noted.

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
Stop band attenuation	High-Resolution mode		95			dB
	All other modes		100			
Stop band	High-Resolution mode		$0.547 f_{\text{DATA}}$		$127.453 f_{\text{DATA}}$	Hz
	All other modes		$0.547 f_{\text{DATA}}$		$63.453 f_{\text{DATA}}$	Hz
Group delay	High-Resolution mode			$39/f_{\text{DATA}}$		s
	All other modes			$38/f_{\text{DATA}}$		s
Settling time (latency)	High-Resolution mode	Complete settling		$78/f_{\text{DATA}}$		s
	All other modes	Complete settling		$76/f_{\text{DATA}}$		s
<b>Voltage Reference Inputs</b>						
Reference input voltage ( $V_{\text{REF}}$ ) ( $V_{\text{REF}} = V_{\text{REFP}} - V_{\text{REFN}}$ )		$f_{\text{CLK}} = 27\text{MHz}$	0.5	2.5	3.1	V
		$f_{\text{CLK}} = 32.768\text{MHz}^{(2)}$	0.5	2.5	2.6	V
Negative reference input ( $V_{\text{REFN}}$ )			AGND – 0.1		AGND + 0.1	V
Positive reference input ( $V_{\text{REFP}}$ )			$V_{\text{REFN}} + 0.5$		$AVDD + 0.1$	V
Reference Input impedance	High-Speed mode			0.65		k $\Omega$
	High-Resolution mode			0.65		k $\Omega$
	Low-Power mode			1.3		k $\Omega$
	Low-Speed mode			6.5		k $\Omega$
<b>Digital Input/Output (IOVDD = 1.8V to 3.6V)</b>						
$V_{\text{IH}}$			$0.7\text{ IOVDD}$		IOVDD	V
$V_{\text{IL}}$			DGND		$0.3\text{ IOVDD}$	V
$V_{\text{OH}}$		$I_{\text{OH}} = 4\text{mA}$	$0.8\text{ IOVDD}$		IOVDD	V
$V_{\text{OL}}$		$I_{\text{OL}} = 4\text{mA}$	DGND		$0.2\text{ IOVDD}$	V
Input leakage		$0 < V_{\text{IN DIGITAL}} < \text{IOVDD}$			$\pm 10$	$\mu\text{A}$
Master clock rate ( $f_{\text{CLK}}$ )		High-Speed mode <sup>(8)</sup>	0.1		32.768	MHz
		Other modes	0.1		27	MHz
<b>Power Supply</b>						
AVDD			4.75	5	5.25	V
DVDD			1.65	1.8	1.95	V
IOVDD			1.65		3.6	V
Power-down current	AVDD			1	10	$\mu\text{A}$
	DVDD			1	50	$\mu\text{A}$
	IOVDD			1	11	$\mu\text{A}$
AVDD current	High-Speed mode			97	145	mA
	High-Resolution mode			97	145	mA
	Low-Power mode			44	64	mA
	Low-Speed mode			9	14	mA
DVDD current	High-Speed mode			23	30	mA
	High-Resolution mode			16	20	mA
	Low-Power mode			12	17	mA
	Low-Speed mode			2.5	4.5	mA
IOVDD current	High-Speed mode			0.25	1	mA
	High-Resolution mode			0.125	0.6	mA
	Low-Power mode			0.125	0.6	mA
	Low-Speed mode			0.035	0.3	mA

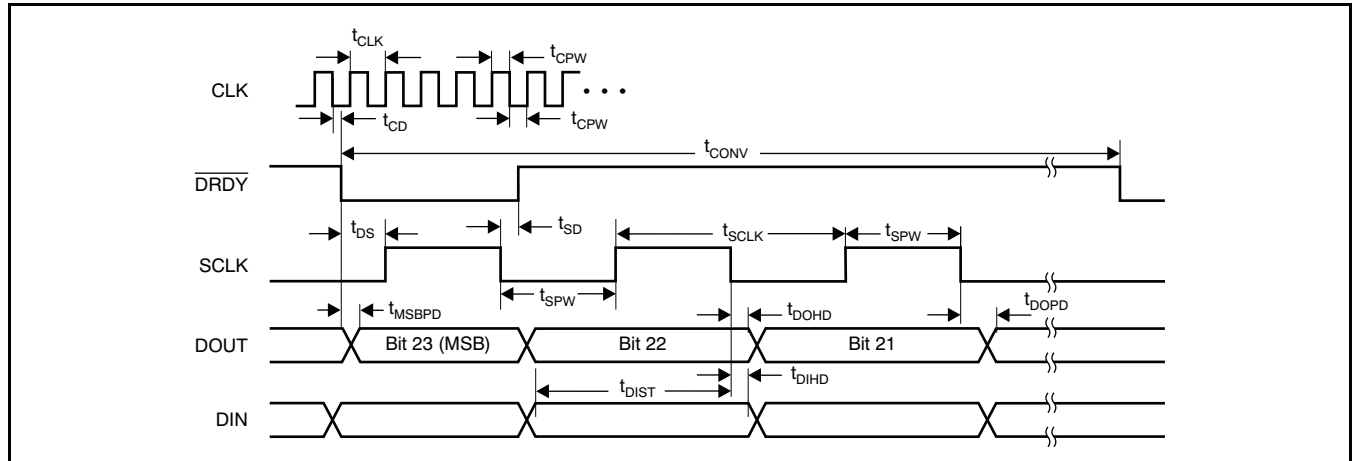
(8)  $f_{\text{CLK}} = 32.768\text{MHz}$  max for High-Speed mode, and  $27\text{MHz}$  max for all other modes. When  $f_{\text{CLK}} > 27\text{MHz}$ , operation is limited to Frame-Sync mode and  $V_{\text{REF}} \leq 2.6\text{V}$ .

### ELECTRICAL CHARACTERISTICS (continued)

All specifications at  $T_A = -55^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $\text{AVDD} = 5\text{ V}$ ,  $\text{DVDD} = 1.8\text{ V}$ ,  $\text{IOVDD} = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $\text{VREFP} = 2.5\text{ V}$ ,  $\text{VREFN} = 0\text{ V}$ , and all channels active, unless otherwise noted.

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Power dissipation	High-Speed mode		530	785	mW
	High-Resolution mode		515	765	mW
	Low-Power mode		245	355	mW
	Low-Speed mode		50	80	mW

### TIMING CHARACTERISTICS: SPI FORMAT



### TIMING REQUIREMENTS: SPI FORMAT

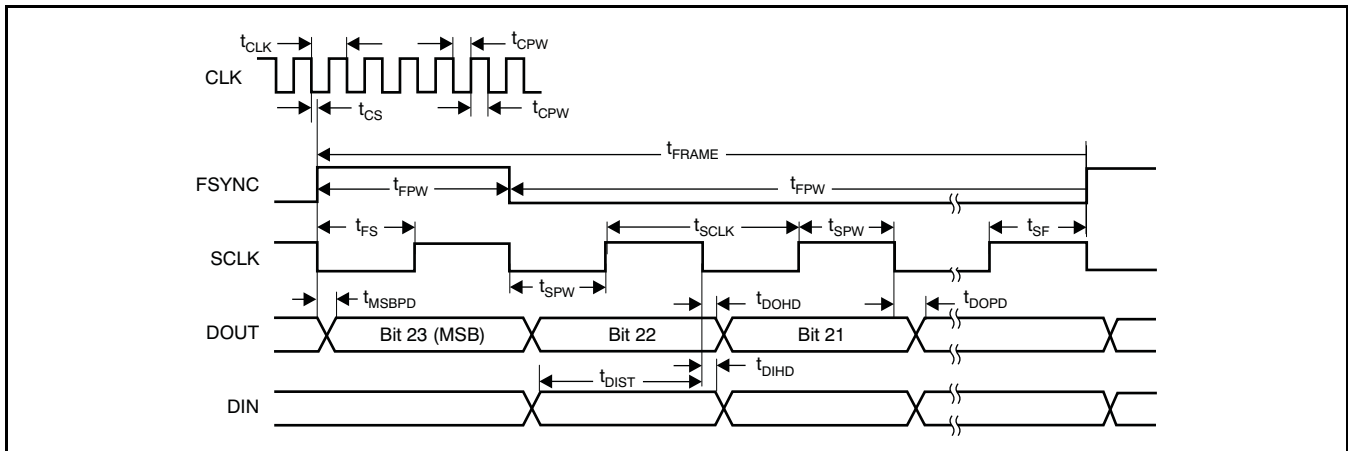
For  $T_A = -40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ ,  $\text{IOVDD} = 1.65\text{ V}$  to  $3.6\text{ V}$ , and  $\text{DVDD} = 1.65\text{ V}$  to  $1.95\text{ V}$ .

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT
$t_{\text{CLK}}$	CLK period ( $1/f_{\text{CLK}}$ ) <sup>(1)</sup>	37		10,000	ns
$t_{\text{CPW}}$	CLK positive or negative pulse width	15			ns
$t_{\text{CONV}}$	Conversion period ( $1/f_{\text{DATA}}$ ) <sup>(2)</sup>	256		2560	$t_{\text{CLK}}$
$t_{\text{CD}}$ <sup>(3)</sup>	Falling edge of CLK to falling edge of DRDY		22		ns
$t_{\text{DS}}$ <sup>(3)</sup>	Falling edge of DRDY to rising edge of first SCLK to retrieve data	1			$t_{\text{CLK}}$
$t_{\text{MSBDP}}$	DRDY falling edge to DOUT MSB valid (propagation delay)			16	ns
$t_{\text{SD}}$ <sup>(3)</sup>	Falling edge of SCLK to rising edge of DRDY		18		ns
$t_{\text{SCLK}}$ <sup>(4)</sup>	SCLK period	1			$t_{\text{CLK}}$
$t_{\text{SPW}}$	SCLK positive or negative pulse width	0.4			$t_{\text{CLK}}$
$t_{\text{DOHD}}$ <sup>(5)(3)(6)</sup>	SCLK falling edge to new DOUT invalid (hold time)	10			ns
$t_{\text{DOPD}}$ <sup>(5)(3)</sup>	SCLK falling edge to new DOUT valid (propagation delay)			32	ns
$t_{\text{DIST}}$	New DIN valid to falling edge of SCLK (setup time)	6			ns
$t_{\text{DIHD}}$ <sup>(6)</sup>	Old DIN valid to falling edge of SCLK (hold time)	6			ns

- (1)  $f_{\text{CLK}} = 27\text{ MHz}$  maximum.
- (2) Depends on  $\text{MODE}[1:0]$  and  $\text{CLKDIV}$  selection. See Table 7 ( $f_{\text{CLK}}/f_{\text{DATA}}$ ).
- (3) Load on DRDY and DOUT = 20pF.
- (4) For best performance, limit  $f_{\text{SCLK}}/f_{\text{CLK}}$  to ratios of 1, 1/2, 1/4, 1/8, etc.
- (5) Timing parameters are characterized or guaranteed by design for specified temperature but not production tested.
- (6)  $t_{\text{DOHD}}$  (DOUT hold time) and  $t_{\text{DIHD}}$  (DIN hold time) are specified under opposite worst-case conditions (digital supply voltage and ambient temperature). Under equal conditions, with DOUT connected directly to DIN, the timing margin is >4ns.



Figure 1. TIMING CHARACTERISTICS: FRAME-SYNC FORMAT

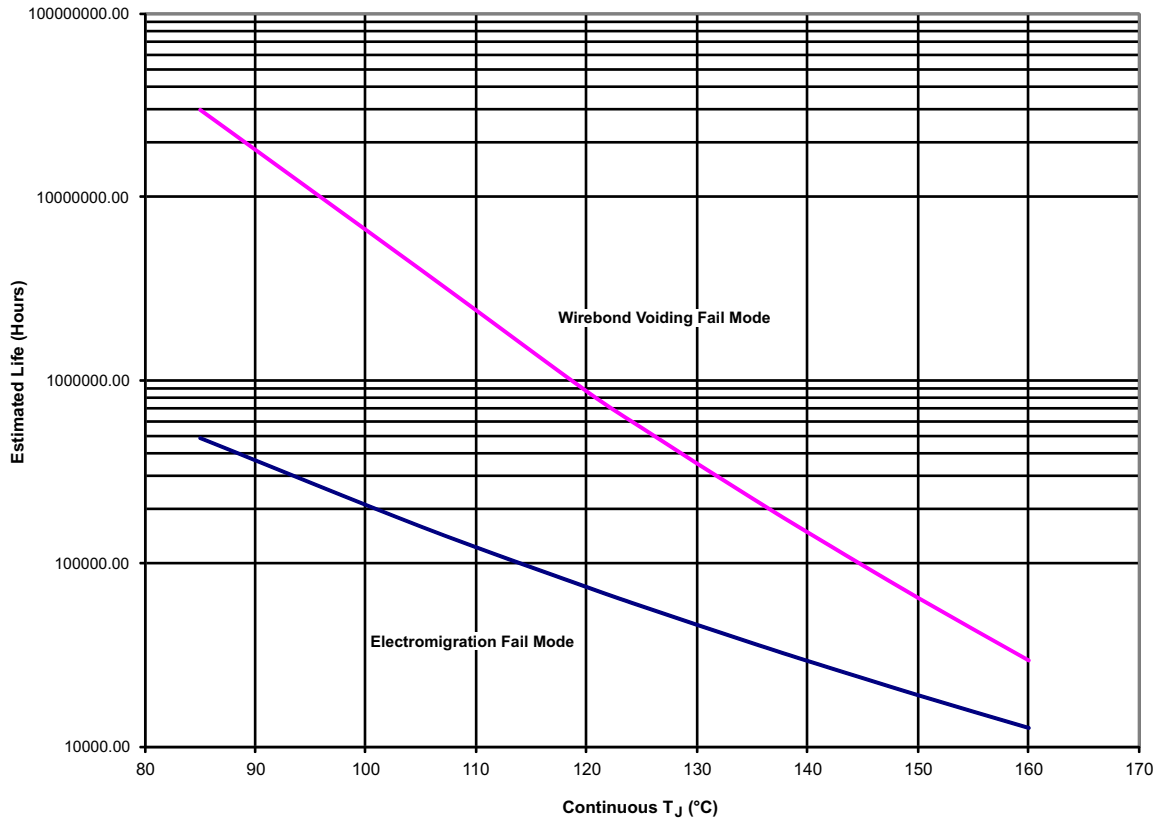


TIMING REQUIREMENTS: FRAME-SYNC FORMAT<sup>(1)</sup>

For  $T_A = -40^\circ\text{C}$  to  $125^\circ\text{C}$ ,  $\text{IOVDD} = 1.65\text{ V}$  to  $3.6\text{ V}$ , and  $\text{DVDD} = 1.65\text{ V}$  to  $1.95\text{ V}$ .

SYMBOL	PARAMETER	MIN	TYP	MAX	UNIT	
$t_{CLK}$	CLK period ( $1/f_{CLK}$ )	All modes		37	10,000	ns
		High-Speed mode only		30.5		ns
$t_{CPW}$	CLK positive or negative pulse width	12			ns	
$t_{CS}$	Falling edge of CLK to falling edge of SCLK	-0.25		0.25	$t_{CLK}$	
$t_{FRAME}$	Frame period ( $1/f_{DATA}$ ) <sup>(2)</sup>	256		2560	$t_{CLK}$	
$t_{FPW}$	FSYNC positive or negative pulse width	1			$t_{SCLK}$	
$t_{FS}$	Rising edge of FSYNC to rising edge of SCLK	5			ns	
$t_{SF}$	Rising edge of SCLK to rising edge of FSYNC	5			ns	
$t_{SCLK}$	SCLK period <sup>(3)</sup>	1			$t_{CLK}$	
$t_{SPW}$	SCLK positive or negative pulse width	0.4			$t_{CLK}$	
$t_{DOHD}$ <sup>(4)(5) (6)</sup>	SCLK falling edge to old DOUT invalid (hold time)	10			ns	
$t_{DOPD}$ <sup>(4)(6)</sup>	SCLK falling edge to new DOUT valid (propagation delay)			31	ns	
$t_{MSBPD}$ <sup>(4)</sup>	FSYNC rising edge to DOUT MSB valid (propagation delay)			31	ns	
$t_{DIST}$	New DIN valid to falling edge of SCLK (setup time)	6			ns	
$t_{DIHD}$ <sup>(5)</sup>	Old DIN valid to falling edge of SCLK (hold time)	6			ns	

- (1) Timing parameters are characterized or guaranteed by design for specified temperature but not production tested.
- (2) Depends on MODE[1:0] and CLKDIV selection. See Table 7 ( $f_{CLK}/f_{DATA}$ ).
- (3) SCLK must be continuously running and limited to ratios of 1, 1/2, 1/4, and 1/8 of  $f_{CLK}$ .
- (4) Timing parameters are characterized or guaranteed by design for specified temperature but not production tested.
- (5)  $t_{DOHD}$  (DOUT hold time) and  $t_{DIHD}$  (DIN hold time) are specified under opposite worst-case conditions (digital supply voltage and ambient temperature). Under equal conditions, with DOUT connected directly to DIN, the timing margin is >4 ns.
- (6) Load on DOUT = 20 pF.



**Figure 2. ADS1278 Operating Life Derating and Wirebond Voiding Fail Mode Chart**

Notes:

1. See datasheet for absolute maximum and minimum recommended operating conditions.
2. Silicon operating life design goal is 10 years at 110°C junction temperature.

**TYPICAL CHARACTERISTICS**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode, AVDD = 5 V, DVDD = 1.8 V, IOVDD = 3.3 V,  $f_{\text{CLK}} = 27 \text{ MHz}$ , VREFP = 2.5 V, and VREFN = 0 V, unless otherwise noted.

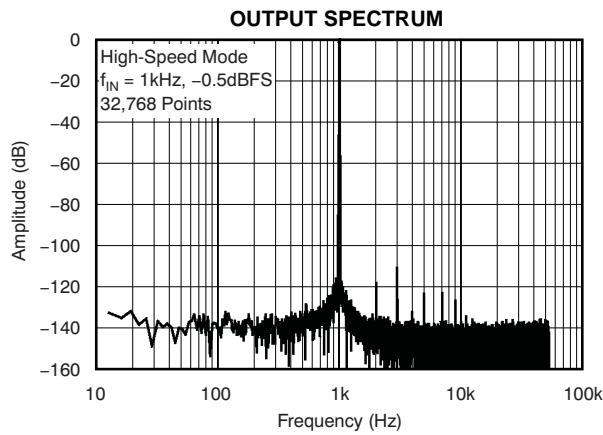


Figure 3.

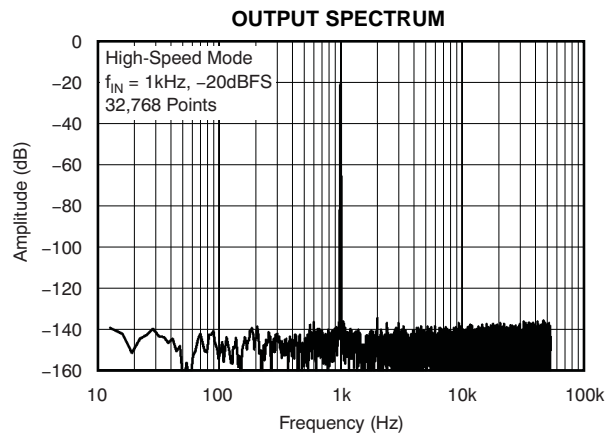


Figure 4.

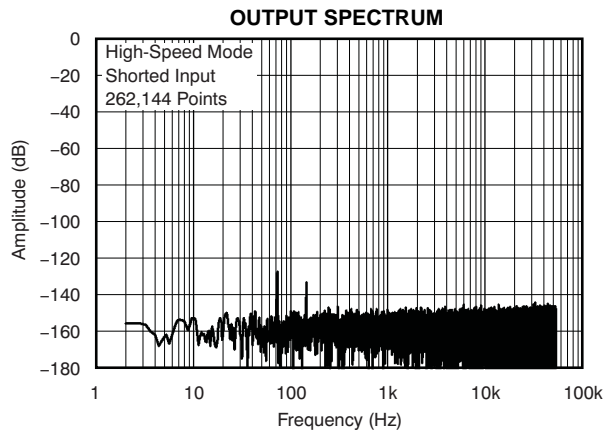


Figure 5.

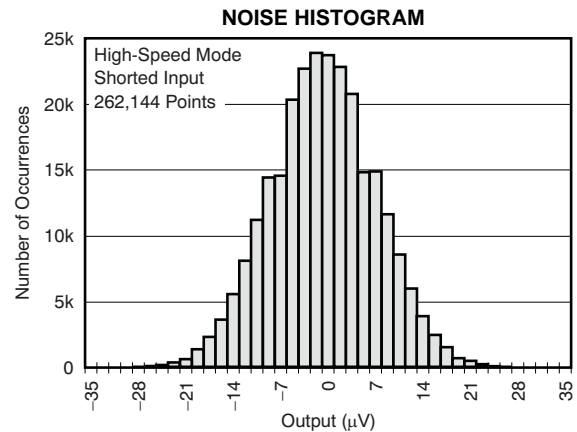


Figure 6.

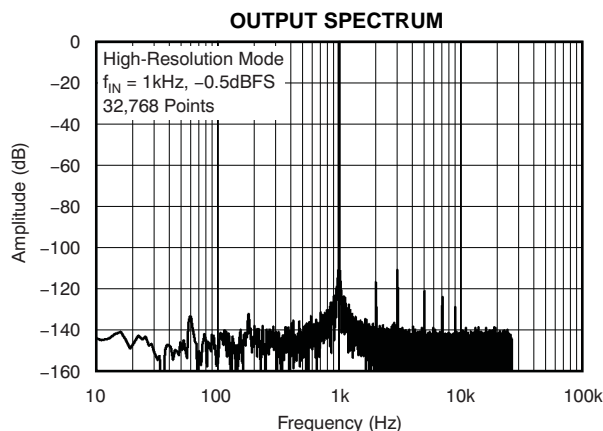


Figure 7.

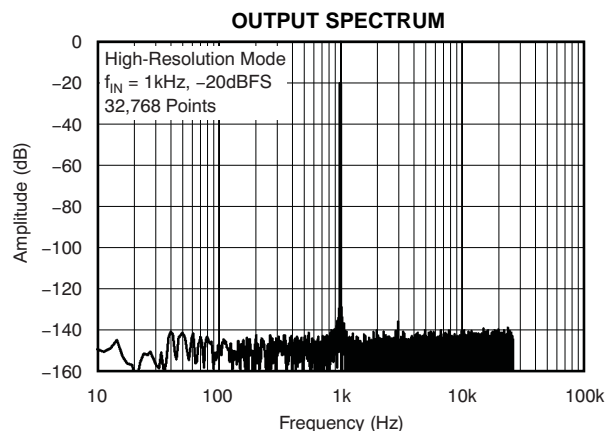


Figure 8.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IOV_{DD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

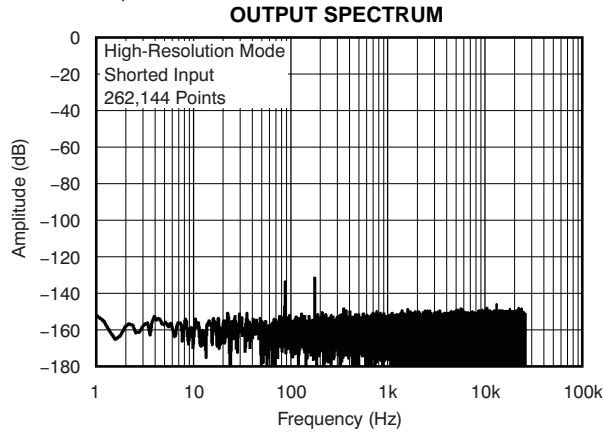


Figure 9.

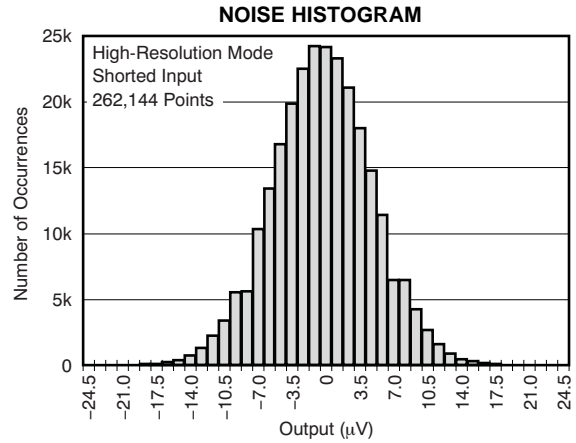


Figure 10.

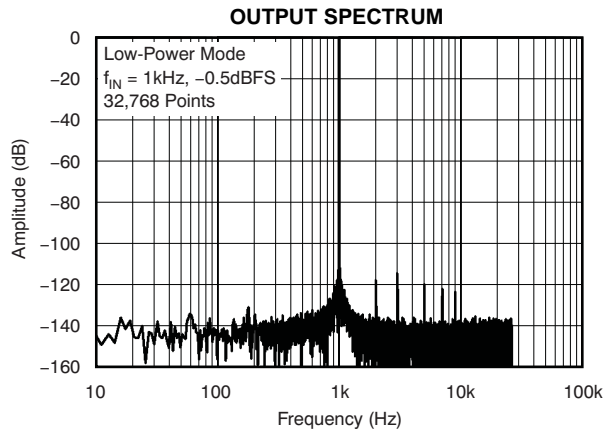


Figure 11.

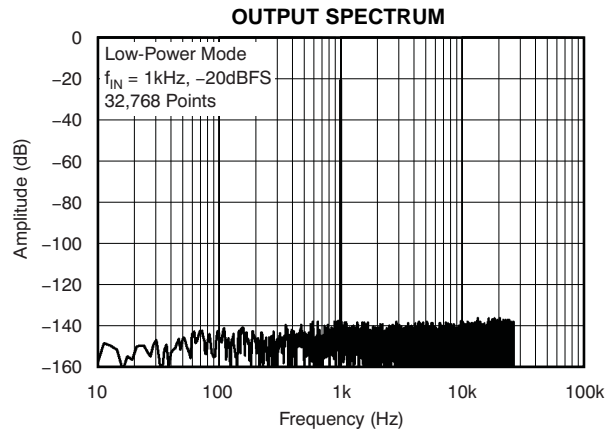


Figure 12.

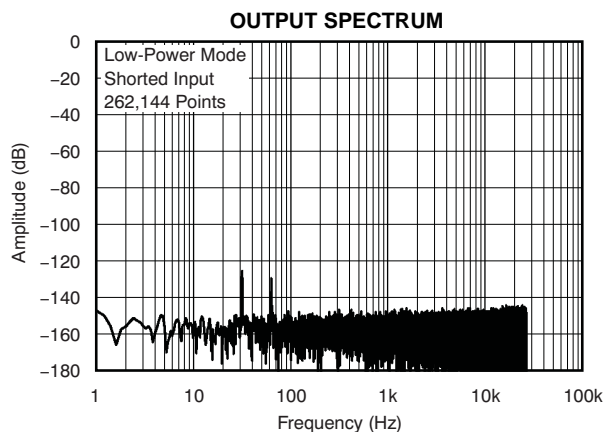


Figure 13.

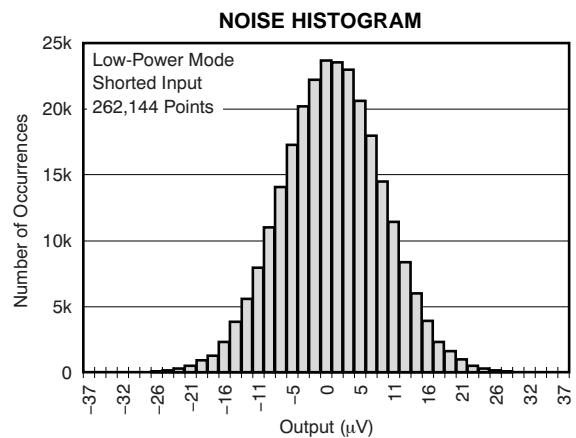


Figure 14.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IO_{VDD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

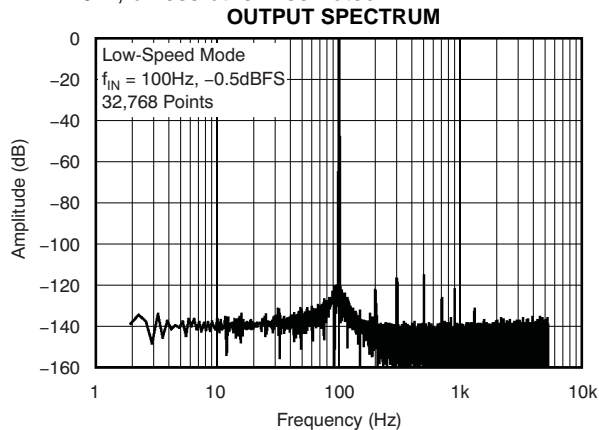


Figure 15.

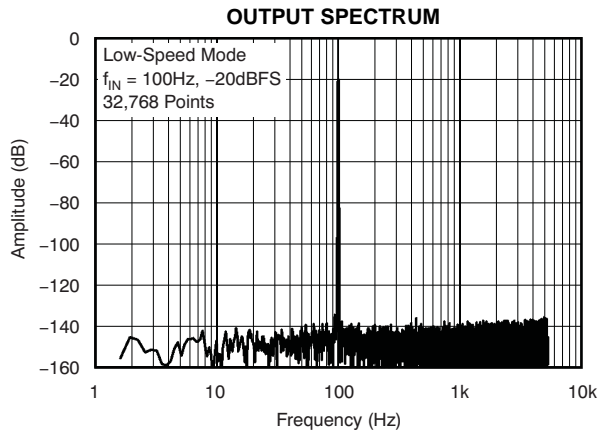


Figure 16.

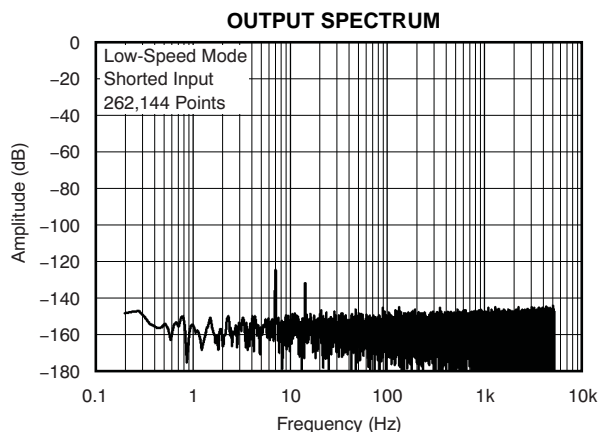


Figure 17.

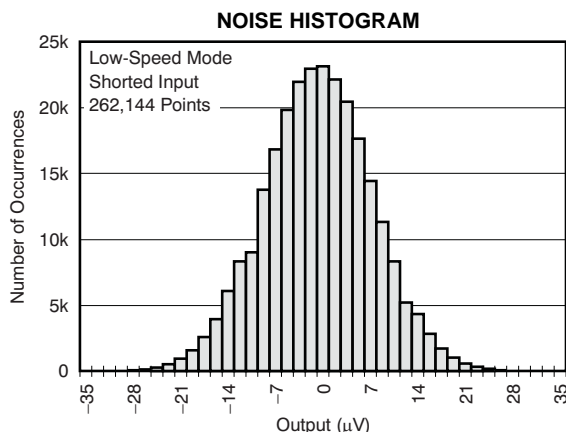


Figure 18.

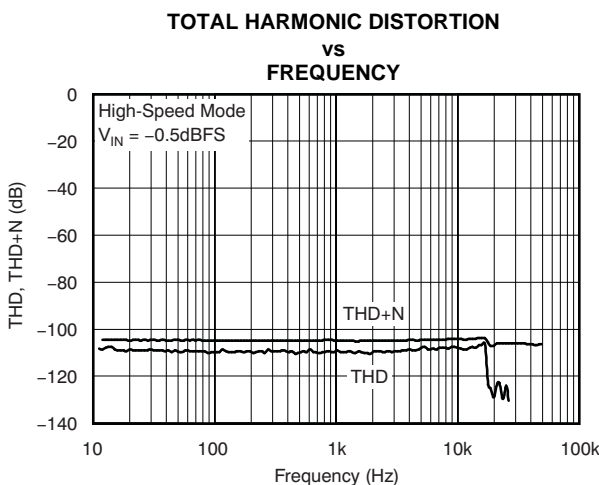


Figure 19.

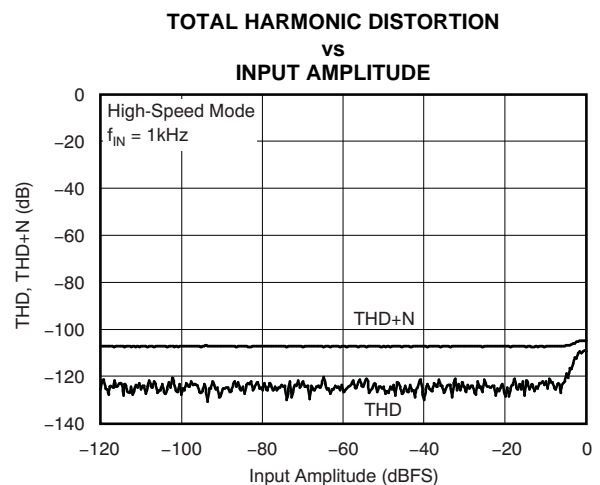


Figure 20.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IOV_{DD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

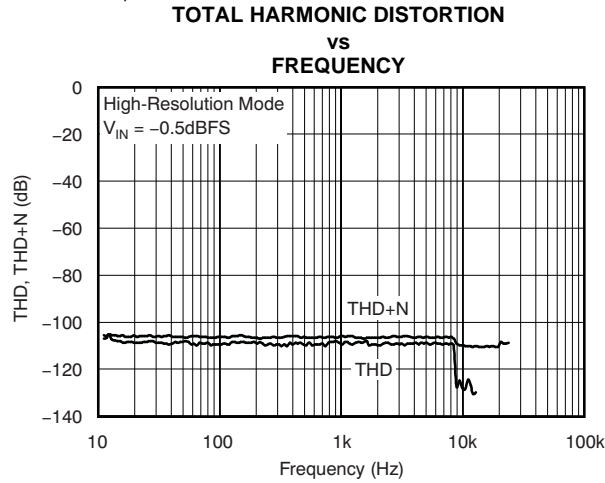


Figure 21.

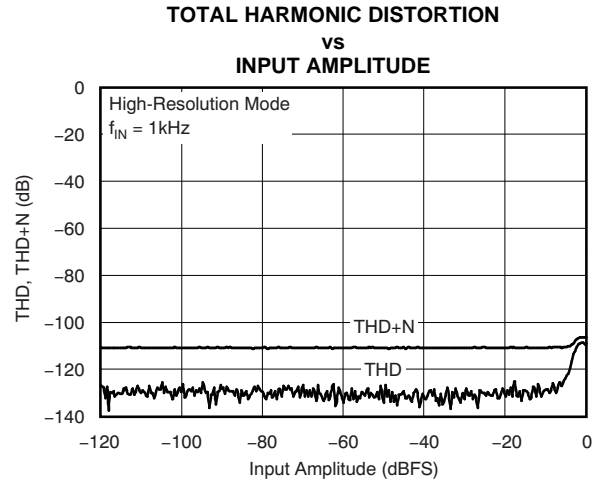


Figure 22.

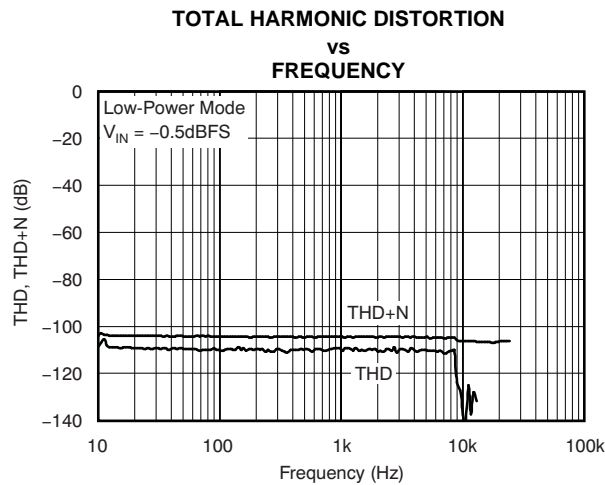


Figure 23.

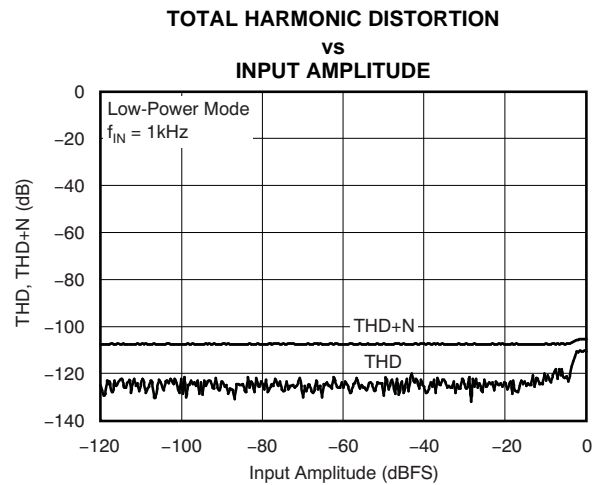


Figure 24.

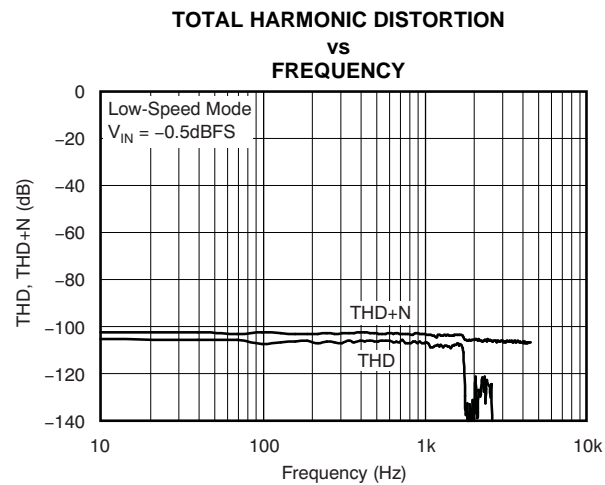


Figure 25.

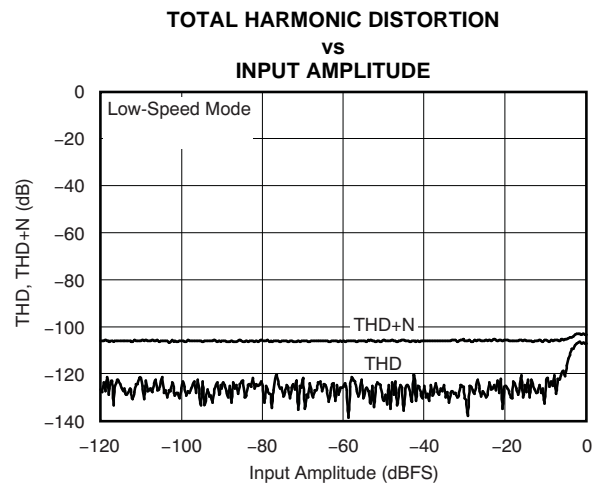


Figure 26.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IOV_{DD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

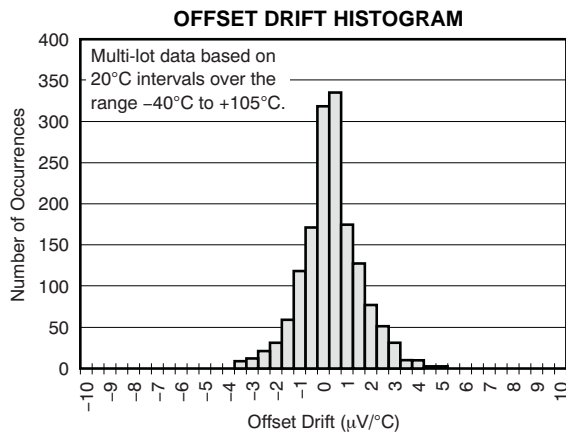


Figure 27.

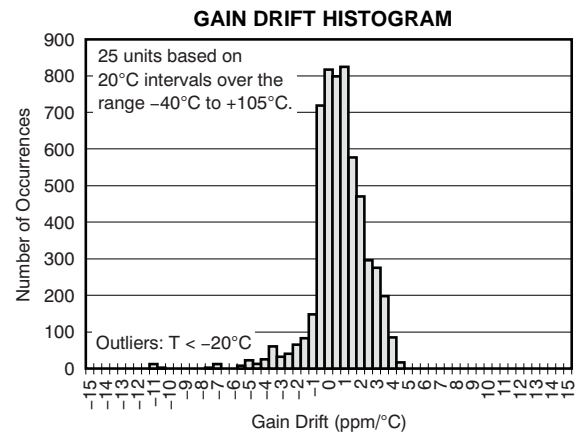


Figure 28.

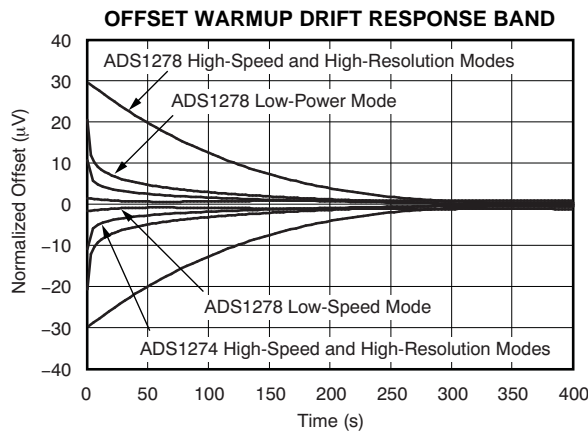


Figure 29.

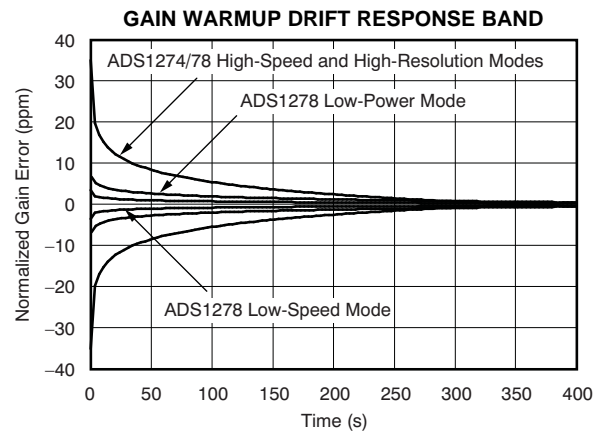


Figure 30.

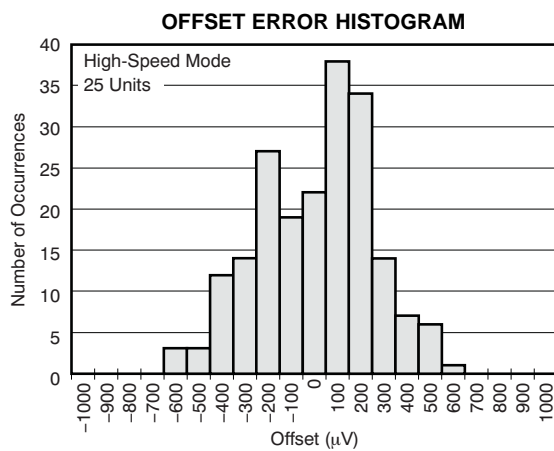


Figure 31.

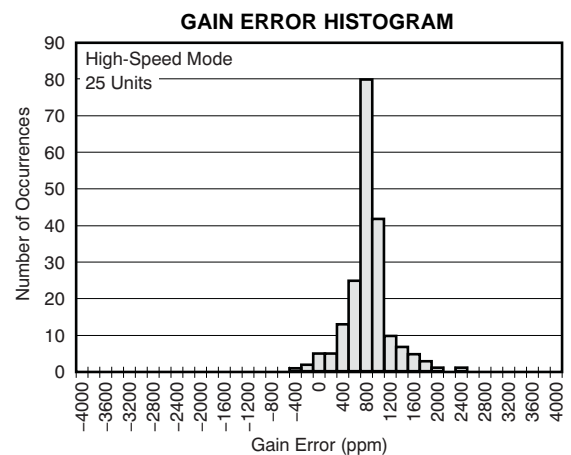


Figure 32.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IOV_{DD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

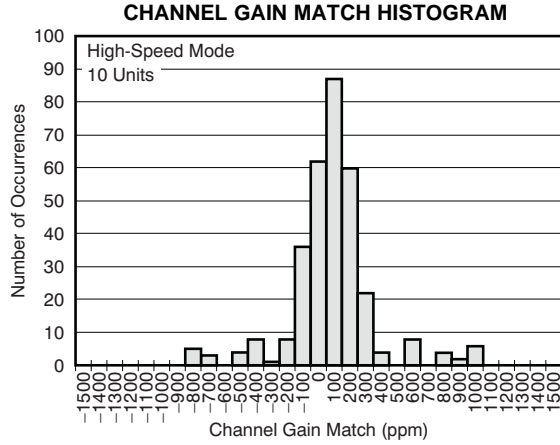


Figure 33.

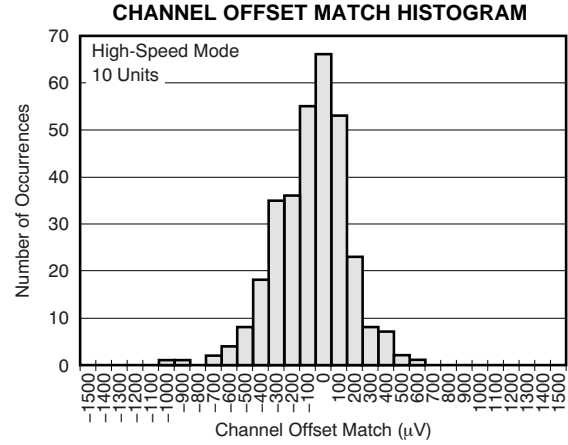


Figure 34.

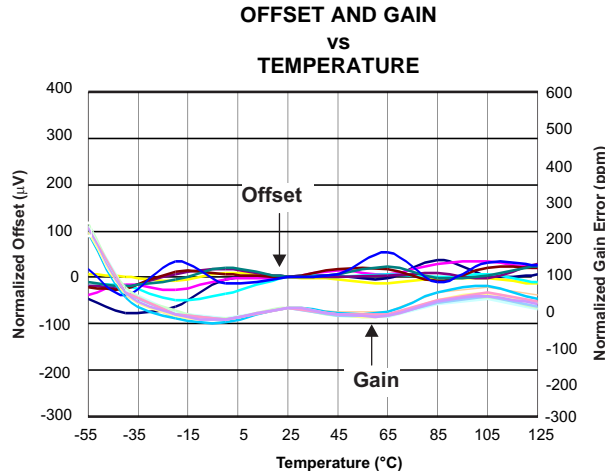


Figure 35.

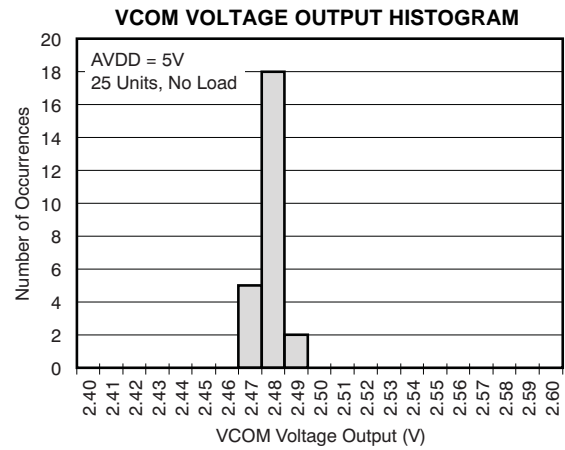


Figure 36.

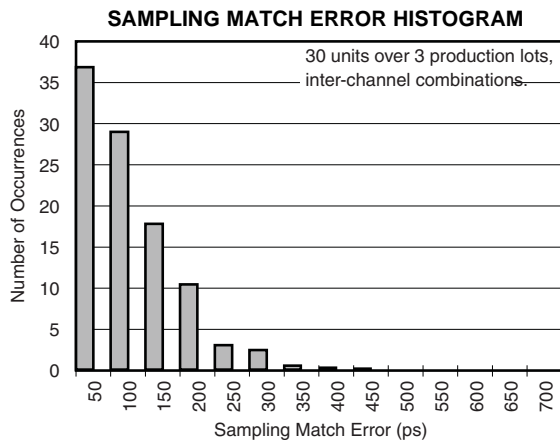


Figure 37.

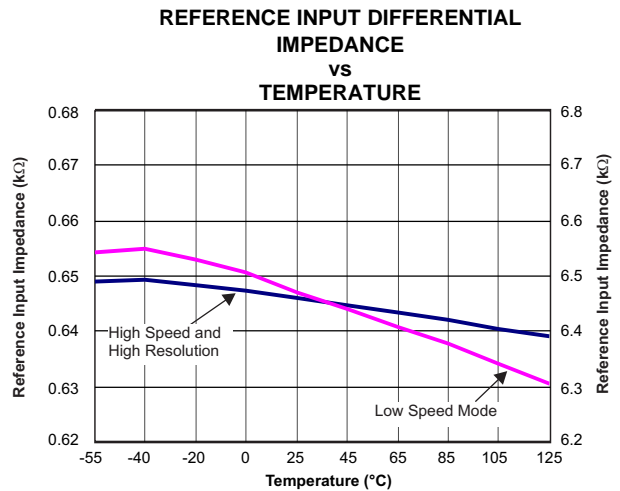


Figure 38.



**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AV_{DD} = 5\text{ V}$ ,  $DV_{DD} = 1.8\text{ V}$ ,  $IO_{VDD} = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $V_{REFP} = 2.5\text{ V}$ , and  $V_{REFN} = 0\text{ V}$ , unless otherwise noted.

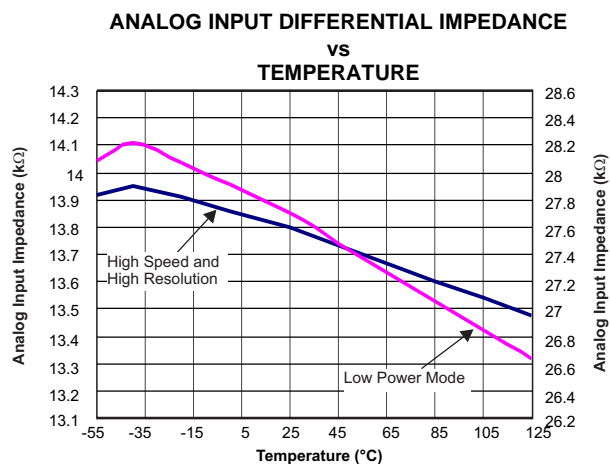


Figure 39.

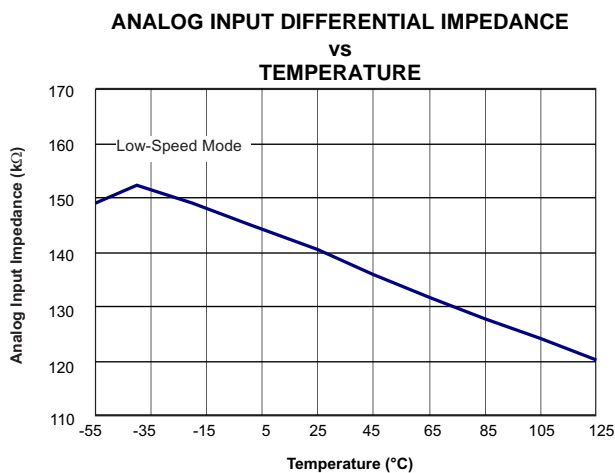


Figure 40.

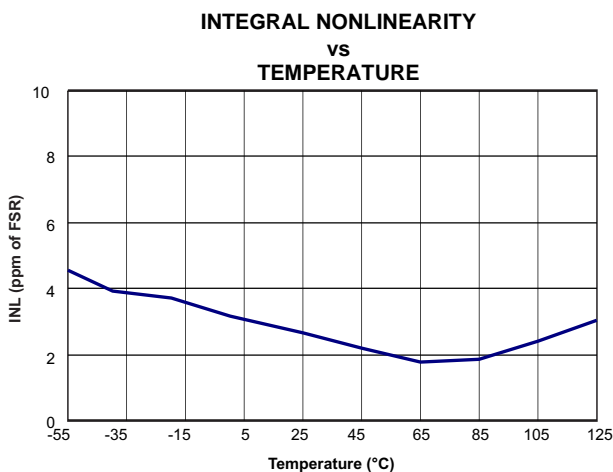


Figure 41.

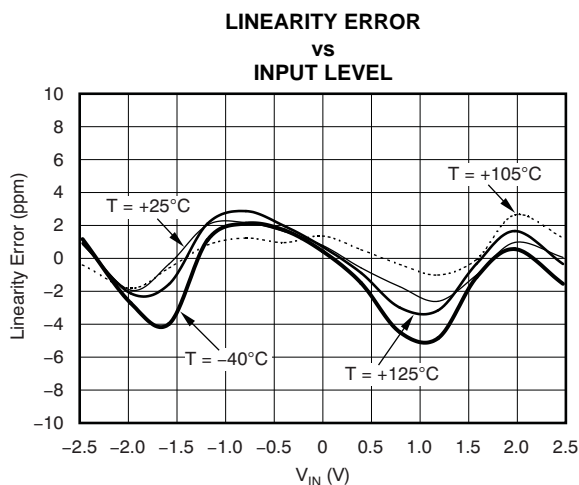


Figure 42.

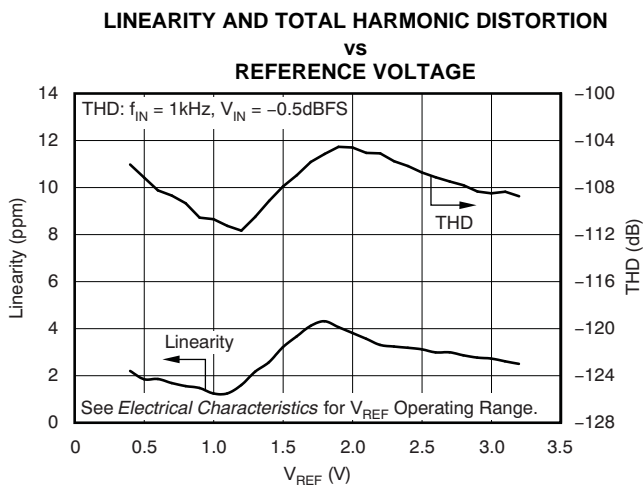


Figure 43.

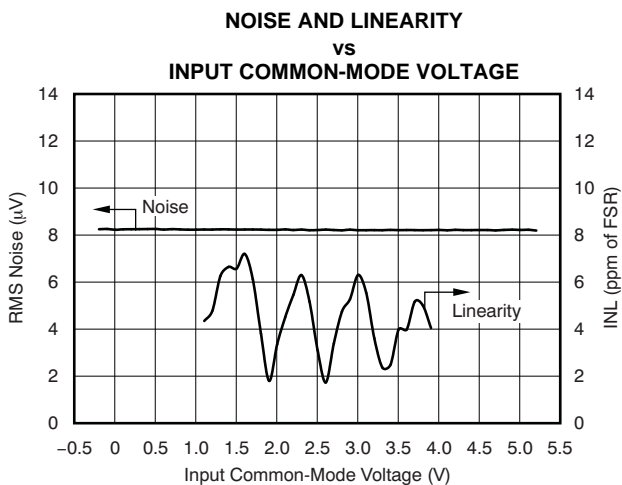


Figure 44.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{\text{CLK}} = 27\text{ MHz}$ ,  $V_{\text{REFP}} = 2.5\text{ V}$ , and  $V_{\text{REFN}} = 0\text{ V}$ , unless otherwise noted.

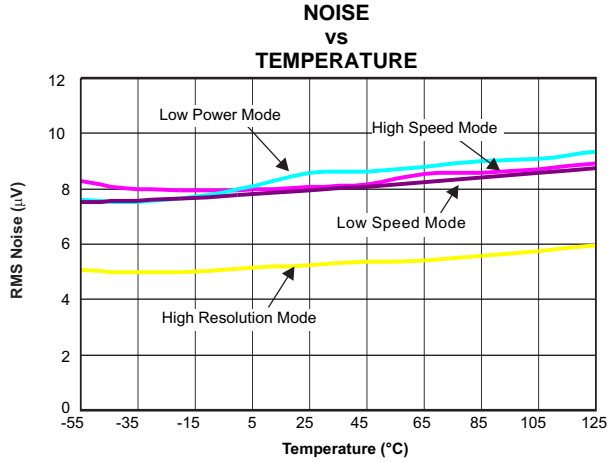


Figure 45.

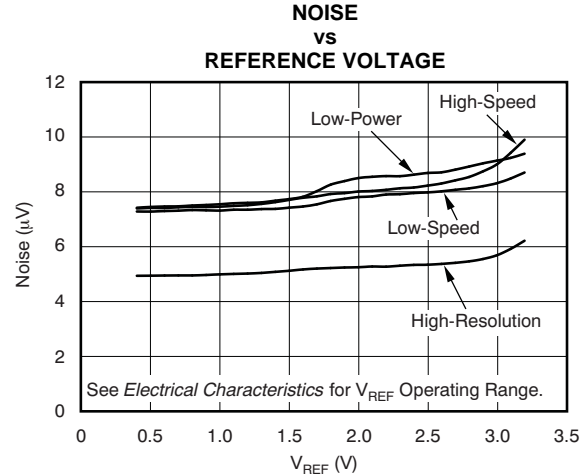


Figure 46.

**TOTAL HARMONIC DISTORTION AND NOISE vs CLK**

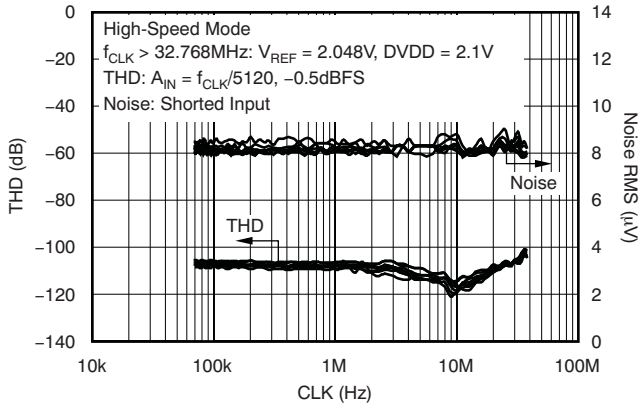


Figure 47.

**COMMON-MODE REJECTION vs INPUT FREQUENCY**

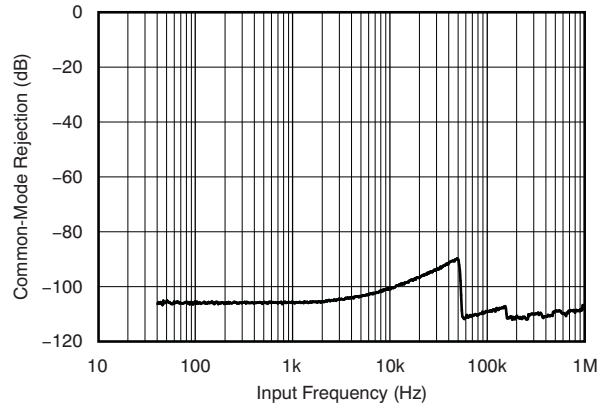


Figure 48.

**POWER-SUPPLY REJECTION vs POWER-SUPPLY FREQUENCY**

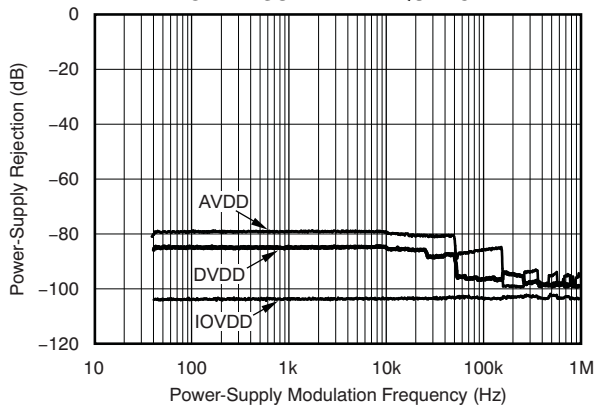


Figure 49.

**AVDD CURRENT vs TEMPERATURE**

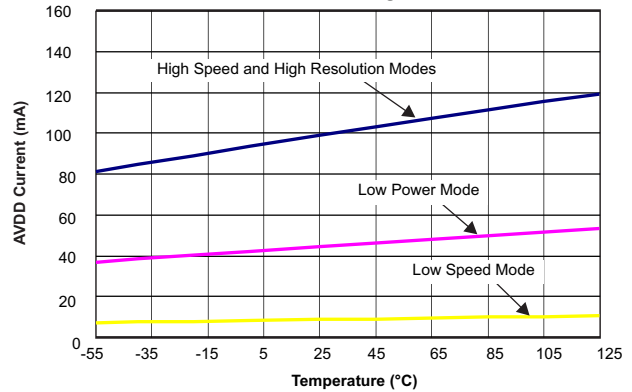


Figure 50.

**TYPICAL CHARACTERISTICS (continued)**

At  $T_A = 25^\circ\text{C}$ , High-Speed mode,  $AVDD = 5\text{ V}$ ,  $DVDD = 1.8\text{ V}$ ,  $IOVDD = 3.3\text{ V}$ ,  $f_{CLK} = 27\text{ MHz}$ ,  $VREFP = 2.5\text{ V}$ , and  $VREFN = 0\text{ V}$ , unless otherwise noted.

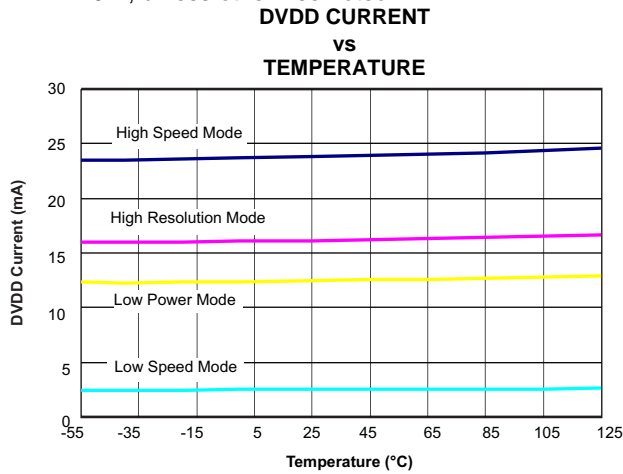


Figure 51.

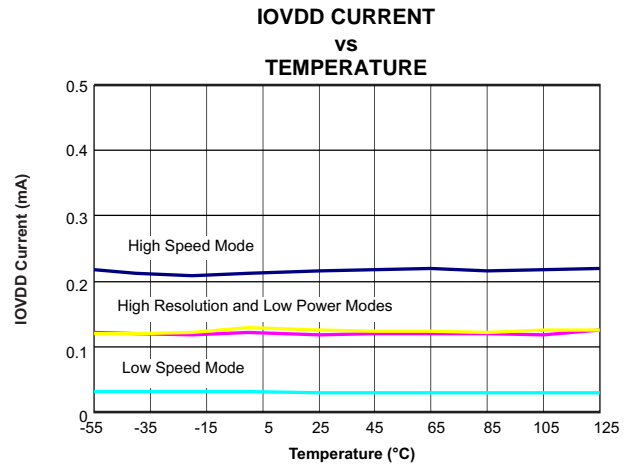


Figure 52.

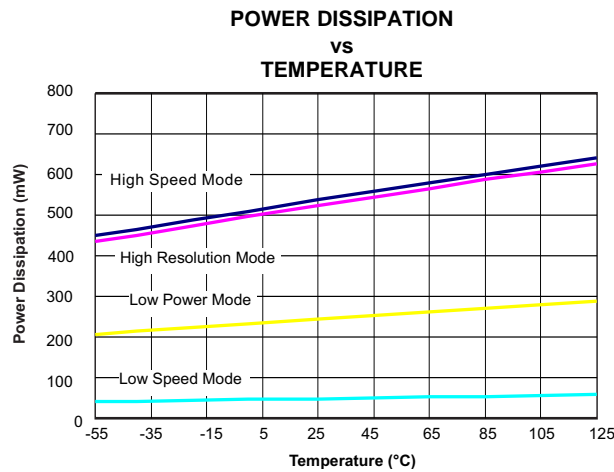


Figure 53.

### OVERVIEW

The ADS1278 is an octal 24-bit, delta-sigma ADC based on the single-channel ADS1271. It offers the combination of outstanding dc accuracy and superior ac performance. Figure 54 shows the block diagram. The converter is comprised of eight advanced, 6th-order, chopper-stabilized, delta-sigma modulators followed by low-ripple, linear phase FIR filters. The modulators measure the differential input signal,  $V_{IN} = (AINP - AINN)$ , against the differential reference,  $V_{REF} = (VREFP - VREFN)$ . The digital filters receive the modulator signal and provide a low-noise digital output. To allow tradeoffs among speed, resolution, and power, four operating modes are supported:

High-Speed, High-Resolution, Low-Power, and Low-Speed. Table 2 summarizes the performance of each mode.

In High-Speed mode, the maximum data rate is 128 kSPS (when operating at 128 kSPS, Frame-Sync format must be used). In High-Resolution mode, the SNR = 111dB ( $V_{REF} = 3.0\text{ V}$ ); in Low-Power mode, the power dissipation is 31 mW/channel; and in Low-Speed mode, the power dissipation is only 7 mW/channel at 10.5 kSPS. The digital filters can be bypassed, enabling direct access to the modulator output.

The ADS1278 is configured by simply setting the appropriate I/O pins—there are no registers to program. Data are retrieved over a serial interface that supports both SPI and Frame-Sync formats. The ADS1278 has a daisy-chainable output and the ability to synchronize externally, so it can be used conveniently in systems requiring more than eight channels.

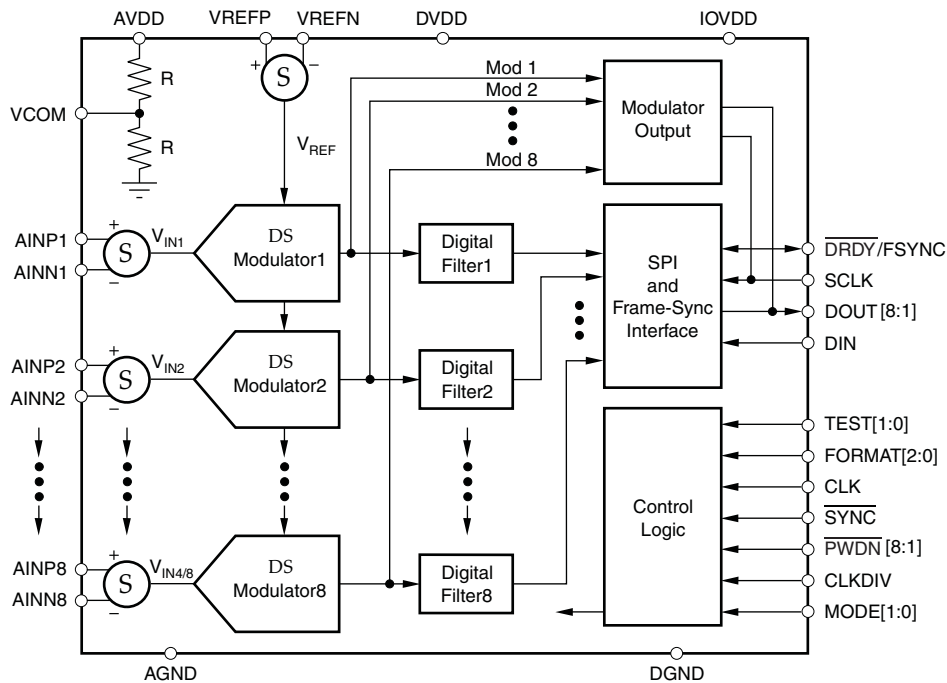


Figure 54. Block Diagram

Table 2. Operating Mode Performance Summary

MODE	MAX DATA RATE (SPS)	PASSBAND (kHz)	SNR (dB)	NOISE ( $\mu\text{V}_{\text{RMS}}$ )	POWER/CHANNEL (mW)
High-Speed	128,000	57,984	106	8.5	70
High-Resolution	52,734	23,889	110	5.5	64
Low-Power	52,734	23,889	106	8.5	31
Low-Speed	10,547	4,798	107	8.0	7

## FUNCTIONAL DESCRIPTION

The ADS1278 is a delta-sigma ADC consisting of eight independent converters that digitize eight input signals in parallel.

The converter is composed of two main functional blocks to perform the ADC conversions: the modulator and the digital filter. The modulator samples the input signal together with sampling the reference voltage to produce a 1s density output stream. The density of the output stream is proportional to the analog input level relative to the reference voltage. The pulse stream is filtered by the internal digital filter where the output conversion result is produced.

In operation, the input signal is sampled by the modulator at a high rate (typically 64x higher than the final output data rate). The quantization noise of the modulator is moved to a higher frequency range where the internal digital filter removes it. Oversampling results in very low levels of noise within the signal passband.

Since the input signal is sampled at a very high rate, input signal aliasing does not occur until the input signal frequency is at the modulator sampling rate. This architecture greatly relaxes the requirement of external antialiasing filters because of the high modulator sampling rate.

## SAMPLING APERTURE MATCHING

The ADS1278 converter operates from the same CLK input. The CLK input controls the timing of the modulator sampling instant. The converter is designed such that the sampling skew, or modulator sampling aperture match between channels, is controlled. Furthermore, the digital filters are synchronized to start the convolution phase at the same modulator clock cycle. This design results in excellent phase match among the ADS1278 channels.

[Figure 37](#) shows the inter-device channel sample matching for the ADS1278.

## FREQUENCY RESPONSE

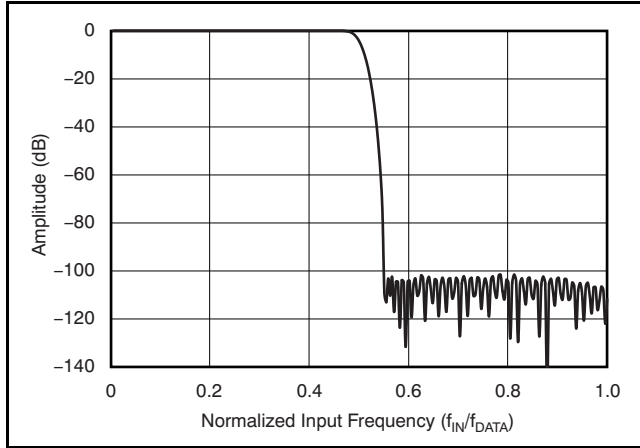
The digital filter sets the overall frequency response. The filter uses a multi-stage FIR topology to provide linear phase with minimal passband ripple and high stop band attenuation. The filter coefficients are identical to the coefficients used in the [ADS1271](#). The oversampling ratio of the digital filter (that is, the ratio of the modulator sampling to the output data rate, or  $f_{\text{MOD}}/f_{\text{DATA}}$ ) is a function of the selected mode, as shown in [Table 3](#).

**Table 3. Oversampling Ratio versus Mode**

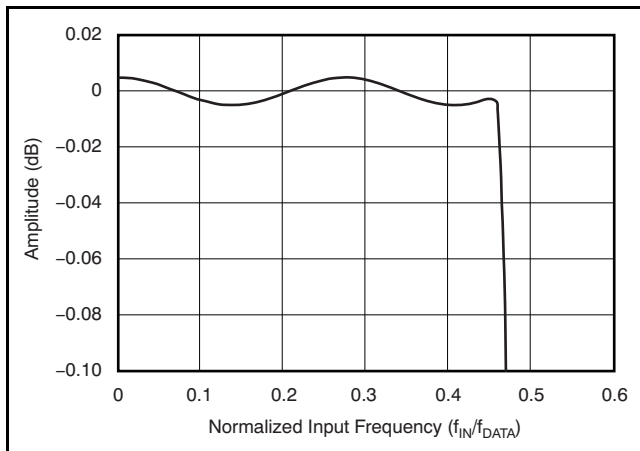
MODE SELECTION	OVERSAMPLING RATIO ( $f_{\text{MOD}}/f_{\text{DATA}}$ )
High-Speed	64
High-Resolution	128
Low-Power	64
Low-Speed	64

**High-Speed, Low-Power, and Low-Speed Modes**

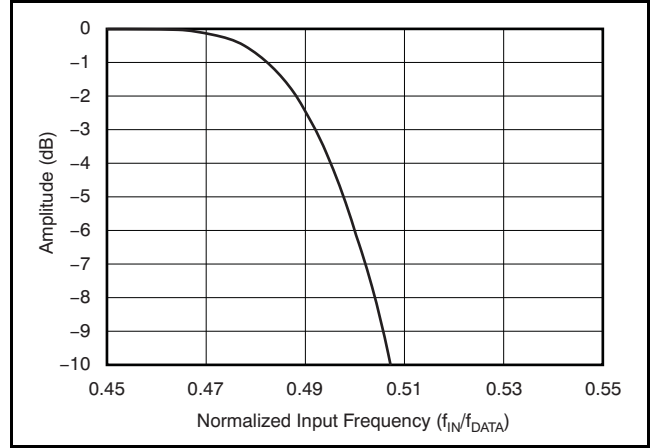
The digital filter configuration is the same in High-Speed, Low-Power, and Low-Speed modes with the oversampling ratio set to 64. Figure 55 shows the frequency response in High-Speed, Low-Power, and Low-Speed modes normalized to  $f_{DATA}$ . Figure 56 shows the passband ripple. The transition from passband to stop band is shown in Figure 57. The overall frequency response repeats at 64x multiples of the modulator frequency  $f_{MOD}$ , as shown in Figure 58.



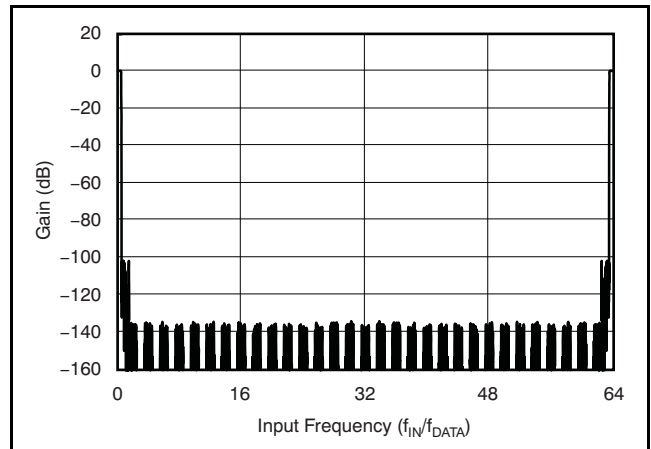
**Figure 55. Frequency Response for High-Speed, Low-Power, and Low-Speed Modes**



**Figure 56. Passband Response for High-Speed, Low-Power, and Low-Speed Modes**



**Figure 57. Transition Band Response for High-Speed, Low-Power, and Low-Speed Modes**



**Figure 58. Frequency Response Out to  $f_{MOD}$  for High-Speed, Low-Power, and Low-Speed Modes**

These image frequencies, if present in the signal and not externally filtered, will fold back (or alias) into the passband, causing errors. The stop band of the ADS1278 provides 100 dB attenuation of frequencies that begin just beyond the passband and continue out to  $f_{MOD}$ . Placing an antialiasing, low-pass filter in front of the ADS1278 inputs is recommended to limit possible high-amplitude, out-of-band signals and noise. Often, a simple RC filter is sufficient. Table 4 lists the image rejection versus external filter order.

**Table 4. Antialiasing Filter Order Image Rejection**

ANTIALIASING FILTER ORDER	IMAGE REJECTION (dB) ( $f_{-3dB}$ at $f_{DATA}$ )	
	HS, LP, LS	HR
1	39	45
2	75	87
3	111	129

### High-Resolution Mode

The oversampling ratio is 128 in High-Resolution mode. Figure 59 shows the frequency response in High-Resolution mode normalized to  $f_{DATA}$ . Figure 60 shows the passband ripple, and the transition from passband to stop band is shown in Figure 61. The overall frequency response repeats at multiples of the modulator frequency  $f_{MOD}$  ( $128 \times f_{DATA}$ ), as shown in Figure 62. The stop band of the ADS1278 provides 100 dB attenuation of frequencies that begin just beyond the passband and continue out to  $f_{MOD}$ . Placing an antialiasing, low-pass filter in front of the ADS1278 inputs is recommended to limit possible high-amplitude out-of-band signals and noise. Often, a simple RC filter is sufficient. Table 4 lists the image rejection versus external filter order.

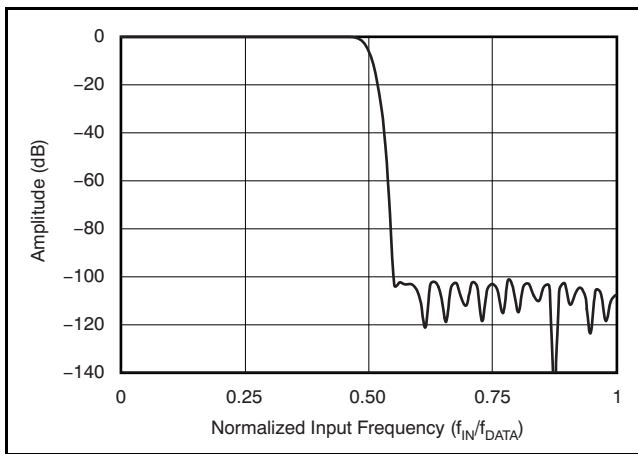


Figure 59. Frequency Response for High-Resolution Mode

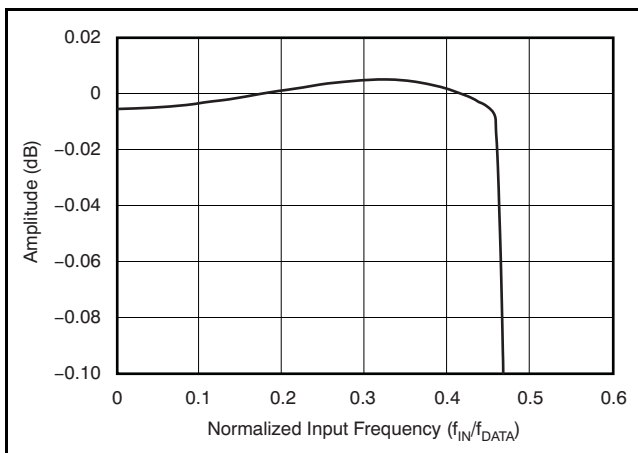


Figure 60. Passband Response for High-Resolution Mode

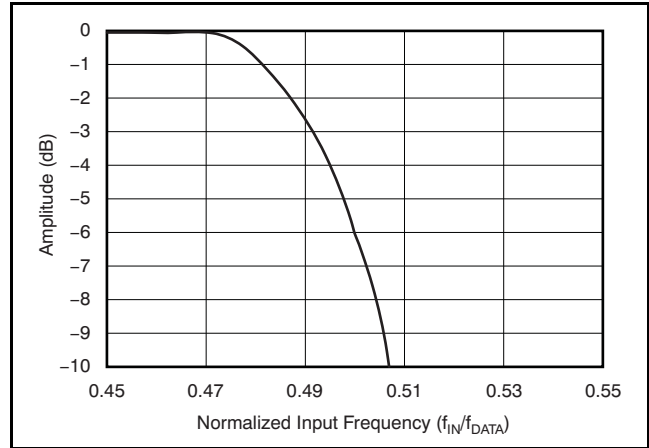


Figure 61. Transition Band Response for High-Resolution mode

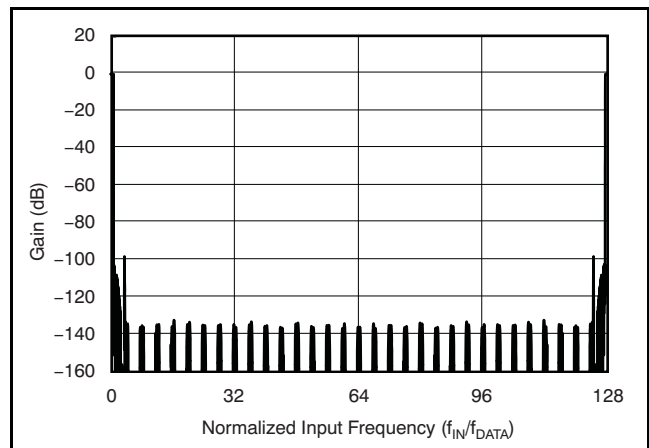


Figure 62. Frequency Response Out to  $f_{MOD}$  for High-Resolution Mode

## PHASE RESPONSE

The ADS1278 incorporates a multiple stage, linear phase digital filter. Linear phase filters exhibit constant delay time versus input frequency (constant group delay). This characteristic means the time delay from any instant of the input signal to the same instant of the output data is constant and is independent of input signal frequency. This behavior results in essentially zero phase errors when analyzing multi-tone signals.

## SETTLING TIME

As with frequency and phase response, the digital filter also determines settling time. Figure 63 shows the output settling behavior after a step change on the analog inputs normalized to conversion periods. The X-axis is given in units of conversion. Note that after the step change on the input occurs, the output data change very little prior to 30 conversion periods. The output data are fully settled after 76 conversion periods for High-Speed and Low-Power modes, and 78 conversion periods for High-Resolution mode.

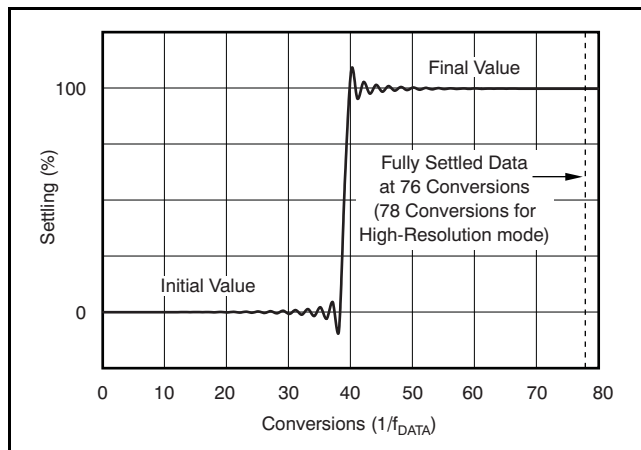


Figure 63. Step Response

## DATA FORMAT

The ADS1278 outputs 24 bits of data in twos complement format.

A positive full-scale input produces an ideal output code of 7FFFFFFh, and the negative full-scale input produces an ideal output code of 800000h. The output clips at these codes for signals exceeding full-scale. Table 5 summarizes the ideal output codes for different input signals.

Table 5. Ideal Output Code versus Input Signal

INPUT SIGNAL $V_{IN}$ ( $A_{INP} - A_{INN}$ )	IDEAL OUTPUT CODE <sup>(1)</sup>
$\geq +V_{REF}$	7FFFFFFh
$\frac{+V_{REF}}{2^{23} - 1}$	000001h
0	000000h
$\frac{-V_{REF}}{2^{23} - 1}$	FFFFFFh
$\leq -V_{REF} \left( \frac{2^{23}}{2^{23} - 1} \right)$	800000h

(1) Excludes effects of noise, INL, offset, and gain errors.

## ANALOG INPUTS (A<sub>INP</sub>, A<sub>INN</sub>)

The ADS1278 measures each differential input signal  $V_{IN} = (A_{INP} - A_{INN})$  against the common differential reference  $V_{REF} = (V_{REFP} - V_{REFN})$ . The most positive measurable differential input is  $+V_{REF}$ , which produces the most positive digital output code of 7FFFFFFh. Likewise, the most negative measurable differential input is  $-V_{REF}$ , which produces the most negative digital output code of 800000h.

For optimum performance, the inputs of the ADS1278 are intended to be driven differentially. For single-ended applications, one of the inputs (A<sub>INP</sub> or A<sub>INN</sub>) can be driven while the other input is fixed (typically to AGND or 2.5 V). Fixing the input to 2.5 V permits bipolar operation, thereby allowing full use of the entire converter range.

While the ADS1278 measures the differential input signal, the absolute input voltage is also important. This value is the voltage on either input (A<sub>INP</sub> or A<sub>INN</sub>) with respect to AGND. The range for this voltage is:

$$-0.1 \text{ V} < (A_{INN} \text{ or } A_{INP}) < AVDD + 0.1 \text{ V}$$

If either input is taken below  $-0.4 \text{ V}$  or above  $(AVDD + 0.4 \text{ V})$ , ESD protection diodes on the inputs may turn on. If these conditions are possible, external Schottky clamp diodes or series resistors may be required to limit the input current to safe values (see the [Absolute Maximum Ratings](#) table).

The ADS1278 is a very high-performance ADC. For optimum performance, it is critical that the appropriate circuitry be used to drive the ADS1278 inputs. See the [Application Information](#) section for several recommended circuits.



The ADS1278 uses switched-capacitor circuitry to measure the input voltage. Internal capacitors are charged by the inputs and then discharged. Figure 64 shows a conceptual diagram of these circuits. Switch  $S_2$  represents the net effect of the modulator circuitry in discharging the sampling capacitor; the actual implementation is different. The timing for switches  $S_1$  and  $S_2$  is shown in Figure 65. The sampling time ( $t_{SAMPLE}$ ) is the inverse of modulator sampling frequency ( $f_{MOD}$ ) and is a function of the mode, the CLKDIV input, and CLK frequency, as shown in Table 6.

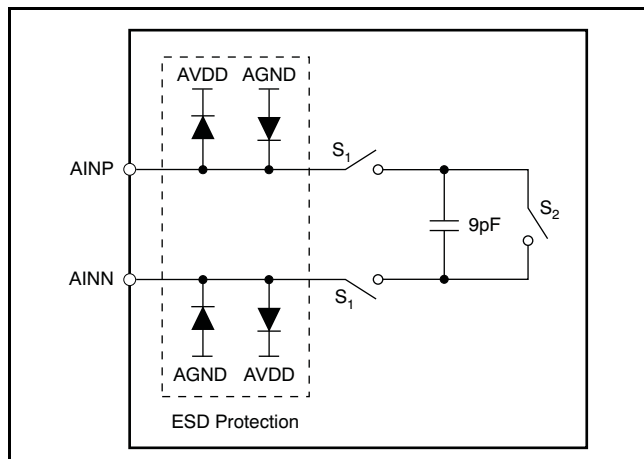


Figure 64. Equivalent Analog Input Circuitry

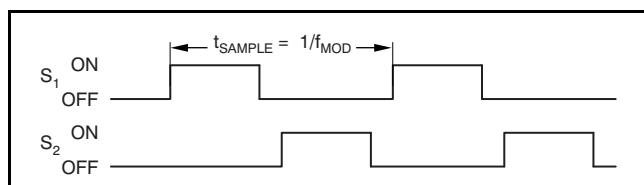


Figure 65.  $S_1$  and  $S_2$  Switch Timing for Figure 64

Table 6. Modulator Frequency ( $f_{MOD}$ ) Mode Selection

MODE SELECTION	CLKDIV	$f_{MOD}$
High-Speed	1	$f_{CLK}/4$
High-Resolution	1	$f_{CLK}/4$
Low-Power	1	$f_{CLK}/8$
	0	$f_{CLK}/4$
Low-Speed	1	$f_{CLK}/40$
	0	$f_{CLK}/8$

The average load presented by the switched capacitor input can be modeled with an effective differential impedance, as shown in Figure 66. Note that the effective impedance is a function of  $f_{MOD}$ .

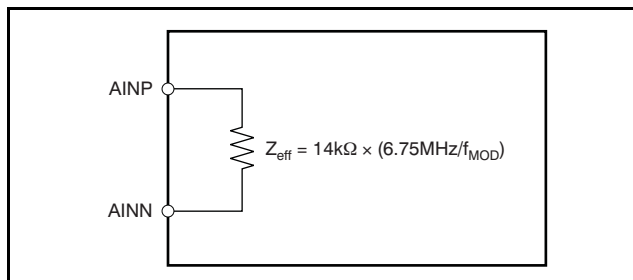


Figure 66. Effective Input Impedances

### VOLTAGE REFERENCE INPUTS (VREFP, VREFN)

The voltage reference for the ADS1278 ADC is the differential voltage between VREFP and VREFN:  $V_{REF} = (VREFP - VREFN)$ . The voltage reference is common to all channels. The reference inputs use a structure similar to that of the analog inputs with the equivalent circuitry on the reference inputs shown in Figure 67. As with the analog inputs, the load presented by the switched capacitor can be modeled with an effective impedance, as shown in Figure 68. However, the reference input impedance depends on the number of active (enabled) channels in addition to  $f_{MOD}$ . As a result of the change of reference input impedance caused by enabling and disabling channels, the regulation and setting time of the external reference should be noted, so as not to affect the readings.

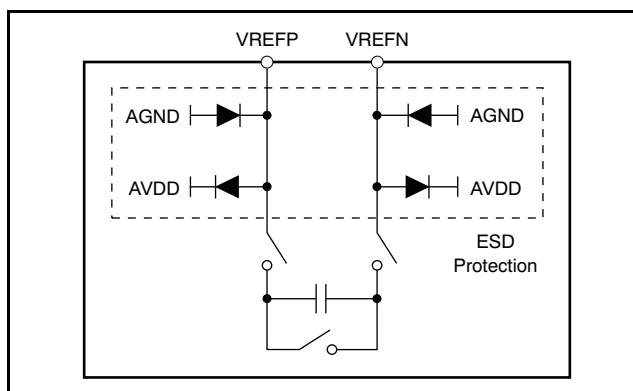


Figure 67. Equivalent Reference Input Circuitry

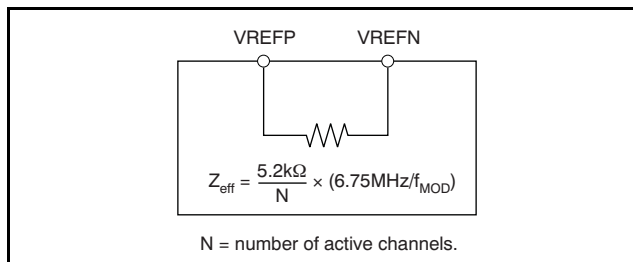


Figure 68. Effective Reference Impedance

ESD diodes protect the reference inputs. To keep these diodes from turning on, make sure the voltages on the reference pins do not go below AGND by more than 0.4 V, and likewise do not exceed AVDD by 0.4 V. If these conditions are possible, external Schottky clamp diodes or series resistors may be required to limit the input current to safe values (see the [Absolute Maximum Ratings](#) table).

Note that the valid operating range of the reference inputs is limited to the following parameters:

$$-0.1 \text{ V} \leq \text{VREFN} \leq +0.1 \text{ V}$$

$$\text{VREFN} + 0.5 \text{ V} \leq \text{VREFP} \leq \text{AVDD} + 0.1 \text{ V}$$

### CLOCK INPUT (CLK)

The ADS1278 requires a clock input for operation. The individual converters of the ADS1278 operate from the same clock input. At the maximum data rate, the clock input can be either 27 MHz or 13.5 MHz for Low-Power mode, or 27 MHz or 5.4 MHz for Low-Speed mode, determined by the setting of the CLKDIV input. For High-Speed mode, the maximum CLK input frequency is 32.768 MHz. For High-Resolution mode, the maximum CLK input frequency is 27 MHz. The selection of the external clock frequency ( $f_{\text{CLK}}$ ) does not affect the resolution of the ADS1278. Use of a slower  $f_{\text{CLK}}$  can reduce the power consumption of an external clock buffer. The output data rate scales with clock frequency, down to a minimum clock frequency of  $f_{\text{CLK}} = 100 \text{ kHz}$ . [Table 7](#) summarizes the ratio of the clock input frequency ( $f_{\text{CLK}}$ ) to data rate ( $f_{\text{DATA}}$ ), maximum data rate and corresponding maximum clock input for the four operating modes.

As with any high-speed data converter, a high-quality, low-jitter clock is essential for optimum performance. Crystal clock oscillators are the recommended clock source. Make sure to avoid excess ringing on the clock input; keeping the clock trace as short as possible, and using a 50- $\Omega$  series resistor placed close to the source end, often helps.

**Table 7. Clock Input Options**

MODE SELECTION	MAX $f_{\text{CLK}}$ (MHz)	CLKDIV	$f_{\text{CLK}}/f_{\text{DATA}}$	DATA RATE (SPS)
High-Speed	32.768	1	256	128,000
High-Resolution	27	1	512	52,734
Low-Power	27	1	512	52,734
	13.5	0	256	
Low-Speed	27	1	2,560	10,547
	5.4	0	512	

### MODE SELECTION (MODE)

The ADS1278 supports four modes of operation: High-Speed, High-Resolution, Low-Power, and Low-Speed. The modes offer optimization of speed, resolution, and power. Mode selection is determined by the status of the digital input MODE[1:0] pins, as shown in [Table 8](#). The ADS1278 continually monitors the status of the MODE pin during operation.

**Table 8. Mode Selection**

MODE[1:0]	MODE SELECTION	MAX $f_{\text{DATA}}$ <sup>(1)</sup>
00	High-Speed	128,000
01	High-Resolution	52,734
10	Low-Power	52,734
11	Low-Speed	10,547

(1)  $f_{\text{CLK}} = 27 \text{ MHz}$  max (32.768MHz max in High-Speed mode).

When using the SPI protocol,  $\overline{\text{DRDY}}$  is held high after a mode change occurs until settled (or valid) data are ready; see [Figure 69](#) and [Table 9](#).

In Frame-Sync protocol, the DOUT pins are held low after a mode change occurs until settled data are ready; see [Figure 69](#) and [Table 9](#). Data can be read from the device to detect when DOUT changes to logic 1, indicating that the data are valid.

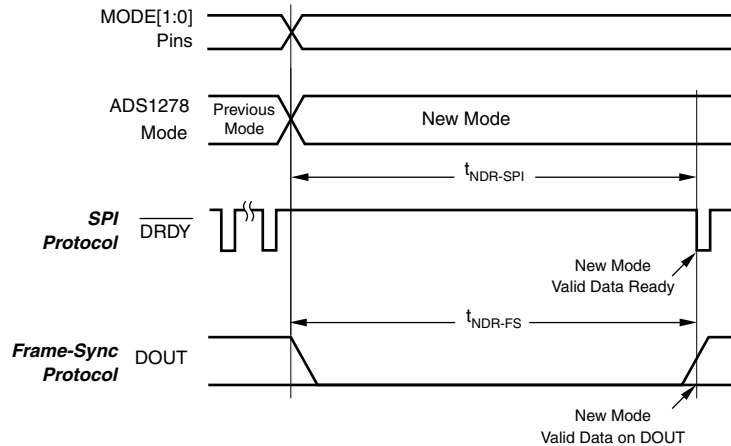


Figure 69. Mode Change Timing

Table 9. New Data After Mode Change

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{\text{NDR-SPI}}$	Time for new data to be ready (SPI)			129	Conversions ( $1/f_{\text{DATA}}$ )
$t_{\text{NDR-FS}}$	Time for new data to be ready (Frame-Sync)	127		128	Conversions ( $1/f_{\text{DATA}}$ )

## SYNCHRONIZATION ( $\overline{\text{SYNC}}$ )

The ADS1278 can be synchronized by pulsing the  $\overline{\text{SYNC}}$  pin low and then returning the pin high. When the pin goes low, the conversion process stops, and the internal counters used by the digital filter are reset. When the  $\overline{\text{SYNC}}$  pin returns high, the conversion process restarts. Synchronization allows the conversion to be aligned with an external event, such as the changing of an external multiplexer on the analog inputs, or by a reference timing pulse.

Because the ADS1278 converters operate in parallel from the same master clock and use the same  $\overline{\text{SYNC}}$  input control, they are always in synchronization with each other. The aperture match among internal channels is typically less than 500 ps. However, the synchronization of multiple devices is somewhat different. At device power-on, variations in internal reset thresholds from device to device may result in uncertainty in conversion timing.

The  $\overline{\text{SYNC}}$  pin can be used to synchronize multiple devices to within the same CLK cycle. Figure 70 illustrates the timing requirement of  $\overline{\text{SYNC}}$  and CLK in SPI format.

See Figure 71 for the Frame-Sync format timing requirement.

After synchronization, indication of valid data depends on whether SPI or Frame-Sync format was used.

In the SPI format,  $\overline{\text{DRDY}}$  goes high as soon as  $\overline{\text{SYNC}}$  is taken low; see Figure 70. After  $\overline{\text{SYNC}}$  is returned high,  $\overline{\text{DRDY}}$  stays high while the digital filter is settling. Once valid data are ready for retrieval,  $\overline{\text{DRDY}}$  goes low.

In the Frame-Sync format, DOUT goes low as soon as  $\overline{\text{SYNC}}$  is taken low; see Figure 71. After  $\overline{\text{SYNC}}$  is returned high, DOUT stays low while the digital filter is settling. Once valid data are ready for retrieval, DOUT begins to output valid data. For proper synchronization, FSYNC, SCLK, and CLK must be established before taking  $\overline{\text{SYNC}}$  high, and must then remain running. If the clock inputs (CLK, FSYNC or SCLK) are subsequently interrupted or reset, re-assert the  $\overline{\text{SYNC}}$  pin.

For consistent performance, re-assert  $\overline{\text{SYNC}}$  after device power-on when data first appear.

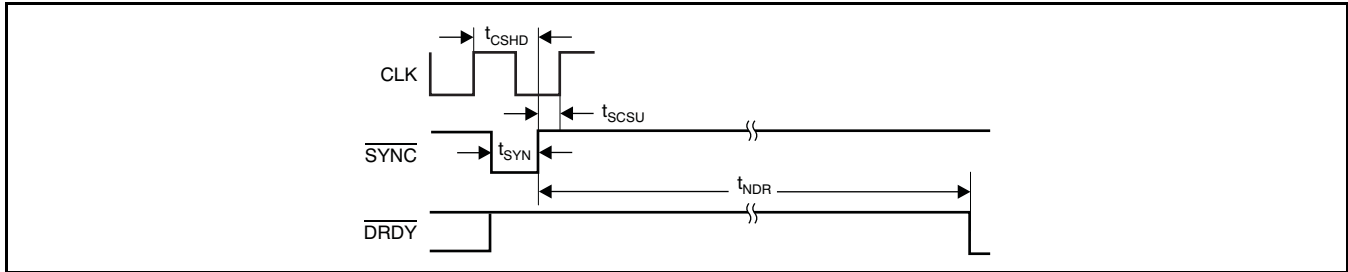


Figure 70. Synchronization Timing (SPI Protocol)

Table 10. SPI Protocol

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{CSHD}$	CLK to $\overline{SYNC}$ hold time	10			ns
$t_{SCSU}$	$\overline{SYNC}$ to CLK setup time	5			ns
$t_{SYN}$	Synchronize pulse width	1			CLK periods
$t_{NDR}$	Time for new data to be ready			129	Conversions ( $1/f_{DATA}$ )

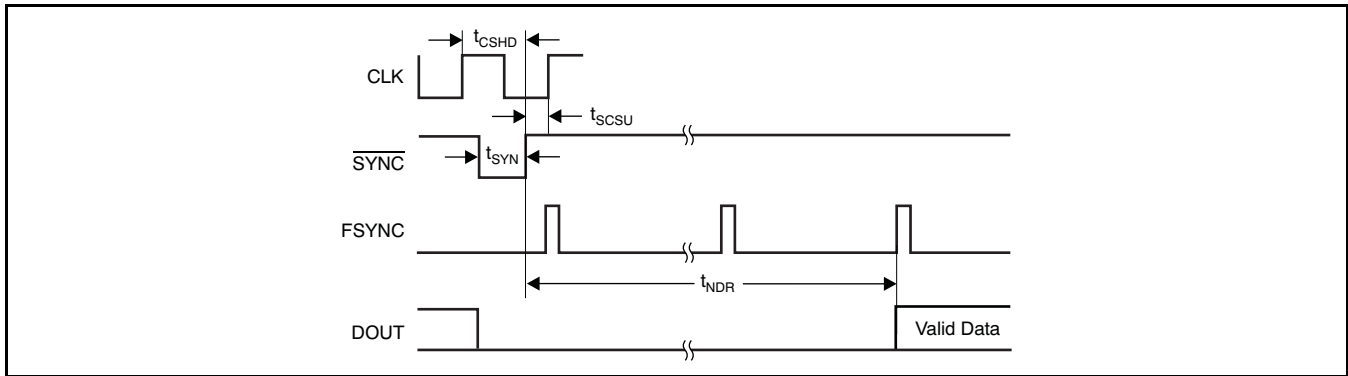


Figure 71. Synchronization Timing (Frame-Sync Protocol)

Table 11. Frame-Sync Protocol

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{CSHD}$	CLK to $\overline{SYNC}$ hold time	10			ns
$t_{SCSU}$	$\overline{SYNC}$ to CLK setup time	5			ns
$t_{SYN}$	Synchronize pulse width	1			CLK periods
$t_{NDR}$	Time for new data to be ready	127		128	Conversions ( $1/f_{DATA}$ )

## POWER-DOWN (P $\overline{\text{WDN}}$ )

The channels of the ADS1278 can be independently powered down by use of the P $\overline{\text{WDN}}$  inputs. To enter the power-down mode, hold the respective P $\overline{\text{WDN}}$  pin low for at least two CLK cycles. To exit power-down, return the corresponding P $\overline{\text{WDN}}$  pin high. Note that when all channels are powered down, the ADS1278 enters a microwatt ( $\mu\text{W}$ ) power state where all internal biasing is disabled. In this state, the TEST[1:0] input pins must be driven; all other input pins can float. The ADS1278 outputs remain driven.

As shown in Figure 72 and Table 12, a maximum of 130 conversion cycles must elapse for SPI interface, and 129 conversion cycles must elapse for Frame-Sync, before reading data after exiting power-down. Data from channels already running are not affected. The user software can perform the required delay time in any of the following ways:

1. Count the number of data conversions after taking the P $\overline{\text{WDN}}$  pin high.
2. Delay  $129/f_{\text{DATA}}$  or  $130/f_{\text{DATA}}$  after taking the P $\overline{\text{WDN}}$  pins high, then read data.
3. Detect for non-zero data in the powered-up channel.

After powering up one or more channels, the channels are synchronized to each other. It is not necessary to use the SYNC pin to synchronize them.

When a channel is powered down in TDM data format, the data for that channel are either forced to zero (fixed-position TDM data mode) or replaced by shifting the data from the next channel into the vacated data position (dynamic-position TDM data mode).

In Discrete data format, the data are always forced to zero. When powering-up a channel in dynamic-position TDM data format mode, the channel data remain packed until the data are ready, at which time the data frame is expanded to include the just-powered channel data. See the *Data Format* section for details.

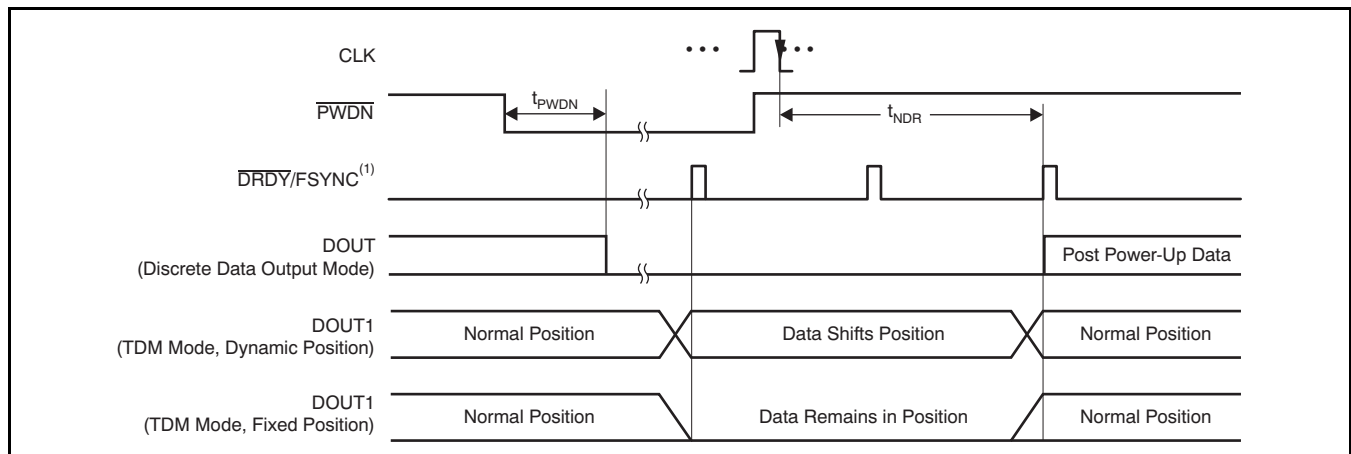


Figure 72. Power-Down Timing

Table 12. Power-Down Timing

SYMBOL	DESCRIPTION	MIN	TYP	MAX	UNITS
$t_{\text{P\overline{\text{WDN}}}$	P $\overline{\text{WDN}}$ pulse width to enter Power-Down mode	2			CLK periods
$t_{\text{NDR}}$	Time for new data ready (SPI)	129		130	Conversions ( $1/f_{\text{DATA}}$ )
$t_{\text{NDR}}$	Time for new data ready (Frame-Sync)	128		129	Conversions ( $1/f_{\text{DATA}}$ )

## FORMAT[2:0]

Data can be read from the ADS1278 with two interface protocols (SPI or Frame-Sync) and several options of data formats (TDM/Discrete and Fixed/Dynamic data positions). The FORMAT[2:0] inputs are used to select among the options. Table 13 lists the available options. See the *DOUT Modes* section for details of the DOUT Mode and Data Position.

**Table 13. Data Output Format**

FORMAT[2:0]	INTERFACE PROTOCOL	DOUT MODE	DATA POSITION
000	SPI	TDM	Dynamic
001	SPI	TDM	Fixed
010	SPI	Discrete	—
011	Frame-Sync	TDM	Dynamic
100	Frame-Sync	TDM	Fixed
101	Frame-Sync	Discrete	—
110	Modulator Mode	—	—

## SERIAL INTERFACE PROTOCOLS

Data are retrieved from the ADS1278 using the serial interface. Two protocols are available: SPI and Frame-Sync. The same pins are used for both interfaces: SCLK, DRDY/FSYNC, DOUT[8:1], and DIN. The FORMAT[2:0] pins select the desired interface protocol.

### SPI SERIAL INTERFACE

The SPI-compatible format is a read-only interface. Data ready for retrieval are indicated by the falling DRDY output and are shifted out on the falling edge of SCLK, MSB first. The interface can be daisy-chained using the DIN input when using multiple devices. See the *Daisy-Chaining* section for more information.

NOTE: The SPI format is limited to a CLK input frequency of 27 MHz, maximum. For CLK input operation above 27 MHz (High-Speed mode only), use Frame-Sync format.

### SCLK

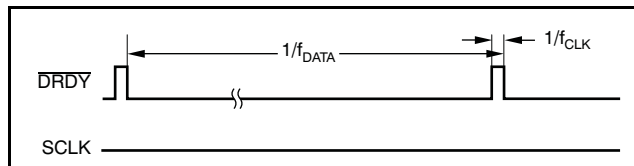
The serial clock (SCLK) features a Schmitt-triggered input and shifts out data on DOUT on the falling edge. It also shifts in data on the falling edge on DIN when this pin is being used for daisy-chaining. The device shifts data out on the falling edge and the user normally shifts this data in on the rising edge.

Even though the SCLK input has hysteresis, it is recommended to keep SCLK as clean as possible to prevent glitches from accidentally shifting the data.

SCLK may be run as fast as the CLK frequency. SCLK may be either in free-running or stop-clock operation between conversions. Note that one  $f_{CLK}$  is required after the falling edge of  $\overline{DRDY}$  until the first rising edge of SCLK. For best performance, limit  $f_{SCLK}/f_{CLK}$  to ratios of 1, 1/2, 1/4, 1/8, etc. When the device is configured for modulator output, SCLK becomes the modulator clock output (see the *Modulator Output* section).

### $\overline{DRDY}$ /FSYNC (SPI Format)

In the SPI format, this pin functions as the  $\overline{DRDY}$  output. It goes low when data are ready for retrieval and then returns high on the falling edge of the first subsequent SCLK. If data are not retrieved (that is, SCLK is held low),  $\overline{DRDY}$  pulses high just before the next conversion data are ready, as shown in Figure 73. The new data are loaded within one CLK cycle before  $\overline{DRDY}$  goes low. All data must be shifted out before this time to avoid being overwritten.



**Figure 73.  $\overline{DRDY}$  Timing with No Readback**

### DOUT

The conversion data are output on DOUT[8:1]. The MSB data are valid on DOUT[8:1] after  $\overline{DRDY}$  goes low. Subsequent bits are shifted out with each falling edge of SCLK. If daisy-chaining, the data shifted in using DIN appear on DOUT after all channel data have been shifted out. When the device is configured for modulator output, DOUT[8:1] becomes the modulator data output for each channel (see the *Modulator Output* section).

### DIN

This input is used when multiple ADS1278s are to be daisy-chained together. The DOUT1 pin of the first device connects to the DIN pin of the next, etc. It can be used with either the SPI or Frame-Sync formats. Data are shifted in on the falling edge of SCLK. When using only one ADS1278, tie DIN low. See the *Daisy-Chaining* section for more information.



## FRAME-SYNC SERIAL INTERFACE

Frame-Sync format is similar to the interface often used on audio ADCs. It operates in slave fashion—the user must supply framing signal FSYNC (similar to the *left/right clock* on stereo audio ADCs) and the serial clock SCLK (similar to the *bit clock* on audio ADCs). The data are output MSB first or *left-justified* on the rising edge of FSYNC. When using Frame-Sync format, the FSYNC and SCLK inputs must be continuously running with the relationships shown in the [Frame-Sync Timing Requirements](#).

### SCLK

The serial clock (SCLK) features a Schmitt-triggered input and shifts out data on DOUT on the falling edge. It also shifts in data on the falling edge on DIN when this pin is being used for daisy-chaining. Even though SCLK has hysteresis, it is recommended to keep SCLK as clean as possible to prevent glitches from accidentally shifting the data. When using Frame-Sync format, SCLK must run continuously. If it is shut down, the data readback will be corrupted. The number of SCLKs within a frame period (FSYNC clock) can be any power-of-2 ratio of CLK cycles (1, 1/2, 1/4, etc), as long as the number of cycles is sufficient to shift the data output from all channels within one frame. When the device is configured for modulator output, SCLK becomes the modulator clock output (see the [Modulator Output](#) section).

### DRDY/FSYNC (Frame-Sync Format)

In Frame-Sync format, this pin is used as the FSYNC input. The frame-sync input (FSYNC) sets the frame period, which must be the same as the data rate. The required number of  $f_{CLK}$  cycles to each FSYNC period depends on the mode selection and the CLKDIV input. [Table 7](#) indicates the number of CLK cycles to each frame ( $f_{CLK}/f_{DATA}$ ). If the FSYNC period is not the proper value, data readback will be corrupted.

### DOUT

The conversion data are shifted out on DOUT[8:1]. The MSB data become valid on DOUT[8:1] after FSYNC goes high. The subsequent bits are shifted out with each falling edge of SCLK. If daisy-chaining, the data shifted in using DIN appear on DOUT[8:1] after all channel data have been shifted out. When the device is configured for modulator output, DOUT becomes the modulator data output (see the [Modulator Output](#) section).

### DIN

This input is used when multiple ADS1278s are to be daisy-chained together. It can be used with either SPI or Frame-Sync formats. Data are shifted in on the falling edge of SCLK. When using only one ADS1278, tie DIN low. See the [Daisy-Chaining](#) section for more information.

### DOUT MODES

For both SPI and Frame-Sync interface protocols, the data are shifted out either through individual channel DOUT pins, in a parallel data format (Discrete mode), or the data for all channels are shifted out, in a serial format, through a common pin, DOUT1 (TDM mode).

#### TDM Mode

In TDM (time-division multiplexed) data output mode, the data for all channels are shifted out, in sequence, on a single pin (DOUT1). As shown in [Figure 74](#), the data from channel 1 are shifted out first, followed by channel 2 data, etc. After the data from the last channel are shifted out, the data from the DIN input follow. The DIN is used to daisy-chain the data output from an additional ADS1278 or other compatible device. Note that when all channels of the ADS1278 are disabled, the interface is disabled, rendering the DIN input disabled as well. When one or more channels of the device are powered down, the data format of the TDM mode can be fixed or dynamic.

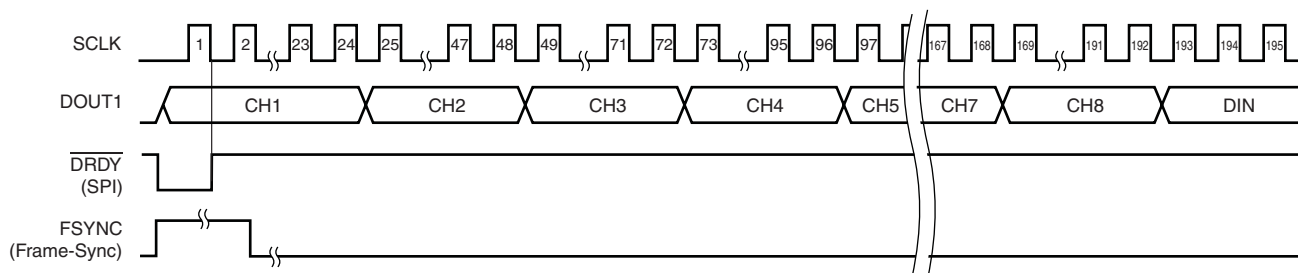


Figure 74. TDM Mode (All Channels Enabled)

**TDM Mode, Fixed-Position Data**

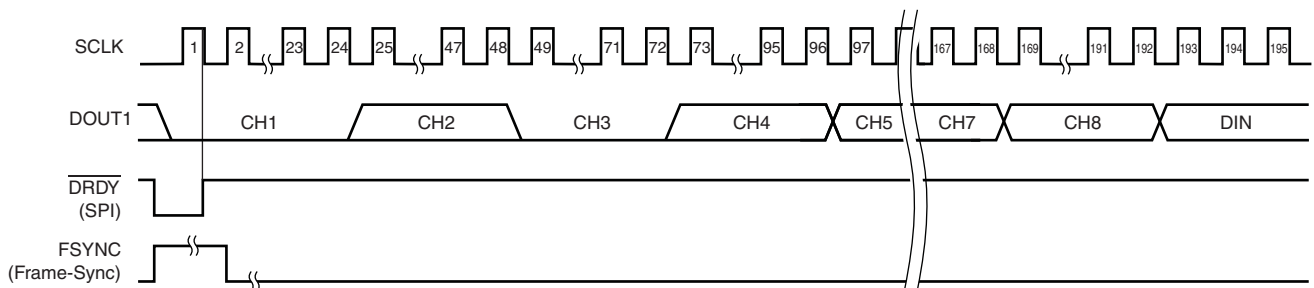
In this TDM data output mode, the data position of the channels remain fixed, regardless of whether the channels are powered down. If a channel is powered down, the data are forced to zero but occupy the same position within the data stream. [Figure 75](#) shows the data stream with channel 1 and channel 3 powered down.

**TDM Mode, Dynamic Position Data**

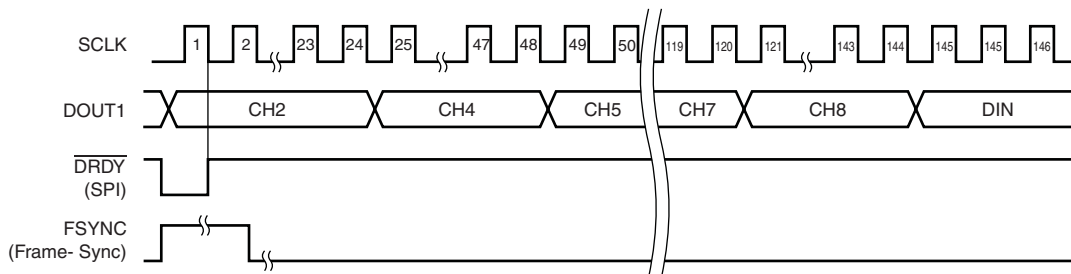
In this TDM data output mode, when a channel is powered down, the data from higher channels shift one position in the data stream to fill the vacated data slot. [Figure 76](#) shows the data stream with channel 1 and channel 3 powered down.

**Discrete Data Output Mode**

In Discrete data output mode, the channel data are shifted out in parallel using individual channel data output pins DOUT[8:1]. After the 24th SCLK, the channel data are forced to zero. The data are also forced to zero for powered down channels. [Figure 77](#) shows the discrete data output format.



**Figure 75. TDM Mode, Fixed-Position Data (Channels 1 and 3 Shown Powered Down)**



**Figure 76. TDM Mode, Dynamic Position Data (Channels 1 and 3 Shown Powered Down)**



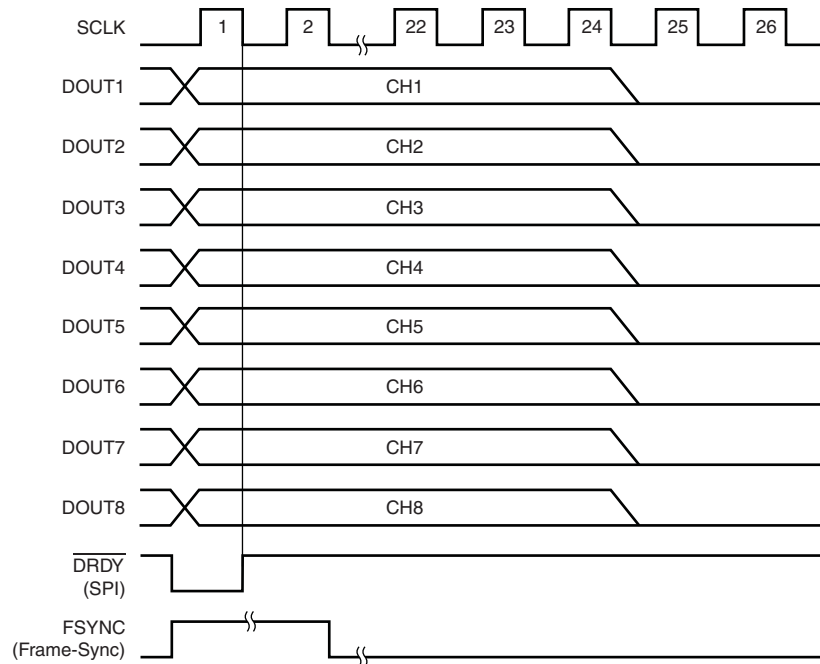


Figure 77. Discrete Data Output Mode

## DAISY-CHAINING

Multiple ADS1278s can be daisy-chained together to output data on a single pin. The DOUT1 data output pin of one device is connected to the DIN of the next device. As shown in Figure 78, the DOUT1 pin of device 1 provides the output data to a controller, and the DIN of device 2 is grounded. Figure 79 shows the data format when reading back data.

The maximum number of channels that may be daisy-chained in this way is limited by the frequency of  $f_{SCLK}$ , the mode selection, and the CLKDIV input. The frequency of  $f_{SCLK}$  must be high enough to completely shift the data out from all channels within one  $f_{DATA}$  period. Table 14 lists the maximum number of daisy-chained channels when  $f_{SCLK} = f_{CLK}$ .

To increase the number of data channels possible in a chain, a segmented DOUT scheme may be used, producing two data streams. Figure 80 illustrates four ADS1278s, with pairs of ADS1278s daisy-chained together. The channel data of each daisy-chained pair are shifted out in parallel and received by the processor through independent data channels.

Table 14. Maximum Channels in a Daisy-Chain

Table 14. Maximum Channels in a Daisy-Chain ( $f_{SCLK} = f_{CLK}$ ) (continued)

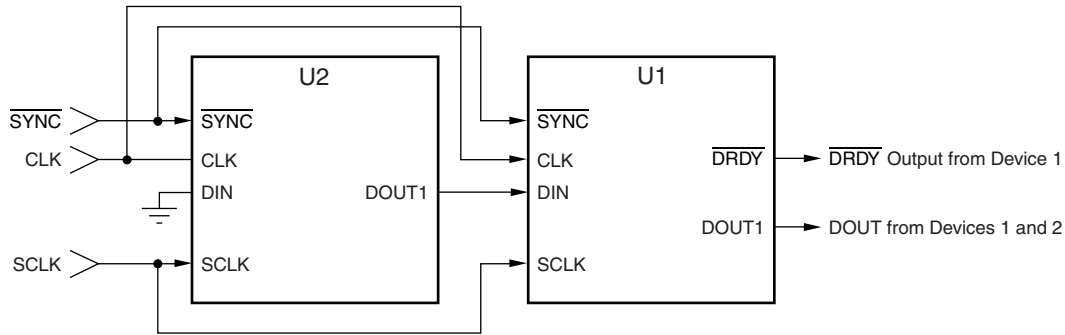
( $f_{SCLK} = f_{CLK}$ )

MODE SELECTION	CLKDIV	MAXIMUM NUMBER OF CHANNELS
High-Speed	1	10
High-Resolution	1	21
Low-Power	1	21
	0	10
Low-Speed	1	106
	0	21

Whether the interface protocol is SPI or Frame-Sync, it is recommended to synchronize all devices by tying the SYNC inputs together. When synchronized in SPI protocol, it is only necessary to monitor the DRDY output of one ADS1278.

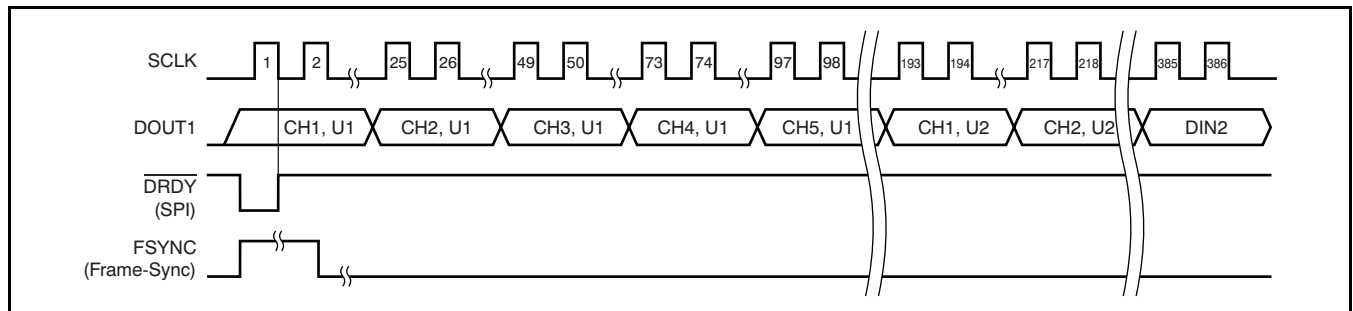
In Frame-Sync interface protocol, the data from all devices are ready after the rising edge of FSYNC.

Since DOUT1 and DIN are both shifted on the falling edge of SCLK, the propagation delay on DOUT1 creates a setup time on DIN. Minimize the skew in SCLK to avoid timing violations.

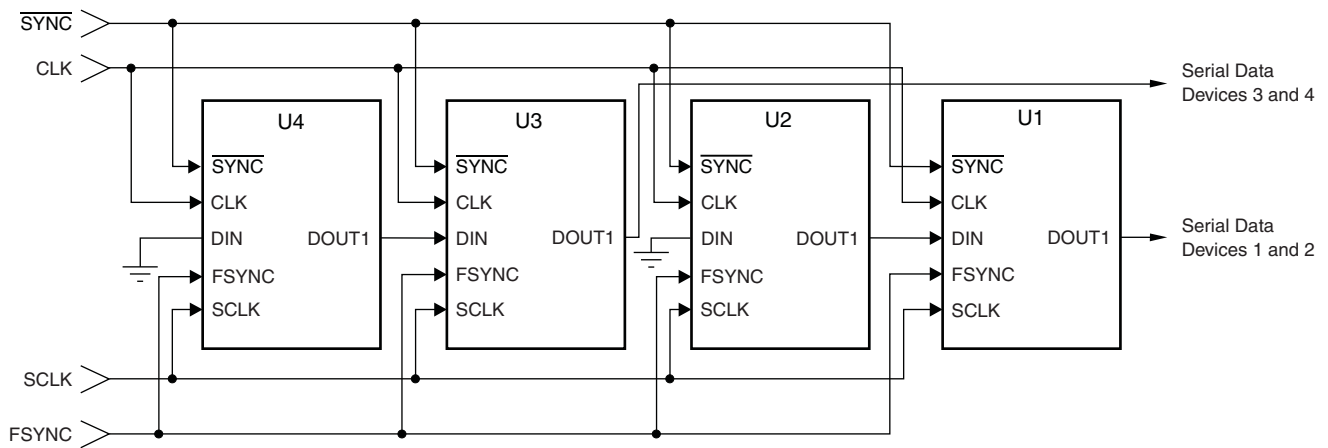


Note: The number of chained devices is limited by the SCLK rate and device mode.

**Figure 78. Daisy-Chaining of Two Devices, SPI Protocol (FORMAT[2:0] = 000 or 001)**



**Figure 79. Daisy-Chain Data Format of Figure 78**



Note: The number of chained devices is limited by the SCLK rate and device mode.

**Figure 80. Segmented DOUT Daisy-Chain, Frame-Sync Protocol (FORMAT[2:0] = 011 or 100)**

## POWER SUPPLIES

The ADS1278 has three power supplies: AVDD, DVDD, and IOVDD. AVDD is the analog supply that powers the modulator, DVDD is the digital supply that powers the digital core, and IOVDD is the digital I/O power supply. The IOVDD and DVDD power supplies can be tied together if desired (1.8 V). To achieve rated performance, it is critical that the power supplies are bypassed with 0.1- $\mu$ F and 10- $\mu$ F capacitors placed as close as possible to the supply pins. A single 10- $\mu$ F ceramic capacitor may be substituted in place of the two capacitors.

Figure 81 shows the start-up sequence of the ADS1278. At power-on, bring up the DVDD supply first, followed by IOVDD and then AVDD. Check the power-supply sequence for proper order, including the ramp rate of each supply. DVDD and IOVDD may be sequenced at the same time if the supplies are tied together. Each supply has an internal reset circuit whose outputs are summed together to generate a global power-on reset. After the supplies have exceeded the reset thresholds,  $2^{18}$   $f_{CLK}$  cycles are counted before the converter initiates the conversion process. Following the CLK cycles, the data for 129 conversions are suppressed by the ADS1278 to allow output of fully-settled data. In SPI protocol,  $\overline{DRDY}$  is held high during this interval. In frame-sync protocol, DOUT is forced to zero. The power supplies should be applied before any analog or digital pin is driven. For consistent performance, assert  $\overline{SYNC}$  after device power-on when data first appear.

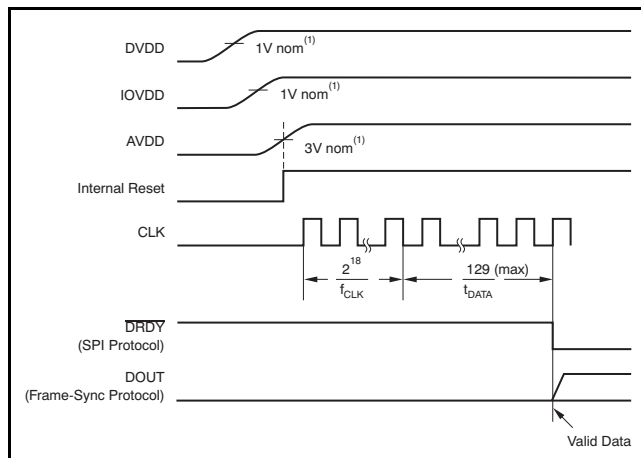


Figure 81. Start-Up Sequence

## MODULATOR OUTPUT

The ADS1278 incorporates a 6th-order, single-bit, chopper-stabilized modulator followed by a multi-stage digital filter that yields the conversion results. The data stream output of the modulator is available directly, bypassing the internal digital filter. The digital filter is disabled, reducing the DVDD current, as shown in Table 15. In this mode, an external digital filter implemented in an ASIC, FPGA, or similar device is required. To invoke the modulator output, tie  $\overline{FORMAT}[2:0]$ , as shown in Figure 82.  $\overline{DOUT}[8:1]$  then becomes the modulator data stream outputs for each channel and  $\overline{SCLK}$  becomes the modulator clock output. The  $\overline{DRDY}/\overline{FSYNC}$  pin becomes an unused output and can be ignored. The normal operation of the Frame-Sync and SPI interfaces is disabled, and the functionality of  $\overline{SCLK}$  changes from an input to an output, as shown in Figure 82.

Table 15. Modulator Output Clock Frequencies

MODE [1:0]	CLKDIV	MODULATOR CLOCK OUTPUT (SCLK)	DVDD (mA)
00	1	$f_{CLK}/4$	8
01	1	$f_{CLK}/4$	7
10	1	$f_{CLK}/8$	4
	0	$f_{CLK}/4$	4
11	1	$f_{CLK}/40$	1
	0	$f_{CLK}/8$	1

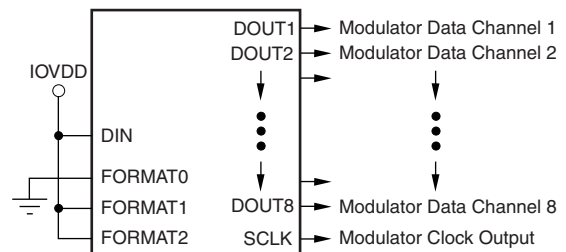


Figure 82. Modulator Output

In modulator output mode, the frequency of the modulator clock output (SCLK) depends on the mode selection of the ADS1278. Table 15 lists the modulator clock output frequency and DVDD current versus device mode.

Figure 83 shows the timing relationship of the modulator clock and data outputs.

The data output is a modulated 1s density data stream. When  $V_{IN} = +V_{REF}$ , the 1s density is approximately 80% and when  $V_{IN} = -V_{REF}$ , the 1s density is approximately 20%.

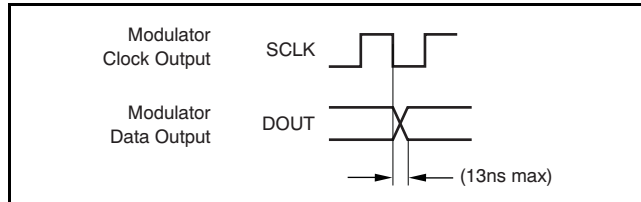


Figure 83. Modulator Output Timing

**PIN TEST USING TEST[1:0] INPUTS**

The test mode feature of the ADS1278 allows continuity testing of the digital I/O pins. In this mode, the normal functions of the digital pins are disabled and routed to each other as pairs through internal logic, as shown in Table 16. The pins in the left column drive the output pins in the right column.

**Note:** some of the digital input pins become outputs; these outputs must be accommodated in the design. The analog input, power supply, and ground pins all remain connected as normal. The test mode is engaged by setting the pins TEST [1:0] = 11. For normal converter operation, set TEST[1:0] = 00. Do not use '01' or '10'.

Table 16. Test Mode Pin Map (TEST[1:0] = 11)

TEST MODE PIN MAP	
INPUT PINS	OUTPUT PINS
$\overline{PWDN1}$	DOUT1
$\overline{PWDN2}$	DOUT2
$\overline{PWDN3}$	DOUT3
$\overline{PWDN4}$	DOUT4
$\overline{PWDN5}$	DOUT5
$\overline{PWDN6}$	DOUT6
$\overline{PWDN7}$	DOUT7
$\overline{PWDN8}$	DOUT8
MODE0	DIN
MODE1	$\overline{SYNC}$
FORMAT0	CLKDIV
FORMAT1	$\overline{FSYNC/DRDY}$
FORMAT2	SCLK

**VCOM OUTPUT**

The VCOM pin provides a voltage output equal to  $AVDD/2$ . The intended use of this output is to set the output common-mode level of the analog input drivers. The drive capability of the output is limited; therefore, the output should only be used to drive high-impedance nodes ( $> 1\text{ M}\Omega$ ). In some cases, an external buffer may be necessary. A  $0.1\text{-}\mu\text{F}$  bypass capacitor is recommended to reduce noise pickup.

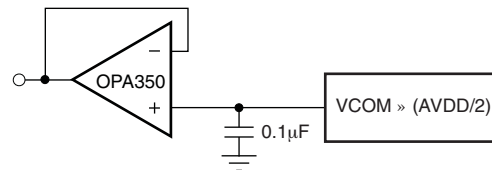


Figure 84. VCOM Output

## APPLICATION INFORMATION

To obtain the specified performance from the ADS1278, the following layout and component guidelines should be considered.

1. **Power Supplies:** The device requires three power supplies for operation: DVDD, IOVDD, and AVDD. The allowed range for DVDD is 1.65 V to 1.95 V; the range of IOVDD is 1.65 V to 3.6 V; AVDD is restricted to 4.75 V to 5.25 V. For all supplies, use a 10- $\mu$ F tantalum capacitor, bypassed with a 0.1- $\mu$ F ceramic capacitor, placed close to the device pins. Alternatively, a single 10- $\mu$ F ceramic capacitor can be used. The supplies should be relatively free of noise and should not be shared with devices that produce voltage spikes (such as relays, LED display drivers, etc.). If a switching power-supply source is used, the voltage ripple should be low (less than 2 mV) and the switching frequency outside the passband of the converter.
2. **Ground Plane:** A single ground plane connecting both AGND and DGND pins can be used. If separate digital and analog grounds are used, connect the grounds together at the converter.
3. **Digital Inputs:** It is recommended to source-terminate the digital inputs to the device with 50- $\Omega$  series resistors. The resistors should be placed close to the driving end of digital source (oscillator, logic gates, DSP, etc.) This placement helps to reduce ringing on the digital lines (ringing may lead to degraded ADC performance).
4. **Analog/Digital Circuits:** Place analog circuitry (input buffer, reference) and associated tracks together, keeping them away from digital circuitry (DSP, microcontroller, logic). Avoid crossing digital tracks across analog tracks to reduce noise coupling and crosstalk.
5. **Reference Inputs:** It is recommended to use a minimum 10- $\mu$ F tantalum with a 0.1- $\mu$ F ceramic capacitor directly across the reference inputs, VREFP and VREFN. The reference input should be driven by a low-impedance source. For best performance, the reference should have less than 3  $\mu$ V<sub>RMS</sub> in-band noise. For references with noise higher than this level, external reference filtering may be necessary.
6. **Analog Inputs:** The analog input pins must be driven differentially to achieve specified performance. A true differential driver or transformer (ac applications) can be used for this purpose. Route the analog inputs tracks (AINP, AINN) as a pair from the buffer to the converter using short, direct tracks and away from digital tracks. A 1-nF to 10-nF capacitor should be used directly across the analog input pins, AINP and AINN. A low-k dielectric (such as COG or film type) should be used to maintain low THD. Capacitors from each analog input to ground can be used. They should be no larger than 1/10 the size of the difference capacitor (typically 100 pF) to preserve the ac common-mode performance.
7. **Component Placement:** Place the power supply, analog input, and reference input bypass capacitors as close as possible to the device pins. This layout is particularly important for small-value ceramic capacitors. Larger (bulk) decoupling capacitors can be located farther from the device than the smaller ceramic capacitors.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
ADS1278MPAPTEP	ACTIVE	HTQFP	PAP	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-55 to 125	ADS1278EP	<a href="#">Samples</a>
V62/12600-01EX	ACTIVE	HTQFP	PAP	64		TBD	Call TI	Call TI	-55 to 125		<a href="#">Samples</a>
V62/12611-01XE	ACTIVE	HTQFP	PAP	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-55 to 125	ADS1278EP	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSELETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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**OTHER QUALIFIED VERSIONS OF ADS1278-EP :**

- Catalog: [ADS1278](#)

NOTE: Qualified Version Definitions:

- Catalog - TI's standard catalog product

## TAPE AND REEL INFORMATION



### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ADS1278MPAPTEP	HTQFP	PAP	64	250	180.0	24.4	13.0	13.0	1.5	16.0	24.0	Q2



TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ADS1278MPAPTEP	HTQFP	PAP	64	250	213.0	191.0	55.0

PAP (S-PQFP-G64)

PowerPAD™ PLASTIC QUAD FLATPACK



- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Body dimensions do not include mold flash or protrusion
  - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 for information regarding recommended board layout. This document is available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>.
  - E. Falls within JEDEC MS-026

PowerPAD is a trademark of Texas Instruments.

## THERMAL PAD MECHANICAL DATA

PAP (S-PQFP-G64)

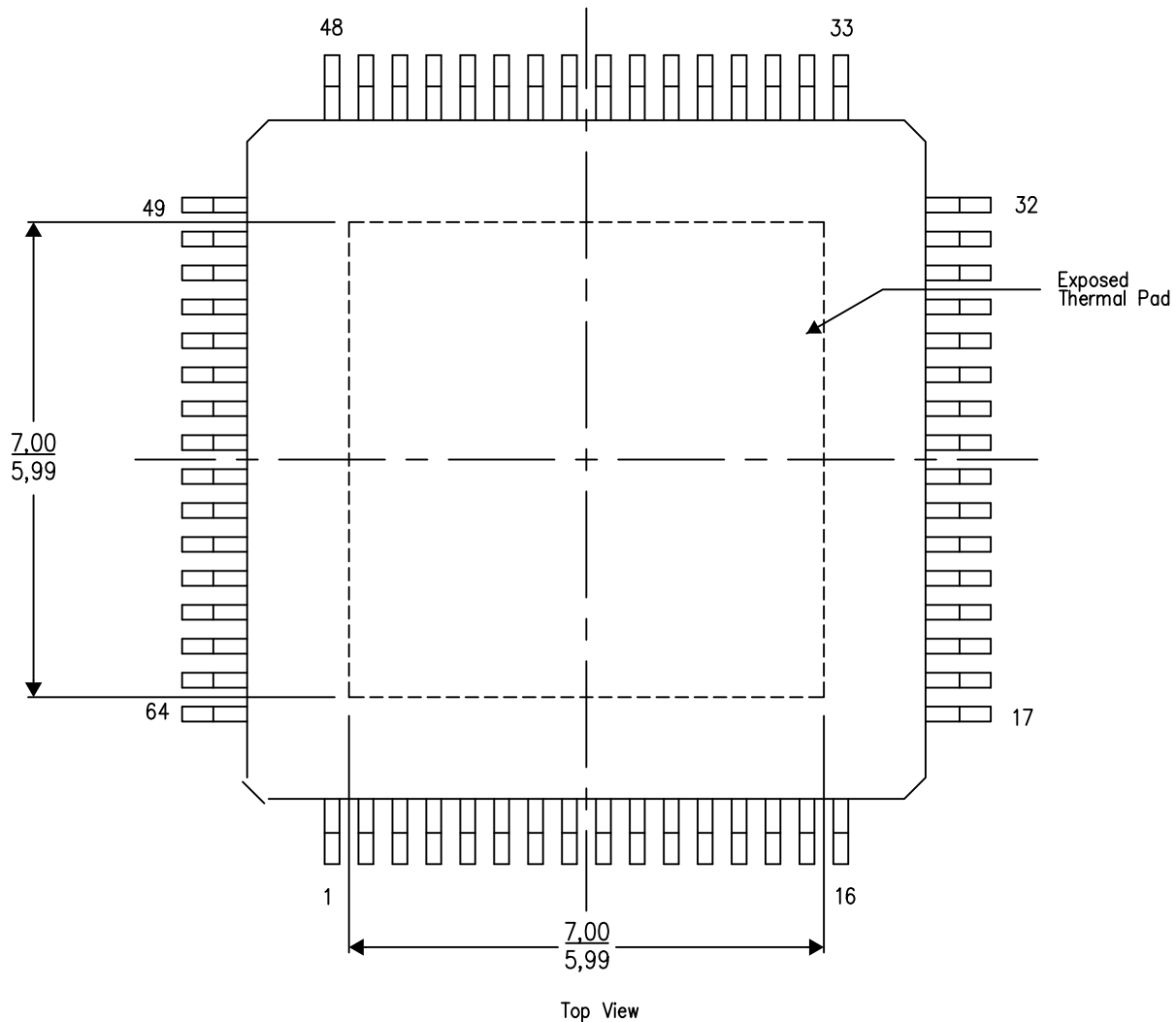
PowerPAD™ PLASTIC QUAD FLATPACK

### THERMAL INFORMATION

This PowerPAD™ package incorporates an exposed thermal pad that is designed to be attached to a printed circuit board (PCB). The thermal pad must be soldered directly to the PCB. After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For additional information on the PowerPAD package and how to take advantage of its heat dissipating abilities, refer to Technical Brief, PowerPAD Thermally Enhanced Package, Texas Instruments Literature No. SLMA002 and Application Brief, PowerPAD Made Easy, Texas Instruments Literature No. SLMA004. Both documents are available at [www.ti.com](http://www.ti.com).

The exposed thermal pad dimensions for this package are shown in the following illustration.



4206326-5/P 05/14

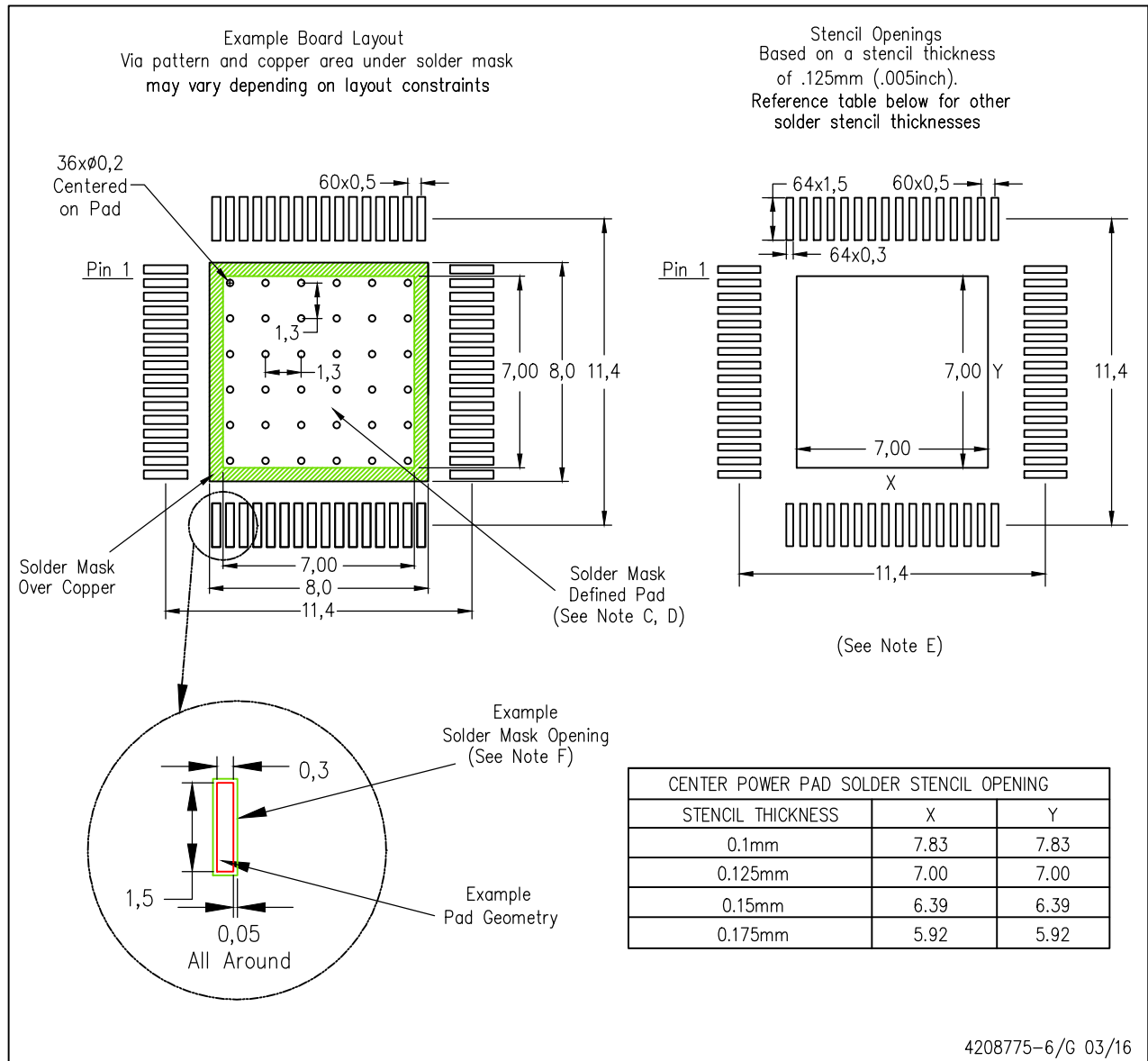
NOTES: A. All linear dimensions are in millimeters

PowerPAD is a trademark of Texas Instruments

# LAND PATTERN DATA

PAP (S-PQFP-G64)

PowerPAD™ PLASTIC QUAD FLATPACK



- NOTES:
- A. All linear dimensions are in millimeters.
  - B. This drawing is subject to change without notice.
  - C. Customers should place a note on the circuit board fabrication drawing not to alter the center solder mask defined pad.
  - D. This package is designed to be soldered to a thermal pad on the board. Refer to Technical Brief, PowerPad Thermally Enhanced Package, Texas Instruments Literature No. SLMA002, SLMA004, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at [www.ti.com](http://www.ti.com) <<http://www.ti.com>>. Publication IPC-7351 is recommended for alternate designs.
  - E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Example stencil design based on a 50% volumetric metal load solder paste. Refer to IPC-7525 for other stencil recommendations.
  - F. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.
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Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
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