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- $\bullet$  **Start-Up Into a Full Load With Supply Voltages as Low as 0.9 V Over Full Temperature Range**
- $\bullet$  **Minimum 100-mA Output Current From 0.8-V Supply Voltage, 250 mA From 1.8 V**
- $\bullet$  **High Power Conversion Efficiency, up to 90%**
- $\bullet$  **Power-Save Mode for Improved Efficiency at Low Output Currents**
- $\bullet$ **Device Quiescent Current Less Than 50** µ**A**
- $\bullet$  **Added System Security With Integrated Low-Battery Comparator** ·
- $\bullet$  **Low-EMI Converter (Integrated Antiringing Switch Across Inductor)**
- $\bullet$ **Micro-Size 10-Pin MSOP Package**
- $\bullet$  **Evaluation Modules Available (TPS6100xEVM–156)**
- $\bullet$  **Applications Include:**
	- **Single- and Dual-Cell Battery Operated Products**
	- **MP3-Players and Wireless Headsets**
	- **Pagers and Cordless Phones**
	- **Portable Medical Diagnostic Equipment**
	- **Remote Controls**

### **description**

The TPS6100x devices are boost converters intended for systems that are typically operated from a single- or dual-cell nickel-cadmium (NiCd), nickel-metal hydride (NiMH), or alkaline battery. The converter output voltage can be adjusted from 1.5 V to a maximum of 3.3 V and provides a minimum output current of 100 mA from a single battery cell and 250 mA from two battery cells. The converter starts up into a full load with a supply voltage of 0.9 V and stays in operation with supply voltages as low as 0.8 V.

The converter is based on a fixed-frequency, current-mode pulse-width-modulation (PWM) controller that goes into power-save mode at low load currents. The current through the switch is limited to a maximum of 1100 mA, depending on the output voltage. The current sense is integrated to further minimize external component count. The converter can be disabled to minimize battery drain when the system is put into standby.

A low-EMI mode is implemented to reduce interference and radiated electromagnetic energy that is caused by the ringing of the inductor when the inductor discharge-current decreases to zero. The device is packaged in the space-saving 10-pin MSOP package.





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† The DGS package is available taped and reeled. Add R suffix to device type (e.g. TPS61000DGSR) to order quantities of 2500 devices per reel.







‡ TPS61007 only



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### **functional block diagram**

#### **fixed output-voltage option**



**adjustable output-voltage option (TPS61000 only)**





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## **functional block diagram (continued)**

### **adjustable output-voltage option (TPS61007 only)**



### **detailed description**

#### **controller circuit**

The device is based on a current-mode control topology using a constant-frequency pulse-width modulator to regulate the output voltage. It runs at an oscillator frequency of 500 kHz. The current sense is implemented by measuring the voltage across the switch. The controller also limits the current through the power switch on a pulse-by-pulse basis. Care must be taken that the inductor saturation current is higher than the current limit of the TPS6100x. This prevents the inductor from going into saturation and therefore protects both device and inductor. The current limit should not become active during normal operating conditions.

The TPS6100x is designed for high efficiency over a wide output current range. Even at light loads the efficiency stays high because the controller enters a power-save mode, minimizing switching losses of the converter. In this mode, the controller only switches if the output voltage trips below a set threshold voltage. It ramps up the output voltage with one or several pulses, and again goes into the power-save mode once the output voltage exceeds the threshold voltage. The controller enters the power-save mode when the output current drops to levels that force the discontinuous current mode. It calculates a minimum duty cycle based on input and output voltage and uses the calculation for the transition out of the power-save mode into continuous current mode.

The control loop must be externally compensated with an R/C/C network connected to the COMP pin. See the application section for more details on the design of the compensation network.

#### **device enable**

The device is put into operation when EN is set high. During start-up of the converter the input current from the battery is limited until the voltage on COMP reaches its operating point. The device is put into a shutdown mode when EN is set to GND. In this mode, the regulator stops switching and all internal control circuitry including the low-battery comparator is switched off. The output voltage drops to one diode drop below the input voltage in shutdown.



#### **detailed description (continued)**

#### **under-voltage lockout**

An under-voltage lockout function prevents the device start-up if the supply voltage on  $V_{\text{BAT}}$  is lower than approximately 0.7 V. This undervoltage lockout function is implemented in order to prevent the malfunctioning of the converter. When in operation and the battery is being discharged, the device automatically enters the shutdown mode if the voltage on  $V<sub>BAT</sub>$  drops below approximately 0.7 V.

If the EN pin is hardwired to V<sub>BAT</sub> and if the voltage at V<sub>BAT</sub> drops temporarily below the UVLO threshold voltage, the device switches off and does not start up again automatically, even if the supply voltage rises above 0.9 V. The device starts up again only after a signal change from low to high on EN or if the battery voltage is completely removed.

#### **low Battery detector circuit (LBI and LBO)**

The low-battery detector circuit is typically used to supervise the battery voltage and to generate an error flag when the battery voltage drops below a user-set threshold voltage. The function is active only when the device is enabled. When the device is disabled, the LBO pin is high impedance. The LBO pin goes active low when the voltage on the LBI pin decreases below the set threshold voltage of 500 mV  $\pm$ 15 mV, which is equal to the internal reference voltage. The battery voltage, at which the detection circuit switches, can be programmed with a resistive divider connected to the LBI pin. The resistive divider scales down the battery voltage to a voltage level of 500 mV, which is then compared to the LBI threshold voltage. The LBI pin has a built-in hysteresis of 10 mV. See the application section for more details about the programming of the LBI threshold.

If the low-battery detection circuit is not used, the LBI pin should be connected to GND (or to  $V_{BAT}$ ) and the LBO pin can be left unconnected. Do not let the LBI pin float.

#### **low-EMI switch**

The device integrates a circuit which removes the ringing that typically appears on the SW-node when the converter enters the discontinuous current mode. In this case, the current through the inductor ramps to zero and the Schottky diode stops conducting. Due to remaining energy that is stored in parasitic components of the diode, inductor, and switch, a ringing on the SW pin is induced. The integrated antiringing switch clamps this voltage internally to  $V<sub>BAT</sub>$  and therefore dampens this ringing.

The antiringing switch is turned on by a comparator that monitors the voltage between SW and V<sub>OUT</sub>. This voltage indicates when the diode is reverse biased. The ringing on the SW-node is damped to a large degree, reducing the electromagnetic interference generated by the switching regulator to a very great extent.

#### **adjustable output voltage (TPS61000 and TPS61007 only)**

The accuracy of the internal voltage reference, the controller topology, and the accuracy of the external resistor divider determine the accuracy of the adjustable output voltage versions. The reference voltage has an accuracy of  $\pm$ 4% over line, load, and temperature. The controller switches between fixed frequency and pulse-skip mode, depending on load current. This adds an offset to the output voltage that is equivalent to 1% of  $V_{\Omega}$ . Using 1% accurate resistors for the feedback divider, a total accuracy of  $\pm 6\%$  can be achieved over the complete temperature and output current range. The TPS61007 is an improved adjustable output voltage version. Ground shift in the feedback loop was eliminated by adding a separate ground pin for the feedback resistor divider (FBGND).



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#### **absolute maximum ratings†**



† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### **DISSIPATION RATING TABLE**



#### **recommended operating conditions**





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### electrical characteristics over recommended operating free-air temperature range, V<sub>BAT</sub> = 1.2 V, EN **= VBAT (unless otherwise noted)**



NOTE 1: Line and load regulation is measured as a percentage deviation from the nominal value (i.e., as percentage deviation from the nominal output voltage). For line regulation,  $x$  %/V stands for  $\pm x$ % change of the nominal output voltage per 1-V change on the input/supply voltage. For load regulation, y% stands for ±y% change of the nominal output voltage per the specified current change.



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### electrical characteristics over recommended operating free-air temperature range, V<sub>BAT</sub> = 1.2 V, EN **= VBAT (unless otherwise noted) (continued)**



#### **PARAMETER MEASUREMENT INFORMATION**



**List of Components:**

- **IC1: Only fixed output versions**
	- **(unless otherwise noted)**
- **L1: Coilcraft DO3308P–333 D1: Motorola Schottky Diode**
- **MBRM120LT3**
- **CI: Ceramic**
- **CO: Ceramic**

**Figure 1. Circuit Used for Typical Characteristics Measurements**



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### **TYPICAL CHARACTERISTICS**



### **Table of Graphs**





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### **TYPICAL CHARACTERISTICS**



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### **TYPICAL CHARACTERISTICS**



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### **APPLICATION INFORMATION**

The TPS6100x boost converter family is intended for systems that are powered by a single-cell NiCd or NiMH battery with a typical terminal voltage between 0.9 V to 1.6 V. It can also be used in systems that are powered by two-cell NiCd or NiMH batteries with a typical stack voltage between 1.8 V and 3.2 V. Additionally, singleor dual-cell, primary and secondary alkaline battery cells can be the power source in systems where the TPS6100x is used.

### **programming the TPS61000 and TPS61007 adjustable output voltage devices**

The output voltage of the TPS61000 and TPS61007 can be adjusted with an external resistor divider. The typical value of the voltage on the FB pin is 500 mV in fixed frequency operation and 485 mV in the power-save operation mode. The maximum allowed value for the output voltage is 3.3 V. The current through the resistive divider should be about 100 times greater than the current into the FB pin. The typical current into the FB pin is 0.01 µA, and the voltage across R4 is typically 500 mV. Based on those two values, the recommended value for R4 is in the range of 500 kΩ in order to set the divider current at 1  $\mu$ A. From that, the value of resistor R3, depending on the needed output voltage  $V_{\text{OUT}}$ , can be calculated using the following equation:

$$
R3 = R4 \times \left(\frac{V_O}{V_{FB}} - 1\right) = 500 \text{ k}\Omega \times \left(\frac{V_O}{500 \text{ mV}} - 1\right)
$$
 (1)

If, as an example, an output voltage of 2.5 V is needed, a 2-MΩ resistor should be chosen for R3.



**Figure 18. Typical Application Circuit for Adjustable Output Voltage Option**

The TPS61007 is an improved version of the TPS61000 adjustable output voltage device. The FBGND pin is internally connected to GND.



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#### **APPLICATION INFORMATION**

#### **programming the low battery comparator threshold voltage**

The current through the resistive divider should be about 100 times greater than the current into the LBI pin. The typical current into the LBI pin is 0.01  $\mu$ A. The voltage across R2 is equal to the reference voltage that is generated on-chip, which has a value of 500 mV ±15 mV. The recommended value for R2 is therefore in the range of 500 kΩ. From that, the value of resistor R1, depending on the desired minimum battery voltage (V<sub>BAT</sub>), can be calculated using the following equation:

$$
R1 = R2 \times \left(\frac{V_{TRIP}}{V_{REF}} - 1\right) = 500 \text{ k}\Omega \times \left(\frac{V_{BAT}}{0.5 \text{ V}} - 1\right)
$$
 (2)

For example, if the low-battery detection circuit should flag an error condition on the LBO output pin at a battery voltage of 1.0 V, a resistor in the range of 500 k $\Omega$  should be chosen for R1.

The output of the low battery comparator is a simple open-drain output that goes active low if the battery voltage drops below the programmed threshold voltage on LBI. The output requires a pullup resistor with a recommended value of 1MΩ, and should only be pulled up to the  $V_{\text{OUT}}$ . If not used, the LBO pin can be left floating.

#### **inductor selection**

The output filter of inductive switching regulators is a low pass filter of second order. It consists of an inductor and a capacitor, often referred to as storage inductor and output capacitor.

To select an inductor, keep the possible peak inductor current below the current limit threshold of the power switch in your chosen configuration. For example, the current limit threshold of the TPS61006's switch is 1100 mA at an output voltage of 3.3 V. The highest peak current through the inductor and the switch depends on the output load, the input ( $V_{BAT}$ ), and the output voltage ( $V_{OUT}$ ). Estimation of the maximum average inductor current can be done using the following equation:

$$
I_{L} = I_{OUT} \times \frac{V_{OUT}}{V_{BAT} \times 0.8}
$$
 (3)

For example, for an output current of 100 mA at 3.3 V, at least 515-mA current flows through the inductor at a minimum input voltage of 0.8 V.

The second parameter for choosing the inductor is the desired current ripple in the inductor. Normally it is advisable to work with a ripple of less than 20% of the average inductor current. A smaller ripple reduces the magnetic hysteresis losses in the inductor as well as output voltage ripple and EMI. But in the same way, the regulation time at load change rises. In addition, a larger inductor increases the total system cost.



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### **APPLICATION INFORMATION**

With those parameters it is possible to calculate the value for the inductor:

$$
L = \frac{V_{BAT} \times (V_{OUT} - V_{BAT})}{\Delta l_L \times f \times V_{OUT}} \tag{4}
$$

Parameter f is the switching frequency and ∆I<sub>L</sub> is the ripple current in the inductor, i.e., 20% x I<sub>L</sub>.

In this example, the desired inductor has the value of  $12 \mu H$ . With this calculated value and the calculated currents, it is possible to chose a suitable inductor. Care has to be taken that load transients and losses in the circuit can lead to higher currents as estimated in equation 3. Also, the losses in the inductor caused by magnetic hysteresis losses and copper losses are a major parameter for total circuit efficiency.

The following inductors from different suppliers were tested. All work with the TPS6100x converter within their specified parameters:

<b>VENDOR</b>	<b>PART NUMBER</b>			
Coilcraft	DO1608P Series			
	DS1608P Series			
	DO3308 Series			
Coiltronics	<b>UP1B Series</b>			
	<b>UP2B Series</b>			
Murata	LOH3N Series			
Sumida	CD43 Series			
	CD54 Series			
	<b>CDR74B Series</b>			
TDK	NLC453232T Series			

**Table 1. Recommended Inductors**

#### **capacitor selection**

The major parameter necessary to define the output capacitor is the maximum allowed output voltage ripple of the converter. This ripple is determined by two parameters of the capacitor, the capacitance and the ESR. It is possible to calculate the minimum capacitance needed for the defined ripple, supposing that the ESR is zero.

$$
C_{\min} = \frac{I_{OUT} \times (V_{OUT} - V_{BAT})}{f \times \Delta V \times V_{OUT}} \tag{5}
$$

Parameter f is the switching frequency and ∆V is the maximum allowed ripple.

With a chosen ripple voltage of 15 mV, a minimum capacitance of 10  $\mu$ F is needed. The total ripple will be larger due to the ESR of the output capacitor. This additional component of the ripple can be calculated using the following equation:

$$
\Delta V_{ESR} = I_{OUT} \times R_{ESR} \tag{6}
$$



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An additional ripple of 30 mV is the result of using a tantalum capacitor with a low ESR of 300 mΩ. The total ripple is the sum of the ripple caused by the capacitance and the ripple caused by the ESR of the capacitor. In this example, the total ripple is 45 mV. It is possible to improve the design by enlarging the capacitor or using smaller capacitors in parallel to reduce the ESR or by using better capacitors with lower ESR, like ceramics. For example, a 10-µF ceramic capacitor with an ESR of 50 mΩ is used on the evaluation module (EVM). Tradeoffs have to be made between performance and costs of the converter circuit.

A 10-µF input capacitor is recommended to improve transient behavior of the regulator. A ceramic capacitor or a tantalum capacitor with a 100-nF ceramic capacitor in parallel placed close to the IC is recommended.

#### **rectifier selection**

The rectifier diode has a major impact on the overall converter efficiency. Standard diodes are not suitable for low-voltage switched mode power supplies. A Schottky diode with low forward voltage and fast reverse recovery should be used as a rectifier to minimize overall losses of the dc-dc converter. The maximum current rating of the diode must be high enough for the application. The maximum diode current is equal to the maximum current in the inductor that was calculated in equation 3. The maximum reverse voltage is the output voltage. The chosen diode should therefore have a reverse voltage rating higher than the output voltage.

<b>VENDOR</b>	<b>PART NUMBER</b>		
Motorola Surface Mount	MBRM120LT3		
	MBR0520LT1		
Motorola Axial Lead	1N1517		
<b>ROHM</b>	RB520S-30		
	RB160L-40		

**Table 2. Recommended Diodes**

The typical forward voltage of those diodes is in the range of 0.35 to 0.45 V assuming a peak diode current of 600 mA.

#### **compensation of the control loop**

An R/C/C network must be connected to the COMP pin in order to stabilize the control loop of the converter. Both the pole generated by the inductor L1 and the zero caused by the ESR and capacitance of the output capacitor must be compensated. The network shown in Figure 19 satisfies these requirements.



**Figure 19. Compensation of the Control Loop**



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### **APPLICATION INFORMATION**

Resistor R<sub>C</sub> and capacitor C<sub>C2</sub> depend on the chosen inductance. For a 33- $\mu$ H inductor, the capacitance of C<sub>C2</sub> should be chosen to 33 nF, or in other words, if the inductor is xx  $\mu$ H, the chosen compensation capacitor should be xx nF, the same number value. The value of the compensation resistor is then chosen based on the requirement to have a time constant of 0.3 ms for the R/C network of R<sub>C</sub> and C<sub>C2</sub>; hence for a 33-nF capacitor, a 10-kΩ resistor should be chosen for  $R_C$ .

Capacitor C<sub>C1</sub> is depending on the ESR and capacitance value of the output capacitor, and on the value chosen for  $R_C$ . Its value is calculated using following equation:

$$
C_{C1} = \frac{C_{O} \times ESR_{COUT}}{3 \times R_{C}}
$$
 (7)

For a selected output capacitor of 22 µF with an ESR of 0.2  $\Omega$ , and R<sub>C</sub> of 33 k $\Omega$ , the value of C<sub>C1</sub> is in the range of 100 pF.

	<b>OUTPUT CAPACITOR</b>				
<b>INDUCTOR</b> $[\mu H]$	<b>CAPACITANCE</b> $[\mu$ F]	<b>ESR</b> $[\Omega]$	$R_{\rm C}$ [ $k\Omega$ ]	$\frac{C_{C1}}{[pF]}$	$CC2$ [nF]
33	22	0.2	10	100	33
22	22	0.3	15	100	22
10	22	0.4	33	100	10
10	10	0.1	33	100	10

**Table 3. Recommended Compensation Components**

**schematic of TPS6100x evaluation modules (TPS6100xEVM–156)**



Evaluation modules are available for device types TPS61000, TPS61002, TPS61003, and TPS61006.



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## **APPLICATION INFORMATION**

**suggested board layout and component placement (21 mm x 21 mm board size)**





**Figure 20. Top Layer Layout and Component Placement**



**Figure 21. Bottom Layer Layout and Component Placement**



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## **THERMAL INFORMATION**

Implementation of integrated circuits in low-profile and fine-pitch surface-mount packages typically requires special attention to power dissipation. Many system-dependent issues such as thermal coupling, airflow, added heat sinks and convection surfaces, and the presence of other heat-generating components affect the powerdissipation limits of a given component.

Three basic approaches for enhancing thermal performance are listed below:

- Improving the power dissipation capability of the PWB design
- Improving the thermal coupling of the component to the PWB
- Introducing airflow in the system

The maximum junction temperature  $(T<sub>J</sub>)$  of the TPS6100x devices is 125°C. The thermal resistance of the 10-pin MSOP package (DGS) is  $R_{\theta,JA} = 294$ °C/W. Specified regulator operation is assured to a maximum ambient temperature ( $T_A$ ) of 85 °C. Therefore, the maximum power dissipation is about 130 mW. More power can be dissipated if the maximum ambient temperature of the application is lower.

$$
P_{D(MAX)} = \frac{T_{J(MAX) - A}}{R_{\Theta JA}} = \frac{125 \,^{\circ}\text{C} - 85 \,^{\circ}\text{C}}{294 \,^{\circ}\text{C}/\text{W}} = 136 \, \text{mW}
$$
 (8)

Under normal operating conditions, the sum of all losses generated inside the converter IC is less than 50 mW, which is well below the maximum allowed power dissipation of 136 mW as calculated in equation 8. Therefore, power dissipation is given no special attention.

Table 4 shows where the losses inside the converter are generated.



### **Table 4. Losses Inside the Converter**





## **PACKAGING INFORMATION**







**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

**(2)** Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check<http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

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Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

**(3)** MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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## **TAPE AND REEL INFORMATION**





### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





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# **PACKAGE MATERIALS INFORMATION**

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\*All dimensions are nominal



DGS (S-PDSO-G10)

PLASTIC SMALL-OUTLINE PACKAGE



А. All linear dimensions are in millimeters.

- This drawing is subject to change without notice. **B.**
- Body dimensions do not include mold flash or protrusion.  $C.$
- D. Falls within JEDEC MO-187 variation BA.



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