

TMP61 Silicon-Based Linear Thermistor for Temperature Sensing

1 Features

- Silicon-Based Thermistor With a Positive Temperature Coefficient (PTC)
- Linear Resistance Change With Temperature
 - Simplifies Resistance-to-Temperature Conversion
 - Decrease Accuracy Spread Compared to Non-Linear Negative Temperature Coefficient (NTC) Thermistor-Based Circuits Across a Wide Temperature Range
- 10-kΩ Nominal Resistance at 25°C (R25)
 - ±1% Maximum (0°C to 70°C)
- Consistent Sensitivity Across Temperature
 - 6400 ppm/°C TCR (25°C)
 - 0.2% Typical TCR Tolerance Across Temperature (-40°C to 125°C)
- Wide Operating Temperature:
 - -65 to +150°C
- Fast Thermal Response Time:
 - 0.6s (DEC package)
- Long Lifetime and Robust Performance
 - Ultra low power consumption compared to traditional NTCs that lower errors due to self heating
 - Built-in fail-safe in case of short circuit failures
 - <1% Maximum Drift after high temperature and high humidity stress tests
- Available Package Options:
 - X1SON (DEC/0402 Footprint)
 - TO-92S (LPG)
 (Contact Representative for Availability)

2 Applications

- Temperature Measurement And Monitoring
- Thermal Compensation
- Thermal Protection (With Comparator)

3 Description

The TMP61xx series of Silicon Linear Thermistors has a linear positive temperature coefficient (PTC) that results in a uniform, consistent temperature coefficient resistance (TCR) across a wide operating temperature range. These devices are designed for temperature measurement, protection, compensation, and control systems. Compared to traditional NTC thermistors, the TMP61xx series of devices offers enhanced linearity and consistent sensitivity across the full temperature range. They also have robust performance due to their immunity to environmental variation and their built-in fail-safe behavior at high temperatures. These devices are currently available in a 2-pin, surface-mount, 0402 footprint-compatible X1SON package and a 2-pin, through-hole, mini-sized transistor-outline TO-92S package.

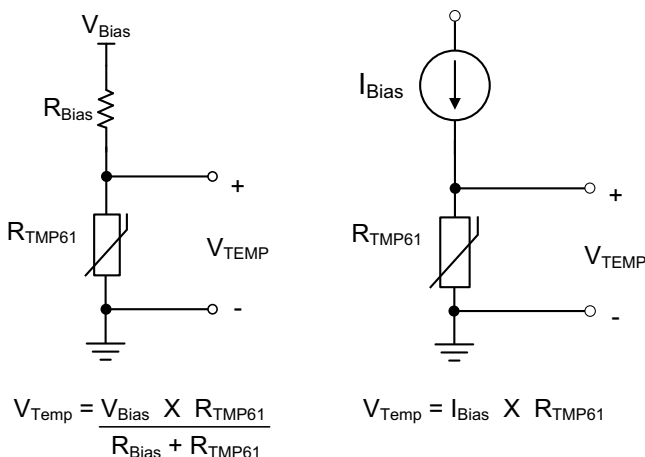
Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
TMP61	X1SON	0.60 mm x 1.00 mm
	TO-92S (2) ⁽²⁾	4.00 mm x 3.15 mm

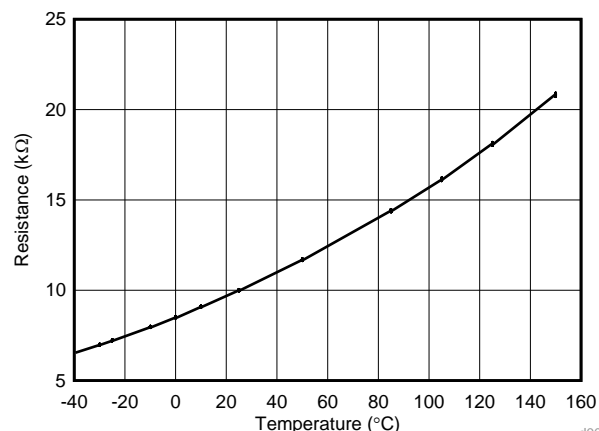
(1) For all available packages, see the orderable addendum at the end of the data sheet.

(2) This package is in preview

Typical Implementation Circuits



Typical Resistances vs Ambient Temperature



d001



Table of Contents

1 Features	1	8.3 Feature Description	8
2 Applications	1	8.4 Device Functional Modes	10
3 Description	1	9 Application and Implementation	11
4 Revision History	2	9.1 Application Information	11
5 Device Comparison Table	3	9.2 Typical Application	11
6 Pin Configuration and Functions	3	10 Power Supply Recommendations	17
7 Specifications	4	11 Layout	17
7.1 Absolute Maximum Ratings	4	11.1 Layout Guidelines	17
7.2 ESD Ratings	4	11.2 Layout Examples	18
7.3 Recommended Operating Conditions	4	12 Device and Documentation Support	19
7.4 Thermal Information	4	12.1 Receiving Notification of Documentation Updates	19
7.5 Electrical Characteristics	5	12.2 Community Resources	19
7.6 Typical Characteristics	6	12.3 Trademarks	19
8 Detailed Description	8	12.4 Electrostatic Discharge Caution	19
8.1 Overview	8	12.5 Glossary	19
8.2 Functional Block Diagram	8	13 Mechanical, Packaging, and Orderable Information	19

4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

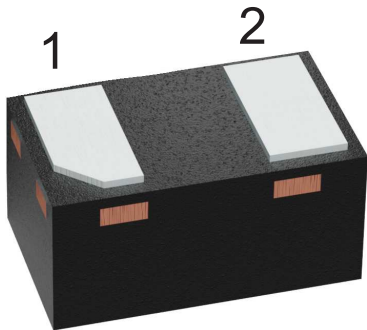
DATE	REVISION	NOTES
December 2018	*	Initial release.

5 Device Comparison Table

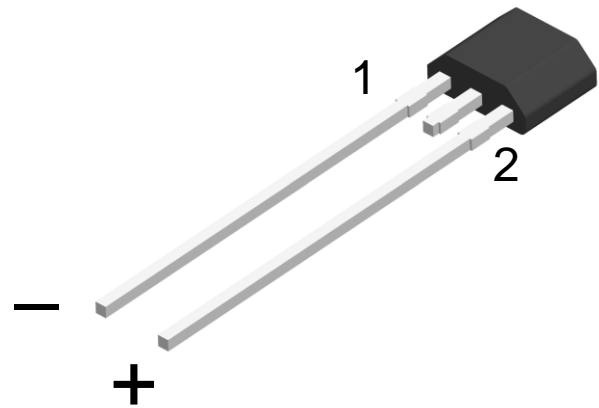
PART NUMBER	RATING	R25 TYP	R25 %TOL	PACKAGE	T _A
TMP61DEC	Catalog	10k	1%	X1SON / DEC (0402)	–65°C to 150°C
TMP61LPG				TO92s / LPG	–65°C to 150°C

6 Pin Configuration and Functions

DEC Package
2-Pin X1SON
Top View (Angled)



LPG Package
2-Pin TO-92S
Top View (Angled)



(1) The package is in preview

Pin Functions

NAME	PIN		TYPE	DESCRIPTION
	X1SON (DEC)	TO-92S (LPG)		
–	1	1	—	Thermistor (–) and (+) terminals. For proper operation, ensure a positive bias where the + terminal is at a higher voltage potential than the – terminal.
+	2	2		

7 Specifications

7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted) ⁽¹⁾

	MIN	MAX	UNIT
Voltage across the device		+6	V
Current through the device		+450	μA
Junction temperature (T _J)	–65	+150	°C
Storage temperature (T _{stg})	–65	+150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

7.2 ESD Ratings

			VALUE	UNIT
V _(ESD)	Electrostatic discharge	Human-body model (HBM) per JESD22-A114 ⁽¹⁾	±1500	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 ⁽²⁾	±750	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V _{Sns}	Voltage Across Pins 2 (+) and 1 (–)	0		5.5	V
I _{Sns}	Current passing through the device	0		400	μA
T _A	Operating free-air temperature (specified performance) (X1SON/DEC Package)	–40		125	°C
T _A	Operating free-air temperature (functional, unspecified performance) (X1SON/DEC Package)	–65		150	°C

7.4 Thermal Information

THERMAL METRIC ⁽¹⁾ ⁽²⁾		TMP6131	Units
		DEC (X1SON)	
		2 PINS	
R _{θJA}	Junction-to-ambient thermal resistance ⁽³⁾ ⁽⁴⁾	443.4	°C/W
R _{θJC(top)}	Junction-to-case (top) thermal resistance	195.7	°C/W
R _{θJB}	Junction-to-board thermal resistance	254.6	°C/W
Ψ _{JT}	Junction-to-top characterization parameter	19.9	°C/W
Ψ _{JB}	Junction-to-board characterization parameter	254.5	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.
 (2) For information on self-heating and thermal response time see [Layout Guidelines](#) section.
 (3) The junction to ambient thermal resistance (R_{θJA}) under natural convection is obtained in a simulation on a JEDEC-standard, High-K board as specified in JESD51-7, in an environment described in JESD51-2. Exposed pad packages assume that thermal vias are included in the PCB, per JESD 51-5.
 (4) Changes in output due to self heating can be computed by multiplying the internal dissipation by the thermal resistance.

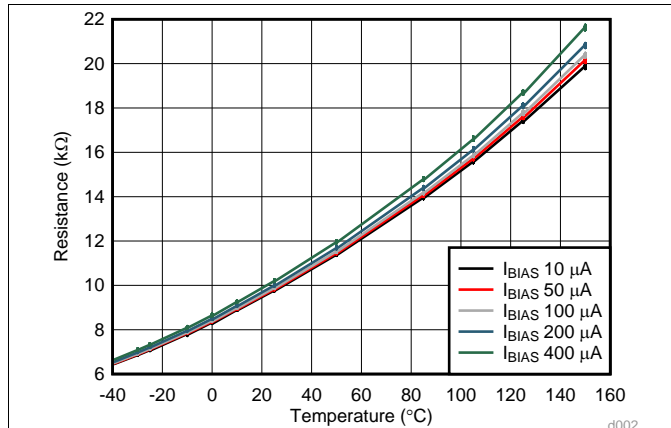
7.5 Electrical Characteristics

 $T_A = -40^{\circ}\text{C} - 125^{\circ}\text{C}$, $I_{\text{Sns}} = 200 \mu\text{A}$ (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
R_{25}	Thermistor Resistance at 25°C	$T_A = 25^{\circ}\text{C}$	9.9	10	10.1	k Ω
R_{TOL}	Resistance Tolerance	$T_A = 25^{\circ}\text{C}$	-1		+1	%
		$T_A = 0^{\circ}\text{C} - 70^{\circ}\text{C}$	-1		+1	
		$T_A = -40^{\circ}\text{C} - 125^{\circ}\text{C}$	-1.5		+1.5	
$\text{TCR}_{.35}$	Temperature Coefficient of Resistance	$T_1 = -40^{\circ}\text{C}$, $T_2 = -30^{\circ}\text{C}$		+6220		ppm/ $^{\circ}\text{C}$
TCR_{25}		$T_1 = 20^{\circ}\text{C}$, $T_2 = 30^{\circ}\text{C}$		+6400		
TCR_{85}		$T_1 = 80^{\circ}\text{C}$, $T_2 = 90^{\circ}\text{C}$		+5910		
$\text{TCR}_{.35} \%$	Temperature Coefficient of Resistance Tolerance	$T_1 = -40^{\circ}\text{C}$, $T_2 = -30^{\circ}\text{C}$		± 0.4		%
$\text{TCR}_{25} \%$		$T_1 = 20^{\circ}\text{C}$, $T_2 = 30^{\circ}\text{C}$		± 0.2		
$\text{TCR}_{85} \%$		$T_1 = 80^{\circ}\text{C}$, $T_2 = 90^{\circ}\text{C}$		± 0.3		
ΔR	Sensor Long Term Drift (Reliability)	96 hours continuous operation, RH=85%, $T_A = 130^{\circ}\text{C}$, $V_{\text{Bias}} = 5.5\text{V}$	0.1		+0.8	%
		600 hours continuous operation, $T_A = 150^{\circ}\text{C}$, $V_{\text{Bias}} = 5.5\text{V}$	0.1		+1	
t_{RES} (stirred liquid)	Thermal response to 63%	$T_1=25^{\circ}\text{C}$ in Still Air to $T_2=125^{\circ}\text{C}$ in Stirred Liquid		0.6		s
t_{RES} (still air)	Thermal response to 63%	$T_1=25^{\circ}\text{C}$ to $T_2=70^{\circ}\text{C}$ in Still Air		3.2		s

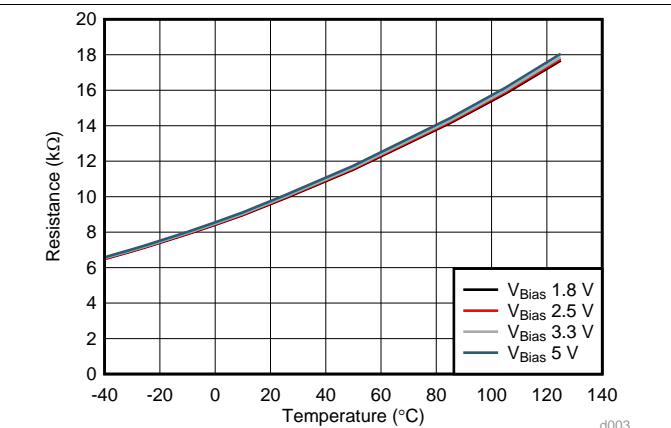
7.6 Typical Characteristics

at $T_A = 25^\circ\text{C}$, (unless otherwise noted)



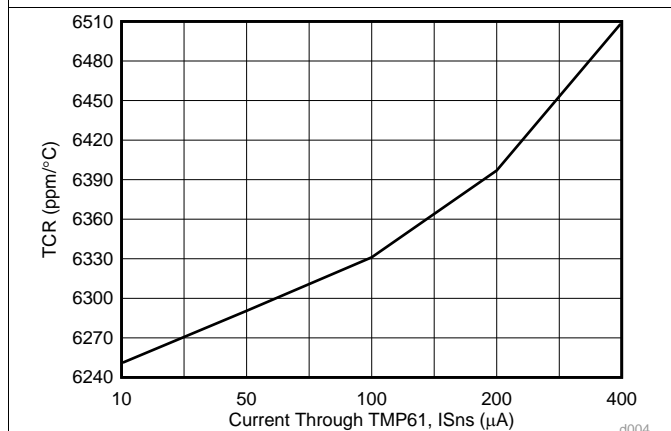
TMP61: $I_{\text{Bias}} = 10, 100, 200,$ and $400 \mu\text{A}$

Figure 1. Resistance vs. Ambient Temperature Using Multiple Bias Currents



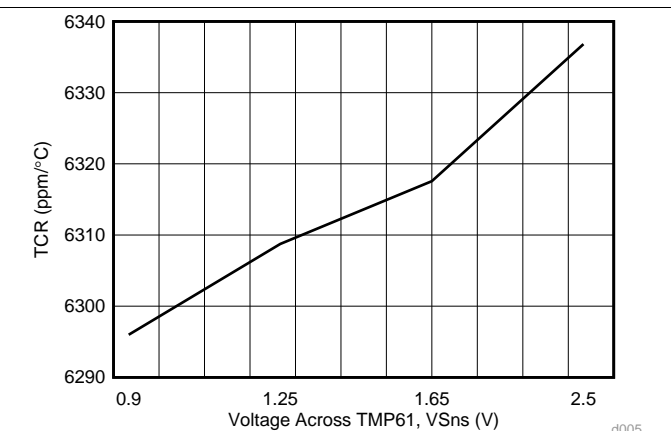
TMP61: $V_{\text{Bias}} = 1.8, 2.5, 3.3,$ and 5.0 V , $R_{\text{Bias}} = 10 \text{ k}\Omega$ with $\pm 0.01\%$ Tolerance

Figure 2. Resistance vs. Ambient Temperature Using Multiple Bias Voltages



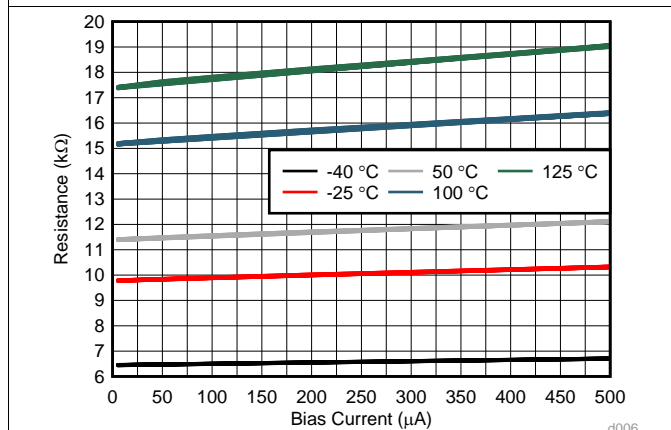
TMP61: $I_{\text{Sns}} = 10, 100, 200,$ and $400 \mu\text{A}$

Figure 3. TCR as a Function of Sense Currents I_{Sns}



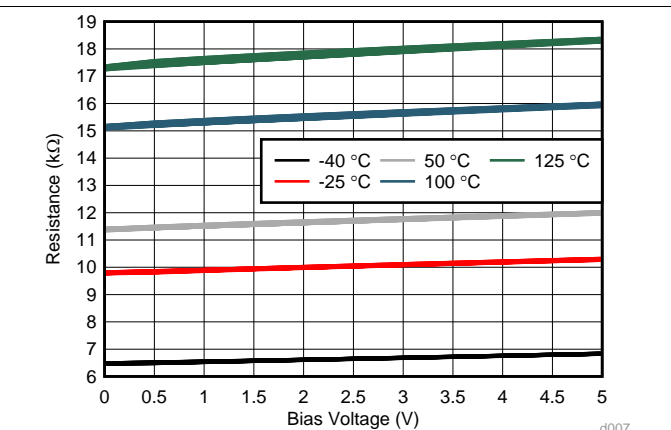
TMP61: $V_{\text{Sns}} = 1.8, 2.5, 3.3,$ and 5.0 V , $R_{\text{Bias}} = 10 \text{ k}\Omega$ with $\pm 0.01\%$ Tolerance

Figure 4. TCR as a Function of Sense Voltages, V_{Sns}



TMP61: $T_A = -40^\circ\text{C}, 25^\circ\text{C}, 50^\circ\text{C}, 100^\circ\text{C},$ and 125°C

Figure 5. Supply Dependence R vs. I_{Bias}

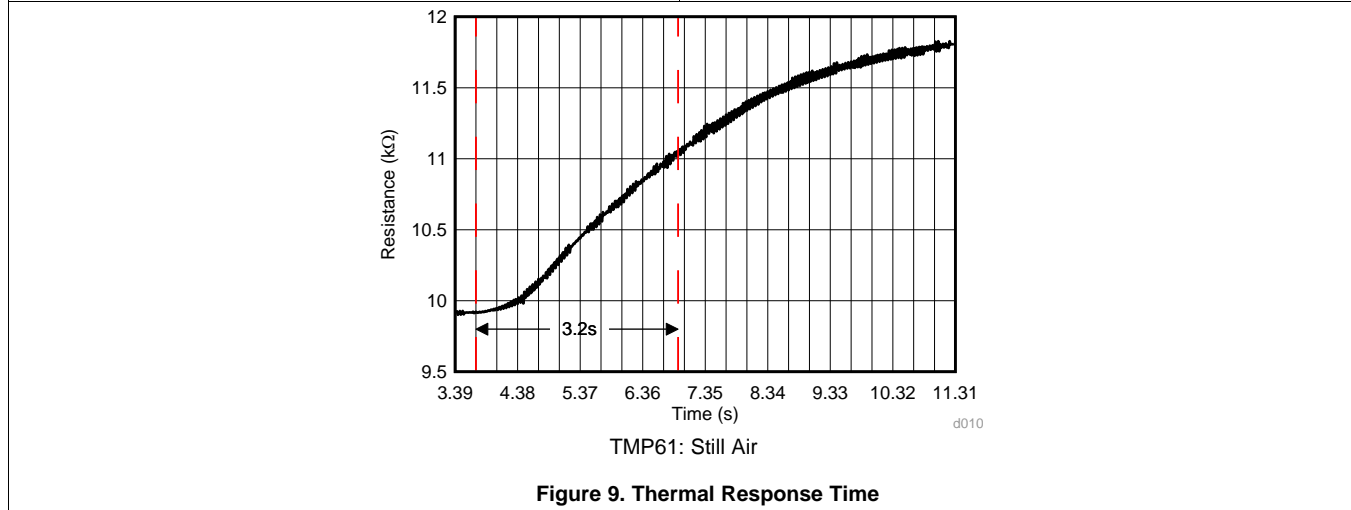
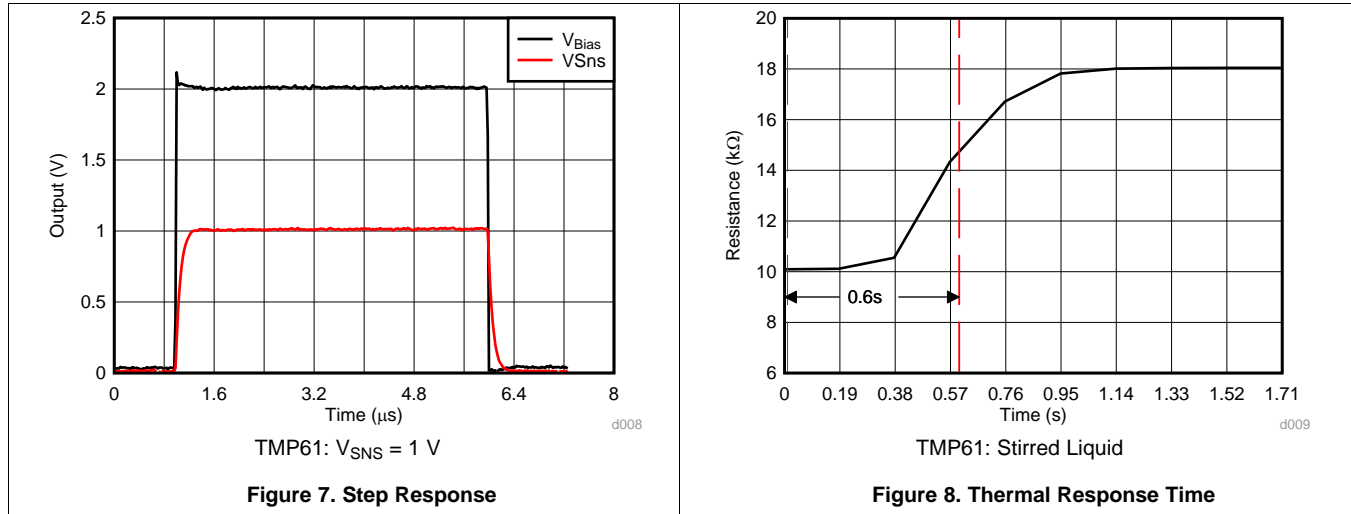


TMP61: $T_A = -40^\circ\text{C}, 25^\circ\text{C}, 50^\circ\text{C}, 100^\circ\text{C},$ & 125°C , $R_{\text{Bias}} = 10 \text{ k}\Omega$ with $\pm 0.01\%$ Tolerance

Figure 6. Supply Dependence R vs. V_{Bias}

Typical Characteristics (continued)

at $T_A = 25^\circ\text{C}$, (unless otherwise noted)



8 Detailed Description

8.1 Overview

The TMP61xx series of Silicon Linear Thermistors has a linear positive temperature coefficient (PTC) that results in a uniform and consistent temperature coefficient of resistance (TCR) across a wide operating temperature range. They are suitable for use for temperature measurement, protection, compensation, and control systems. Compared to traditional NTC thermistors, the TMP61xx series of devices offers enhanced linearity and consistent sensitivity across the full temperature range. They also have robust performance due to their immunity to environmental variation and their built-in fail-safe behavior at high temperatures. These devices are currently available in 2-pin, DEC surface-mount, 0402 footprint compatible packages and 2-pin LPG through-hole, mini-sized transistor-outline TO-92S packages.

8.2 Functional Block Diagram

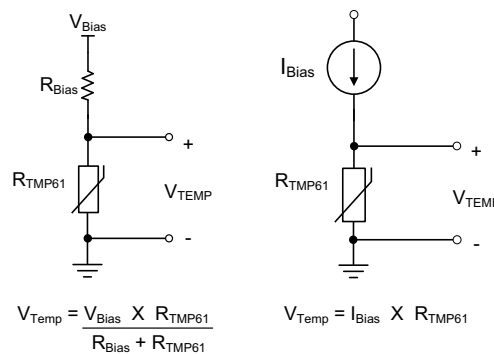


Figure 10. Typical Implementation Circuits

8.3 Feature Description

As shown in [Figure 1](#) and [Figure 2](#), the TMP61xx has a good linear behaviour across the whole temperature range, but a small non-linearity can be observed as well as supply dependence as shown in [Figure 3](#) and [Figure 4](#). The TMP61xx is fabricated using a special silicon process where the device key characteristics—the temperature coefficient of resistance (TCR) and nominal resistance (R25)—are controlled using the doping level and active region area. Also, the TMP61xx has an active area and a substrate due to the polarized terminals of the device. The positive terminal should be connected to the highest potential while the negative terminal (which is tied to the substrate internally) should be connected to the lowest potential. [Equation 1](#) and [Equation 2](#) can help the user approximate the device resistance and TCR. [Table 1](#) and [Table 2](#) show the typical resistances, resistance spread, and maximum expected error across temperature using a direct Ideal bias current or an ideal voltage bias in a divider circuit.

R (Ω)

$$\approx 8504.85 + 55.08 T + 0.17 T^2$$

where

- T is the temperature of interest (1)

$$\text{TCR (ppm/°C)} = (R_{T2} - R_{T1}) / ((T_2 - T_1) \times R_{(T_2+T_1)/2}) \quad (2)$$

Below are the definitions of the key terms used throughout this document:

- I_{Sns} : Current flowing through TMP61
- V_{Sns} : Voltage across the two terminals of TMP61
- I_{Bias} : Current supplied by the biasing circuit
- V_{Bias} : Voltage supplied by the biasing circuit
- V_{Temp} : Output voltage corresponding to the measured temperature. Note that this is different than V_{Sns} in case of a voltage divider circuit with TMP61 in the high side and V_{Temp} is taken across R_{Bias} .

Feature Description (continued)
Table 1. TMP61 Transfer Table Using an Ideal I_{Bias} of 200 μ A

TEMPERATURE (°C)	Resistance (Ω)			$\Delta R/\Delta T$ ($\Omega/^\circ\text{C}$)	Temperature Error ⁽¹⁾⁽²⁾ (°C)
	Min.	Typ.	Max.		
-40	6445	6543	6641	42	2.32
-35	6657	6759	6860	44	2.30
-30	6879	6983	7088	46	2.29
-25	7109	7217	7325	48	2.28
-20	7347	7459	7571	49	2.27
-15	7594	7710	7825	51	2.27
-10	7849	7968	8088	53	2.27
-5	8112	8235	8359	54	2.28
0	8425	8510	8595	56	1.53
5	8704	8792	8880	57	1.53
10	8992	9083	9173	59	1.54
15	9287	9381	9475	60	1.55
20	9590	9687	9783	62	1.56
25	9900	10000	10100	63	1.58
30	10218	10321	10424	65	1.59
35	10544	10650	10757	67	1.60
40	10877	10987	11097	68	1.61
45	11218	11332	11445	70	1.62
50	11568	11685	11801	71	1.64
55	11925	12045	12166	73	1.65
60	12291	12415	12539	75	1.66
65	12665	12792	12920	76	1.67
70	13047	13179	13311	78	1.69
75	13371	13574	13778	80	2.55
80	13769	13979	14188	82	2.56
85	14177	14393	14608	84	2.58
90	14594	14816	15038	86	2.59
95	15021	15250	15479	88	2.61
100	15458	15694	15929	90	2.62
105	15906	16148	16391	92	2.63
110	16365	16614	16863	94	2.64
115	16835	17091	17348	97	2.65
120	17317	17581	17844	99	2.66
125	17811	18082	18353	102	2.67

(1) Assuming ideal current source

(2) Table defined based on 4th order equation

Table 2. TMP61 Transfer Table Using a Voltage Divider With an Ideal V_{Bias} of 2.5 V and R_{Bias} of 10 k Ω With $\pm 0.01\%$ Tolerance

TEMPERATURE (°C)	Resistance (Ω) ⁽¹⁾			$\Delta R/\Delta T$ ($\Omega/^\circ\text{C}$)	Temperature Error ⁽²⁾ (°C)
	Min.	Typ.	Max.		
-40	6411	6508	6606	41	2.39
-35	6617	6717	6818	43	2.35
-30	6833	6937	7041	45	2.32

(1) Table defined based on 4th order equation

(2) Assuming ideal voltage source, 10k Ω with $\pm 0.01\%$ R_{Bias}

Table 2. TMP61 Transfer Table Using a Voltage Divider With an Ideal V_{Bias} of 2.5 V and R_{Bias} of 10 k Ω With $\pm 0.01\%$ Tolerance (continued)

TEMPERATURE (°C)	Resistance (Ω) ⁽¹⁾			$\Delta R/\Delta T$ ($\Omega/^\circ\text{C}$)	Temperature Error ⁽²⁾ (°C)
	Min.	Typ.	Max.		
-25	7058	7165	7273	47	2.30
-20	7293	7404	7515	49	2.29
-15	7536	7651	7765	50	2.28
-10	7788	7906	8025	52	2.28
-5	8048	8170	8293	54	2.29
0	8358	8442	8527	55	1.53
5	8635	8722	8809	57	1.54
10	8920	9010	9100	58	1.55
15	9212	9305	9398	60	1.56
20	9511	9607	9703	61	1.57
25	9817	9916	10016	63	1.58
30	10131	10233	10335	64	1.60
35	10451	10557	10662	65	1.61
40	10779	10888	10997	67	1.63
45	11113	11226	11338	68	1.64
50	11455	11571	11687	70	1.66
55	11804	11923	12043	71	1.67
60	12161	12283	12406	73	1.69
65	12524	12651	12777	74	1.70
70	12896	13026	13156	76	1.72
75	13208	13409	13610	77	2.60
80	13593	13800	14007	79	2.62
85	13987	14200	14413	81	2.64
90	14390	14609	14828	83	2.65
95	14801	15026	15252	84	2.67
100	15222	15453	15685	86	2.68
105	15652	15890	16129	88	2.70
110	16093	16338	16583	91	2.71
115	16544	16796	17048	93	2.72
120	17006	17265	17524	95	2.73
125	17480	17746	18012	97	2.73

8.4 Device Functional Modes

The device has one mode of operation that applies when operated within the [Recommended Operating Conditions](#).

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

The TMP61 is a positive temperature coefficient (PTC) linear silicon thermistor. The device behaves like a temperature-dependent resistor, and may be configured in a variety of ways to monitor temperature based on the system-level requirements. The TMP61 has a nominal resistance at 25°C (R_{25}) of 10 kΩ with ±1% maximum tolerance, a maximum operating voltage of 5.5 V (V_{Sns}), and maximum supply current of 400 μA (I_{Sns}). This device may be used in a variety of applications to monitor temperature close to a heat source with the very small DEC package option compatible with the typical 0402 (inch) footprint. Some of the factors that influence the total measurement error include the ADC resolution (if applicable), the tolerance of the bias current or voltage, the tolerance of the bias resistance in the case of a voltage divider configuration, and the location of the sensor with respect to the heat source.

9.2 Typical Application

9.2.1 Thermistor Biasing Circuits

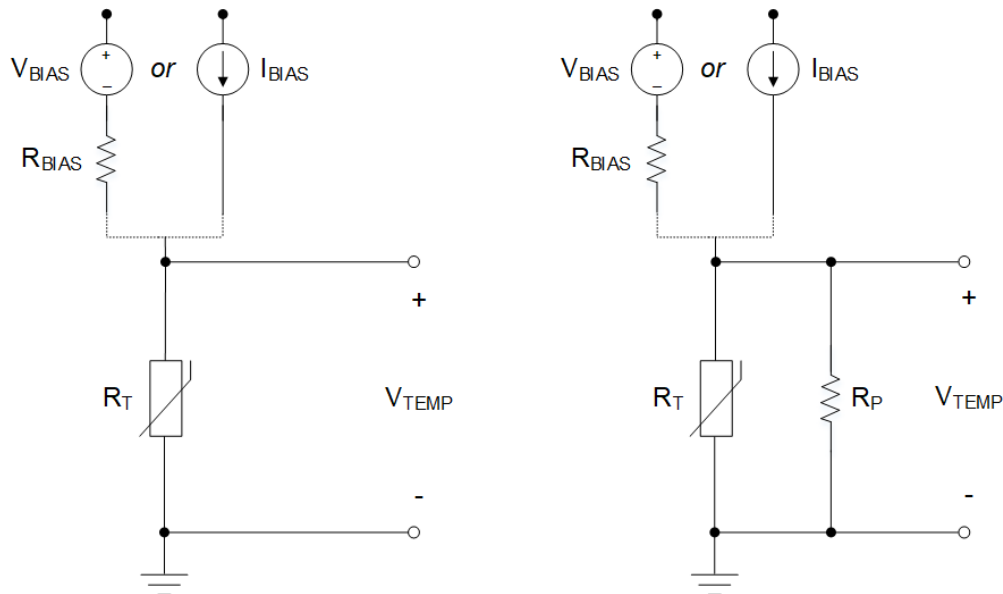


Figure 11. Biasing Circuit Implementations With Linear Thermistor (Left) vs. Non-Linear Thermistor (Right)

9.2.1.1 Design Requirements

Existing thermistors, in general, have a non-linear temperature vs. resistance curve. To linearize the thermistor response, a voltage linearization circuit using a voltage divider configuration is used or a resistance linearization circuit may be used by adding another resistance in parallel with the thermistor, R_P . Figure 11 highlights the two implementations, where R_T is the thermistor resistance. To generate an output voltage across the thermistor, one can use either a voltage divider circuit with the thermistor placed at either the high side (close to supply) or low side (close to ground), depending on the desired voltage response (negative or positive). Additionally, the resistor can be biased directly using a precision current source (yielding the highest accuracy and voltage gain).

Typical Application (continued)

It is common to use a voltage divider with thermistors because of its simple implementation and lower cost. The TMP61, on the other hand, has a linear positive temperature coefficient (PTC) of resistance such that the voltage measured across it increases linearly with temperature. As such, the need for linearization circuits is no longer a requirement, and a simple current source or a voltage divider circuit can be used to generate the temperature voltage.

This output voltage can be interpreted using a comparator against a voltage reference to trigger a temperature trip point, tied directly to an ADC to monitor temperature across a wider range, or used as feedback input for an active feedback control circuit.

The voltage across the TMP61 can be translated to temperature using either a lookup table method (LUT) or a fitting polynomial, $V(T)$, as described in Equation 3. The temperature voltage must first be digitized using an ADC. The necessary resolution of this ADC is dependent on the biasing method used. Additionally, for best accuracy, the bias voltage (V_{BIAS}) should be tied to the reference voltage of the ADC to create a measurement where the difference in tolerance between the bias voltage and the reference voltage are cancelled. A low-pass filter may also be implemented to reject system level noise, and should be placed as close to the ADC input as possible.

9.2.1.2 Detailed Design Procedure

The resistive circuit divider method produces an output voltage (V_{TEMP}) scaled according to the bias voltage (V_{BIAS}). When V_{BIAS} is also used as the reference voltage of the ADC, any fluctuations or tolerance error due to the voltage supply will be canceled and will not affect the temperature accuracy. This type of configuration is shown in Figure 12. Equation 3 describes the output voltage (V_{TEMP}) based on the variable resistance of the TMP61 (R_{TMP61}) and bias resistor (R_{BIAS}). The ADC code corresponding to that output voltage, ADC full-scale range, and ADC resolution is given in Equation 4.

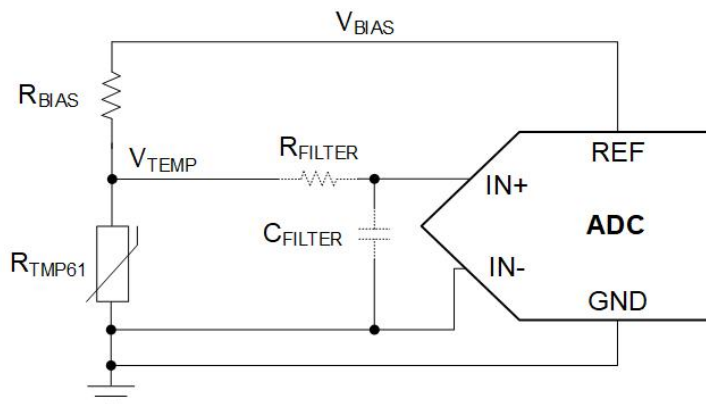


Figure 12. TMP61 Voltage Divider with an ADC.

$$V_{TEMP} = V_{BIAS} \times \left(\frac{R_{TMP61}}{R_{TMP61} + R_{BIAS}} \right) \quad (3)$$

$$ADC \text{ Code} = \frac{V_{TEMP}}{FSR} 2^n$$

where

- FSR is the full-scale range of the ADC, which is the voltage at REF to GND (V_{REF})
 - n is the resolution of the ADC
- (4)

Equation 5 shows whenever $V_{REF} = V_{BIAS}$, V_{BIAS} will cancel out.

$$ADC \text{ Code} = \frac{V_{BIAS} \times \left(\frac{R_{TMP61}}{R_{TMP61} + R_{BIAS}} \right)}{V_{BIAS}} 2^n = \left(\frac{R_{TMP61}}{R_{TMP61} + R_{BIAS}} \right) 2^n \quad (5)$$

Typical Application (continued)

A polynomial equation or a LUT can be used to extract the temperature reading based on the ADC code read in the microcontroller.

The cancellation of V_{BIAS} is a benefit to using a voltage-divider (ratio-metric approach), but the sensitivity of the output voltage of the divider circuit cannot be increased very much. Therefore, not all of the ADC codes will be used due to the small voltage output range compared to the FSR. This application is very common, however, and is simple to implement.

A current source-based circuit, like the one shown in [Figure 13](#), can be used to get better control over the sensitivity of the output voltage and achieve higher accuracy. In this case, the output voltage is simply $V = I \times R$. For example, if a current source of $400 \mu\text{A}$ is used with the TMP61, the output voltage will span approximately 5.5 V and will have a gain up to 40 mV/C . Having control over the voltage range and sensitivity allows for full utilization of the ADC codes and full-scale range. Based on the bias current, the temperature voltage is shown in [Figure 14](#). Similar to the ratio-metric approach above, if the ADC has built-in current source that share the same bias as the reference voltage of the ADC, the tolerance of the supply current will be cancelled. In this case, a precision ADC is not required. This method yields the best accuracy, but can increase the system implementation cost.

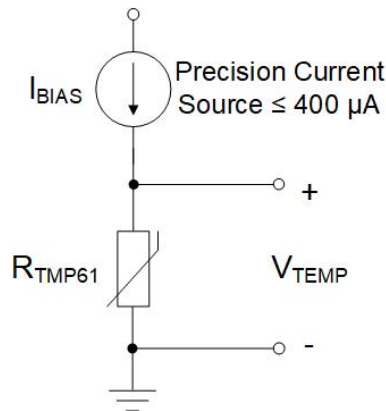


Figure 13. TMP61 Biasing Circuit With Current Source

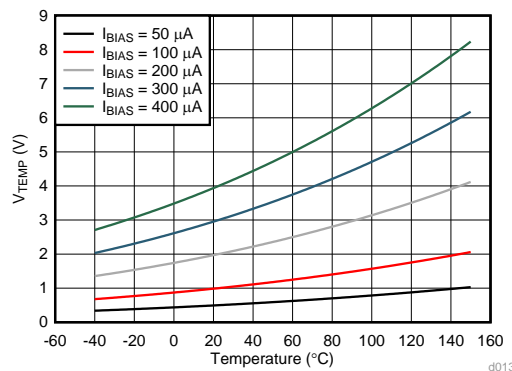


Figure 14. TMP61 Temperature Voltage With Varying Current Sources

In comparison to the non-linear NTC thermistor in a voltage divider, the TMP61 has an enhanced linear output characteristic. The two voltage divider circuits with and without a linearization parallel resistor, R_P , is shown in [Figure 15](#). For example, consider an example where $V_{BIAS} = 5 \text{ V}$, $R_{BIAS} = 10 \text{ k}\Omega$, and a parallel resistor (R_P) is used with the NTC thermistor (R_{NTC}) to linearize the output voltage with an additional $10\text{-k}\Omega$ resistor. The output characteristics of the voltage dividers are shown in [Figure 16](#). The TMP61 produces a linear curve across the entire temperature range while the NTC curve is only linear across a small temperature region. When the parallel resistor (R_P) is added to the NTC circuit, the added resistor makes the curve much more linear, but greatly affects the output voltage range.

Typical Application (continued)

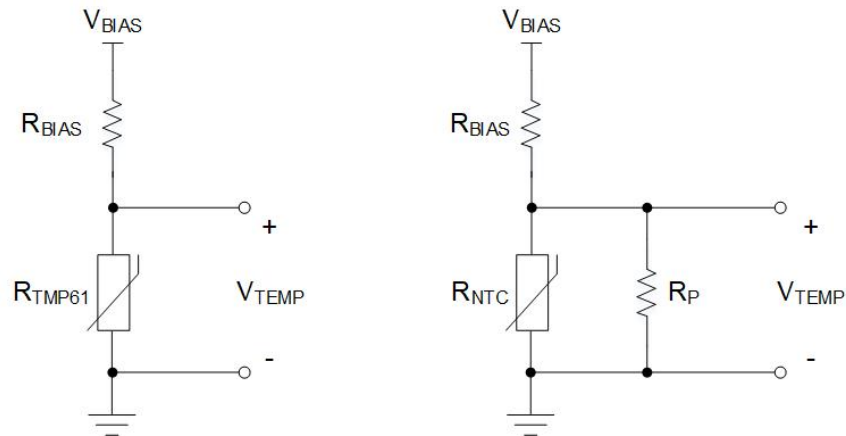


Figure 15. TMP61 vs. NTC With Linearization Resistor (R_P) Voltage Divider Circuits

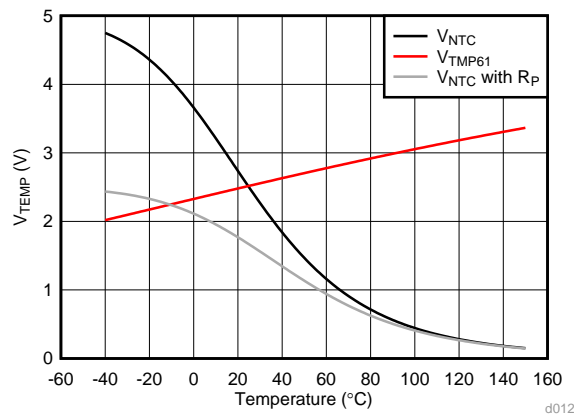


Figure 16. NTC With and Without a Linearization Resistor vs. TMP61 Temperature Voltages

9.2.1.2.1 Thermal Compensation

The TMP61 can be used to compensate for components within systems whose characteristics vary over temperature. For example, resistors will change with temperature based on their specified temperature coefficient. In certain systems where these resistors are included in the feedback loop, the performance over temperature may be greatly affected by the changes in resistance. Examples include components like those in control systems within the feedback loop or linear dropout regulators with feedback resistors and solenoids or coils with varying impedance. One implementation is to put the TMP61 in a feedback loop to compensate for temperature drift, along with other resistive components to better control the temperature coefficient (α) of the compensation circuit.

Equation 6 can describe this type of circuit:

$$R(T) = R(T_0) \times (1 + \alpha \Delta T)$$

where

- $R(T_0)$ is the resistance
- the temperature coefficient, α , is specified (25°C)
- the change in temperature, ΔT , is the temperature of interest, T , minus T_0 (25°C)

This circuit is shown in Figure 17.

Typical Application (continued)

$$R_{\text{total}} = R_S + \frac{R_{\text{TMP61}} \times R_P}{R_{\text{TMP61}} + R_P} \quad (7)$$

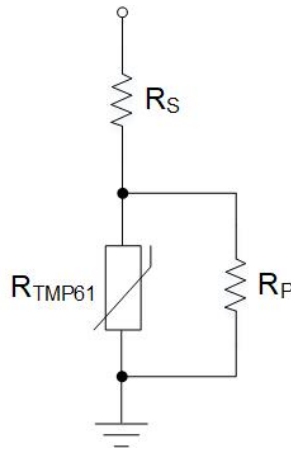


Figure 17. TMP61 Thermal Compensation Circuit

9.2.1.2.2 Thermal Protection With Comparator

Thermal protection can be programmed using the TMP61, a voltage reference, and a comparator. As shown in Figure 18, the output of the comparator will remain low until the voltage of the thermistor divider, with R_{BIAS} and R_{TMP61} , rises above the threshold voltage, set by R_1 and R_2 . Then the output will go high, signaling an overtemperature warning signal. Hysteresis can also be useful to program when the output will return low, so that the output does not continuously toggle around the threshold. Either a comparator with built-in hysteresis or feedback resistors may be used.

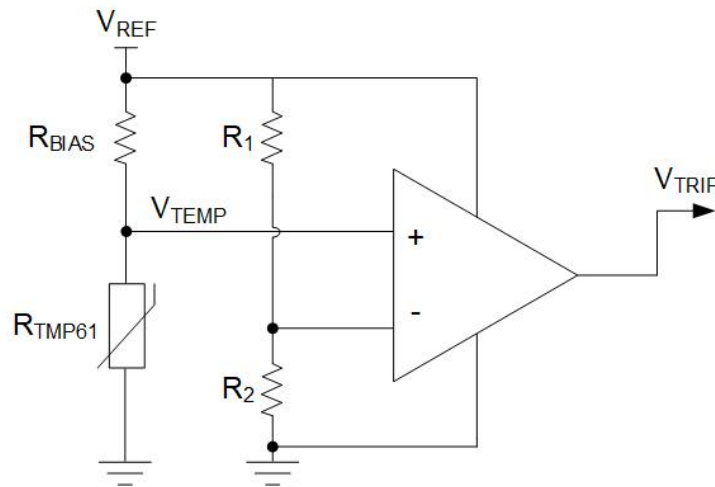


Figure 18. Temperature Switch Using TMP61 Voltage Divider and a Comparator

9.2.1.2.3 Thermal Foldback

One application that uses the output voltage of the TMP61 in active control circuit is thermal foldback. This is performed to reduce, or fold back, the current driving a string of LEDs, for example. At high temperatures, the LEDs begin to heat up due to environmental conditions and self-heating. Thus, at a certain temperature threshold based on the LED's safe operating area, the driving current must be reduced to cool down the LEDs and prevent thermal runaway. The TMP61 voltage output increases with temperature, when it is in the lower position of the voltage divider, and provides a response that can be used to fold back the current. Typically, the current is held at a specified level until a high temperature is reached, known as the knee point, where the current must be

Typical Application (continued)

rapidly reduced. To better control the temperature/voltage sensitivity of the TMP61, a rail-to-rail operational amplifier is used. In the example shown in Figure 19, the temperature “knee” where the foldback begins is set by the reference voltage (2.5 V) at the positive input, and the feedback resistors set the response of the foldback curve. The foldback knee point may be chosen based on the output of the voltage divider and the corresponding temperature from Equation 8 like 110°C, for example. A buffer is used in-between the voltage divider with R_{TMP61} and the input to the op amp to prevent loading and variations in V_{TEMP} .

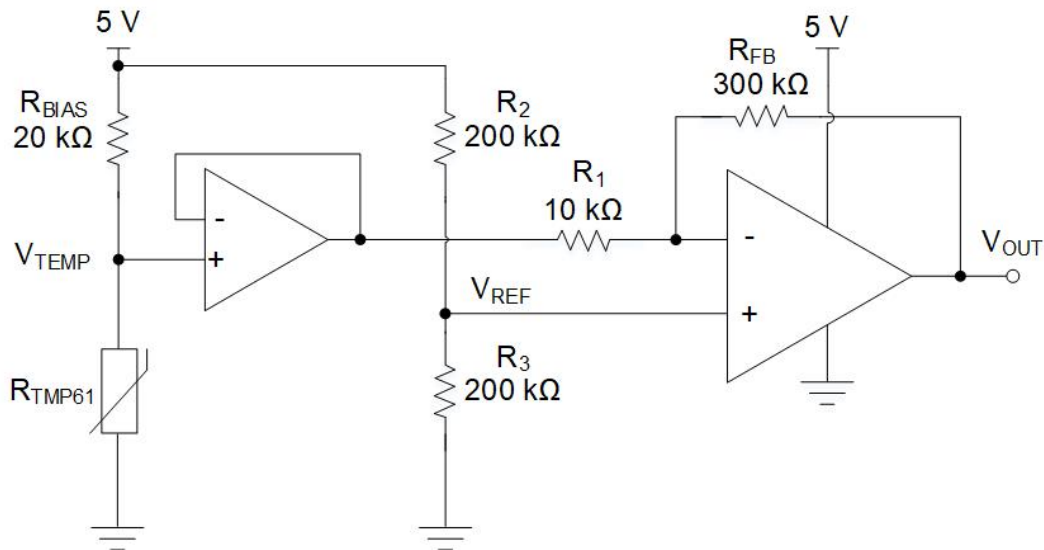


Figure 19. Thermal Foldback Using TMP61 Voltage Divider and a Rail-to-Rail Op Amp

The op amp will remain high as long as the voltage output is below V_{REF} . When the temperature goes above 110°C, then the output will swing low to the 0-V rail of the op amp. The rate at which the foldback occurs is dependent on the feedback network, R_{FB} and R_1 , which varies the gain of the op amp, G , given by Equation 9. This in return controls the voltage/temperature sensitivity of the circuit. This voltage output is fed into a LED driver IC that will adjust output current accordingly. The final output voltage used for thermal foldback is V_{OUT} , and is given in Equation 10. In this example where the knee point is set at 110°C, the output voltage curve is as shown in Figure 20.

$$V_{TEMP} = V_{BIAS} \times \left(\frac{R_{TMP61}}{R_{TMP61} + R_{BIAS}} \right) \quad (8)$$

$$G = \frac{R_{FB}}{R_1} \quad (9)$$

$$V_{OUT} = -G \times V_{TEMP} + (1 + G) \times V_{REF} \quad (10)$$

Typical Application (continued)

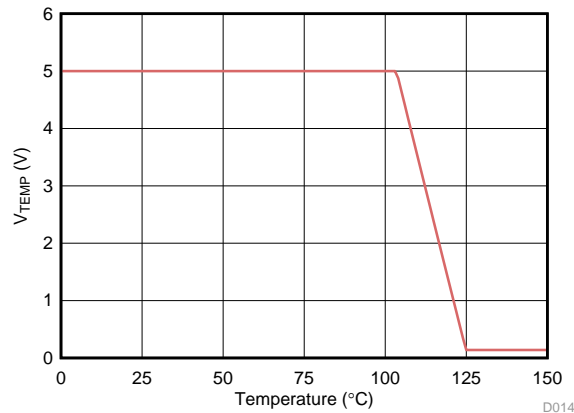


Figure 20. Thermal Foldback Voltage Output Curve

9.2.1.3 Application Curve

The TMP61 accuracy varies depending on the selected biasing circuit. This variation can be seen in Figure 21. V_{TEMP} is shown with either V_{BIAS} at 2 V in a resistor divider circuit (R_{BIAS} = 10 kΩ ±1%) or I_{BIAS} at 200 μA. Supply sources used are assumed to be ideal. The best accuracy is achieved using a direct current bias method.

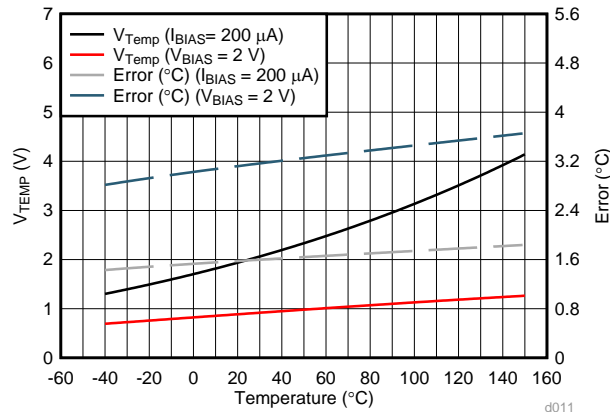


Figure 21. TMP61 Voltage Output and Temperature Error Based on the Bias Method

10 Power Supply Recommendations

The maximum recommended operating voltage of the TMP61 is 5.5 V (V_{SNS}), and the maximum current through the device is 400 μA (I_{SNS}).

11 Layout

11.1 Layout Guidelines

The layout of the TMP61 is similar to that of a passive component. If the device is biased with a current source, the positive pin 2 will be connected to the source, while the negative pin 1 will be connected to ground. If the circuit is biased with a voltage source, and the device is placed on the lower side of the resistor divider, V₋ will be connected to ground and V₊ will be connected to the output, V_{TEMP}. If the device is placed on the upper side of the divider, V₊ is connected to the voltage source and V₋ is connected to the output voltage, V_{TEMP}. Device layout is as shown in Figure 22.

11.2 Layout Examples

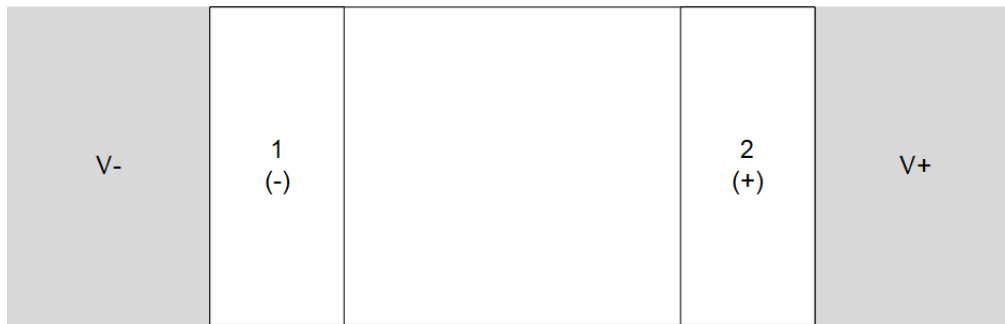


Figure 22. Recommended Layout: DEC Package

12 Device and Documentation Support

12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

TI E2E™ Online Community *TI's Engineer-to-Engineer (E2E) Community*. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

Design Support *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

12.3 Trademarks

E2E is a trademark of Texas Instruments.
All other trademarks are the property of their respective owners.

12.4 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

12.5 Glossary

[SLYZ022](#) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
PTMP6131LPGM	PREVIEW	TO-92	LPG	2	3000	TBD	Call TI	Call TI	-65 to 150		
TMP6131DECR	ACTIVE	X1SON	DEC	2	10000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-65 to 150	EL	Samples
TMP6131DECT	ACTIVE	X1SON	DEC	2	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-65 to 150	EL	Samples
TMP6131DYAR	PREVIEW			2	3000	TBD	Call TI	Call TI	-65 to 150		
TMP6131DYAT	PREVIEW			2	250	TBD	Call TI	Call TI	-65 to 150		
TMP6131LPG	PREVIEW	TO-92	LPG	2	1000	TBD	Call TI	Call TI	-65 to 150		
TMP6131LPGM	PREVIEW	TO-92	LPG	2	3000	TBD	Call TI	Call TI	-65 to 150		

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSELETE: TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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TAPE AND REEL INFORMATION

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

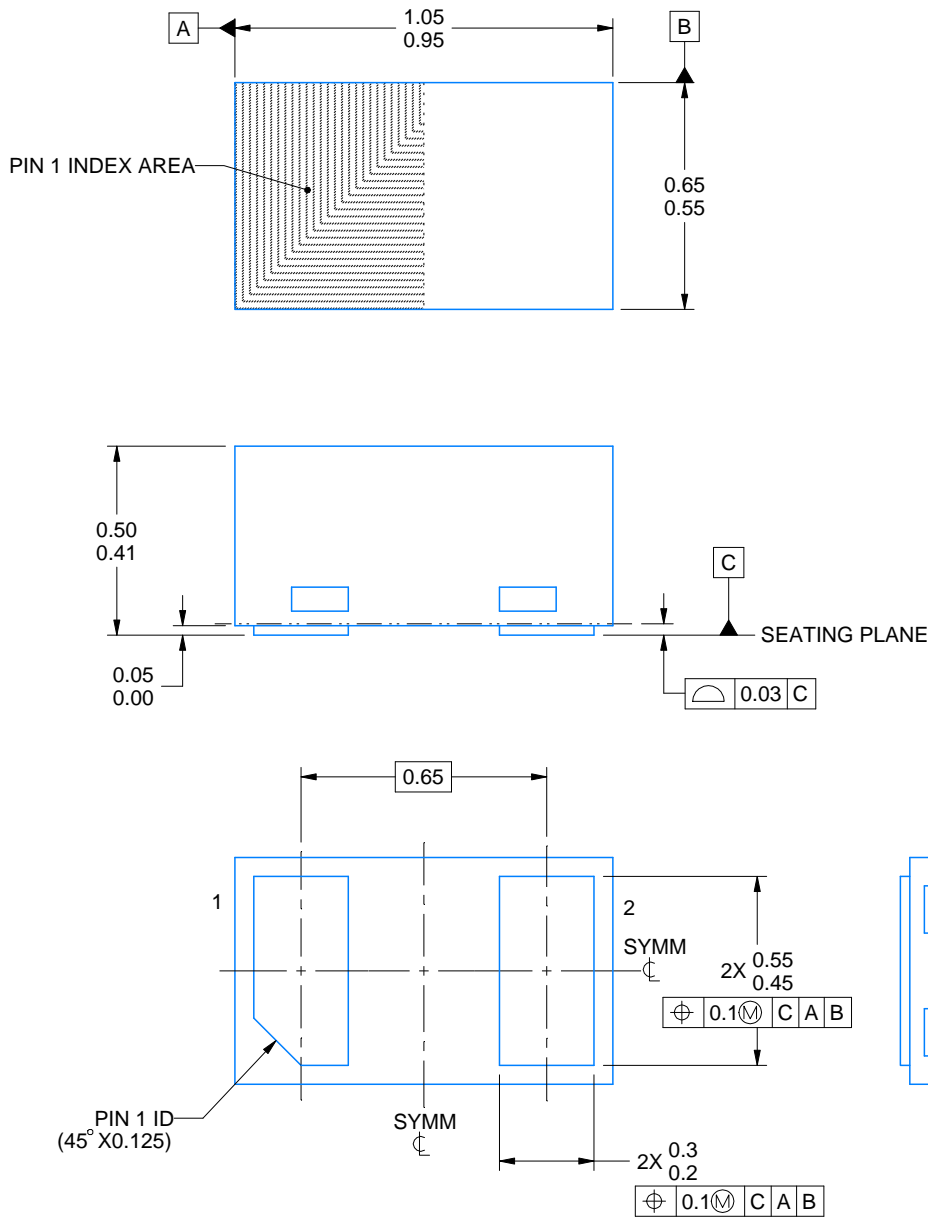
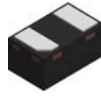

*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TMP6131DECR	X1SON	DEC	2	10000	178.0	8.4	0.7	1.15	0.47	2.0	8.0	Q1
TMP6131DECT	X1SON	DEC	2	250	178.0	8.4	0.7	1.15	0.47	2.0	8.0	Q1

TAPE AND REEL BOX DIMENSIONS


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TMP6131DECR	X1SON	DEC	2	10000	205.0	200.0	33.0
TMP6131DECT	X1SON	DEC	2	250	205.0	200.0	33.0



4224506/A 08/2018

NOTES:

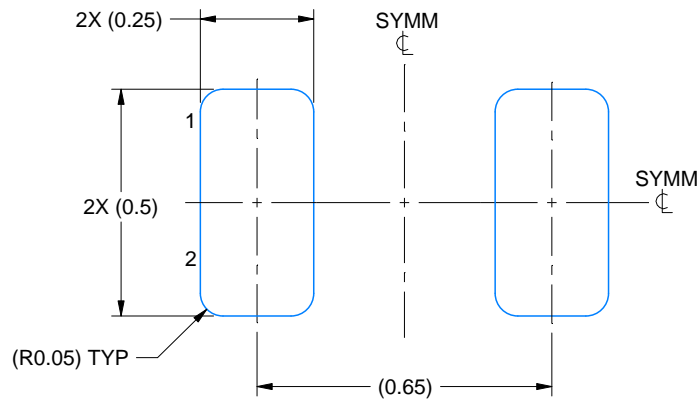
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

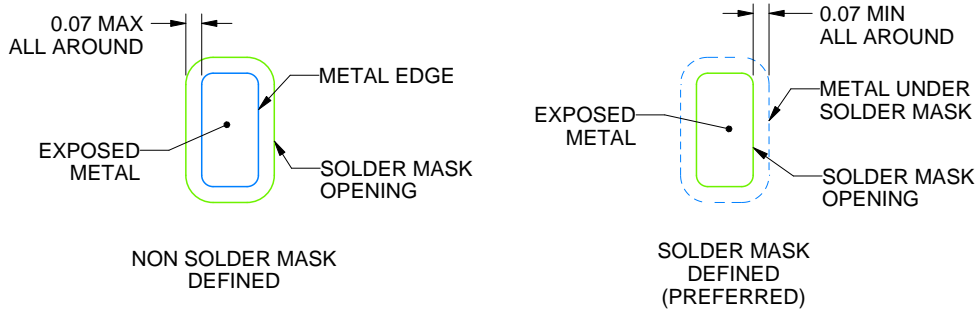
DEC0002A

X1SON - 0.5 mm max height

PLASTIC SMALL OUTLINE - NO LEAD



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE:60X



SOLDER MASK DETAILS

4224506/A 08/2018

NOTES: (continued)

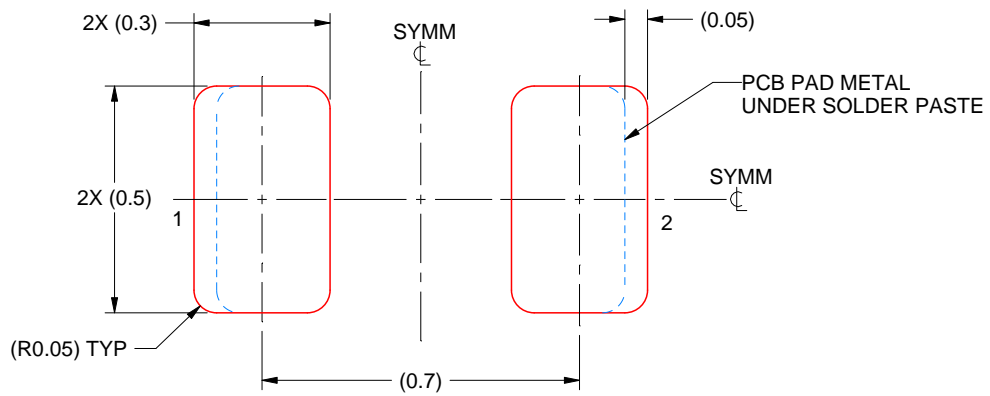
3. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slue271).
4. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

DEC0002A

X1SON - 0.5 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

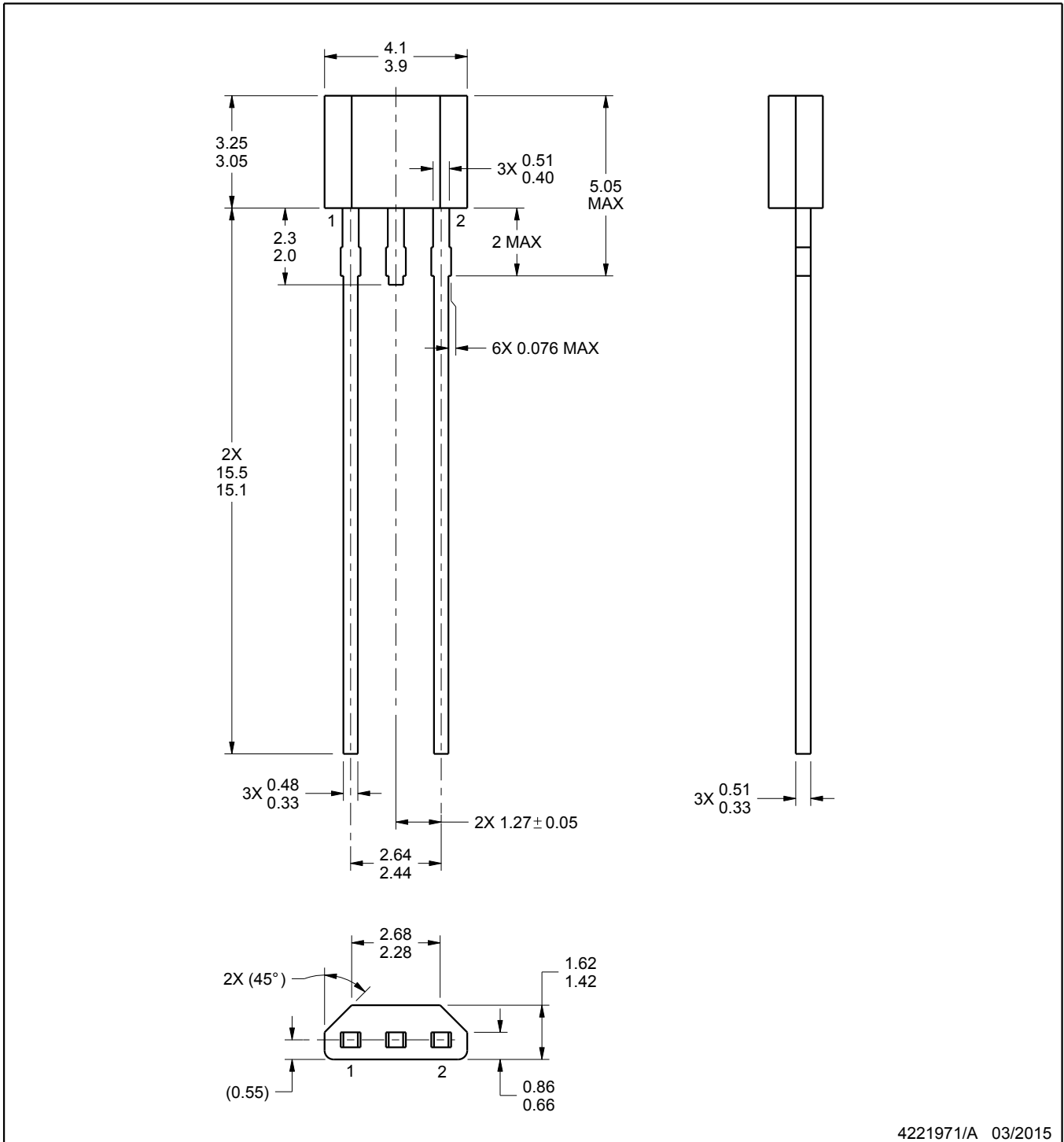


SOLDER PASTE EXAMPLE
BASED ON 0.1 mm THICK STENCIL
SCALE:60X

4224506/A 08/2018

NOTES: (continued)

5. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.



4221971/A 03/2015

NOTES:

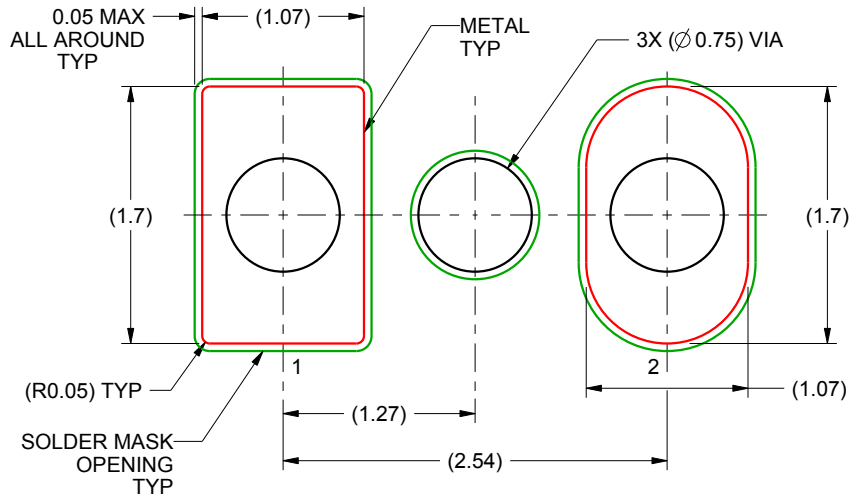
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

EXAMPLE BOARD LAYOUT

LPG0002A

TO-92 - 5.05 mm max height

TO-92



LAND PATTERN EXAMPLE
NON-SOLDER MASK DEFINED
SCALE:20X

4221971/A 03/2015

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