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bq500215 SLUSBZ1A-OCTOBER 2014-REVISED NOVEMBER 2014

# bq500215 WPC v1.1 Compliant Wireless Power Transmitter Manager With Proprietary 10-W Power Delivery

Technical

Documents

## 1 Features

- Qi-Certified WPC v1.1 Solution for 5-W Operation and Proprietary 10-W Charging Capability With TI bq51025 Wireless Power Receiver
  - Proprietary Authentication Protocol With TI bq51025 Receiver
  - Faster Charging Time
  - Compatible With Standard 5-W WPC Receivers
- 12-V Input, Fixed Frequency, Rail Voltage Control Architecture
- Conforms to Wireless Power Consortium (WPC)
   A29 Transmitter Type Specification
- Enhanced Foreign Objection Detection (FOD) Implementation With FOD Ping that Detects Metal Objects Prior to Power Transfer
- Low Standby Power During Idle and 'Charge Complete'
- 10 Configurable LED Modes Indicate Charging State and Fault Status
- Digital Demodulation Reduces Components and Simplifies Circuitry

## 2 Applications

- WPC v1.1 Wireless Chargers:
  - Qi-Certified Smart Phones, Tablets, and Other Handhelds
  - Point-of-Sale Devices
  - Custom Wireless Power Applications

## 4 Simplified Diagram

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• See www.ti.com/wirelesspower for More Information on TI's Wireless Charging Solutions

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## 3 Description

Tools &

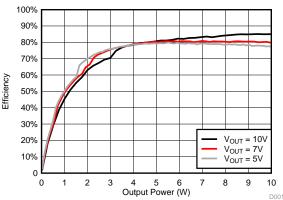
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The bq500215 is a dedicated wireless power digital controller that integrates the logic functions required to control wireless power transfer to a single WPCcompliant receiver. The bq500215 complies with the WPC v1.1 standard for power delivery up to 5 W and uses a proprietary bidirectional communication protocol to allow charging at up to 10 W with the bq51025 wireless power receiver. The bq500215 is an intelligent device that periodically pings the surrounding environment for available devices to be powered, detects if a foreign metal object is present on the charging pad, monitors all communication from the device being wirelessly powered, and adjusts power applied to the transmitter coil per feedback received from the powered device. The bq500215 also manages the fault conditions associated with the power transfer and controls the operating mode status indicator. The bq500215 uses a rail voltage control scheme instead of the traditional frequency control to adjust the amount of power delivered to the receiver.

### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)
bq500215	VQFN (64)	9.00 mm × 9.00 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.



#### Efficiency vs System Output Power With bq51025 Receiver

An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, intellectual property matters and other important disclaimers. PRODUCTION DATA.

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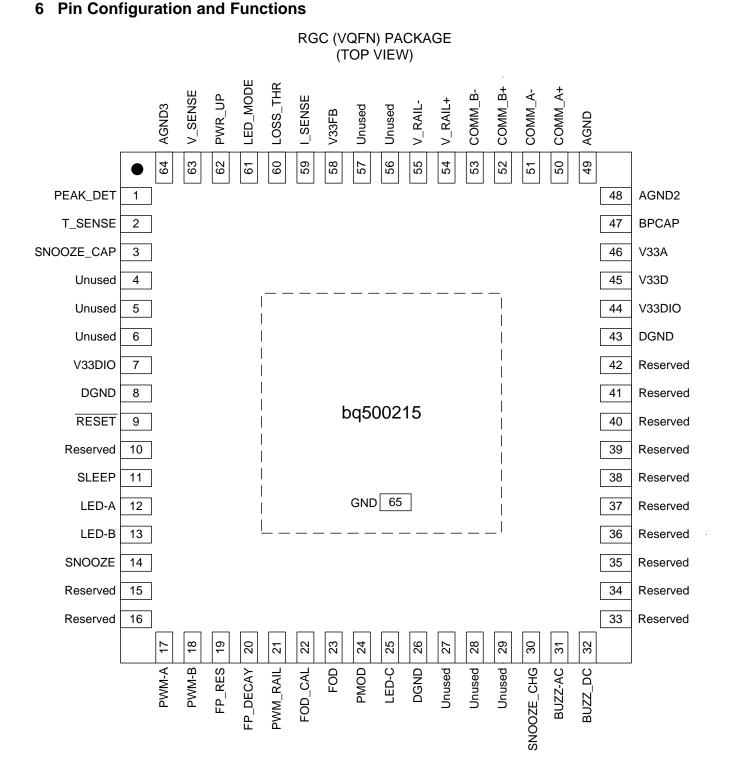
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#### 6 Din Configuration and



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NSTRUMENTS

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PIN I/O DESCRIPTION						
0.	1/0	DESCRIPTION				
1	Ι	Input from peak detect circuit				
2	Ι	Sensor input. Device shuts down when below 1 V. If not used, keep above 1 V by simply connecting to 3.3-V supply				
3	Ι	Indicates wake from SNOOZE (short) or SLEEP (long)				
4	—	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.				
5	_	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.				
6	—	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.				
7	_	3.3-V IO power supply				
8	_	GND				
9	I	Device reset. Use 10- to 100-k $\Omega$ pullup resistor to 3.3-V supply				
10	—	Reserved, leave this pin open				
11	0	Force SLEEP (5 s low power). Connected to 5-s interval circuit				
12	0	Connect to an LED with a 470- $\Omega$ resistor for status indication.				
13	0	Connect to an LED with a 470- $\Omega$ resistor for status indication.				
14	0	Force SNOOZE (500 ms low power)				
15	Ι	Reserved, connect to GND				
16	I/O	Reserved, connect to GND				
17	0	PWM output A, controls one half of the full bridge in a phase-shifted full bridge. Switching dead times must be externally generated.				
18	0	PWM output B, controls other half of the full bridge in a phase-shifted full bridge. Switching dead times must be externally generated.				
19	0	Output to select the FOD ping calibration threshold				
20	0	Output to select the FOD ping calibration threshold				
21	0	PWM control signal for full bridge rail voltage				
22	0	Output to select the FOD calibration				
23	0	Output to select the foreign object detection (FOD) threshold				
24	0	Output to select the PMOD threshold				
25	0	Connect to an LED with a 470- $\Omega$ resistor for status indication.				
26		GND				
27	—	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.				
28	_	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.				
29	_	This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.				
30	0	SNOOZE capacitor charging source. Connected to capacitor				
31	0	AC buzzer output. A 400-ms, 4-kHz AC pulse train when charging begins				
32	0	DC buzzer output. A 400-ms DC pulse when charging begins. This could also be connected to an LED with a $470-\Omega$ resistor.				
33	_	Reserved, leave this pin open				
34		Reserved, leave this pin open				
35	_	Reserved, leave this pin open				
36		Reserved, leave this pin open				
37		Reserved, leave this pin open				
38		Reserved, leave this pin open				
39	_	Reserved, leave this pin open				
40	_	Reserved, connect to $10-k\Omega$ resistor to GND				
11	_	Reserved, leave this pin open				
12	_	Reserved, leave this pin open				
	1       2         3       4         2       3         3       4         5       6         7       3         4       5         6       7         8       9         9       0         1       2         3       4         5       6         7       8         9       0         11       2         12       3         4       5         6       7         8       9         0       1         12       3         4       5         6       7         8       9         0       1         12       3         44       5         5       6         7       8         9       0         1       1         1       1         1       1         1       1	O.       I         1       I         2       I         3       I         4          5          6          7          8          9       I         0          1       O         2       O         3       O         4       O         5       I         6       I/O         7       O         8       O         9       O         10       O         2       O         3       O         4       O         5       O         6          7          8          9          0       O         1       O         1          6          7          8          9          6          7				



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#### **Pin Functions (continued)**

PIN			DECODIDEION			
NAME	NO.	I/O	DESCRIPTION			
V33DIO	44	_	3.3-V IO power supply			
V33D	45	_	Digital core 3.3-V supply. Be sure to decouple with bypass capacitors as close to the part as possible.			
V33A	46		Analog 3.3-V supply. This pin can be derived from V33D supply, decouple with $22-\Omega$ resistor and additional bypass capacitors.			
BPCAP	47		Connect to 1uF bypass capacitors to 3.3V supply and GND			
AGND2	48		GND			
AGND	49		GND			
COMM_A+	50	Ι	Digital demodulation non-inverting input A. Connect parallel to input B+			
COMM_A-	51	Ι	Digital demodulation inverting input A. Connect parallel to input B-			
COMM_B+	52	Ι	Digital demodulation non-inverting input B. Connect parallel to input A+			
COMM_B-	53	Ι	Digital demodulation inverting input B. Connect parallel to input A-			
V_RAIL+	54	Ι	Feedback for full bridge rail voltage control +			
V_RAIL-	55	Ι	Feedback for full bridge rail voltage control –			
Unused	56		This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.			
Unused	57		This pin can be either connected to GND or left open. Connecting to GND can improve layout grounding.			
V33FB	58	Ι	Reserved, leave this pin open			
I_SENSE	59	Ι	Full bridge input current sense			
LOSS_THR	60	Ι	Input for FOD/PMOD calibration and configuration			
LED_MODE	61	Ι	LED mode select			
PWR_UP	62	Ι	First power-up indicator (pull high if unused)			
V_SENSE	63	Ι	Transmitter rail voltage sense			
AGND3	64	_	GND			
EPAD	65	_	Flood with copper GND plane and stitch vias to PCB internal GND plane			

## 7 Specifications

## 7.1 Absolute Maximum Ratings<sup>(1)</sup>

over operating free-air temperature (unless otherwise noted)

	MIN	MAX	UNIT
Voltage applied at V33D to DGND	-0.3	3.6	
Voltage applied at V33A to AGND	-0.3	3.6	V
Voltage applied to any pin <sup>(2)</sup>	-0.3	3.6	

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltages referenced to GND.

## 7.2 Handling Ratings

			MIN	MAX	UNIT
T <sub>stg</sub>	Storage temperatu	-40	150	°C	
V <sub>(ESD)</sub> Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins <sup>(1)</sup>	-2	2	kV	
	Charged device model (CDM), per JEDEC specification JESD22-C101, all pins <sup>(2)</sup>	-750	750	kV	

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V	Supply voltage during operation, V33D, V33A	3.0	3.3	3.6	V
T <sub>A</sub>	Operating free-air temperature range	-40		85	°C
TJ	Junction temperature			125	U

## 7.4 Thermal Information

	THERMAL METRIC <sup>(1)</sup>	bq500215	UNIT
		RGC (64 pins)	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	29.5	
R <sub>0JC(top)</sub>	Junction-to-case (top) thermal resistance	15.1	
$R_{\theta J B}$	Junction-to-board thermal resistance	8.4	°C/W
ΨJT	Junction-to-top characterization parameter	0.2	°C/vv
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	8.3	
R <sub>0JC(bot)</sub>	Junction-to-case (bottom) thermal resistance	1.2	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.



## 7.5 Electrical Characteristics

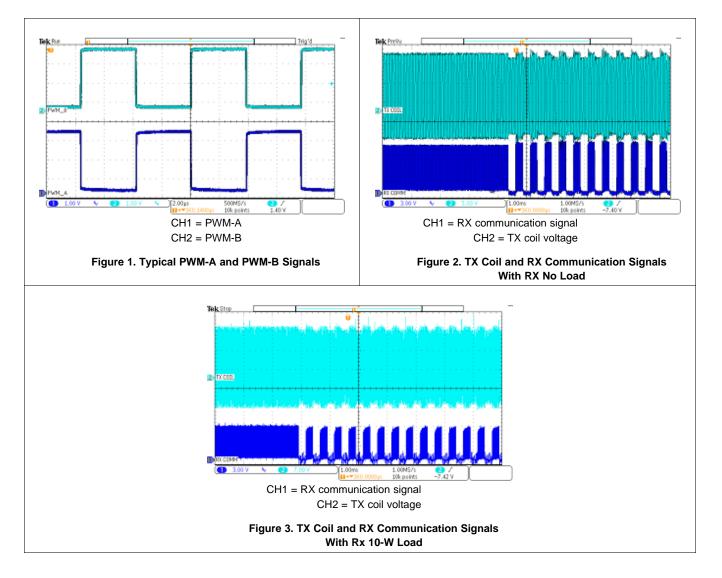
over operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT	
SUPPLY CU	RRENT						
I <sub>V33A</sub>		V33A = 3.3 V		8	15		
I <sub>V33D</sub>	Supply current	V33D = 3.3 V		44	55	mA	
I <sub>Total</sub>		V33D = V33A = 3.3 V		52	70		
EXTERNALI	LY SUPPLIED 3.3 V POWER		1				
V33D	Digital 3.3-V power	$T_A = 25^{\circ}C$	3		3.6	.,	
V33A	Analog 3.3-V power	$T_A = 25^{\circ}C$	3		3.6	V	
V33Slew	3.3-V slew rate	3.3-V slew rate between 2.3 and 2.9 V, V33A = V33D	0.25			V/ms	
DIGITAL DE	MODULATION INPUTS: COMM_A+, COMM	A-, COMM_B+, COMM_B-					
V <sub>CM</sub>	Common mode voltage each pin		-0.15		1.631	V	
COMM+, COMM–	Modulation voltage digital resolution			1		mV	
R <sub>EA</sub>	Input Impedance	Ground reference	0.5	1.5	3	MΩ	
IOFFSET	Input offset current	1-kΩ source impedance	-5		5	μA	
ANALOG IN	PUTS: V_SENSE, I_SENSE, T_SENSE, LED		1				
VADC OPEN	Voltage indicating open pin	LED_MODE, LOSS_THR open	2.37				
V <sub>ADC_SHORT</sub>	Voltage indicating pin shorted to GND	LED_MODE, LOSS_THR shorted to ground			0.36	V	
V <sub>ADC_RANGE</sub>	Measurement range for voltage monitoring	All analog inputs	0		2.5		
INL	ADC integral nonlinearity		-2.5		2.5	mV	
l <sub>ikg</sub>	Input leakage current	3 V applied to pin			100	nA	
R <sub>IN</sub>	Input impedance	Ground reference	8			MΩ	
C <sub>IN</sub>	Input capacitance				10	pF	
DIGITAL INF	PUTS/OUTPUTS						
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 6 mA , V33D = 3 V		DG	ND1 + 0.25		
V <sub>OH</sub>	High-level output voltage	I <sub>OH</sub> = -6 mA , V33D = 3 V	V33D – 0.6 V			.,	
V <sub>IH</sub>	High-level input voltage	V33D = 3 V	2.1		3.6	V	
V <sub>IL</sub>	Low-level input voltage	V33D = 3.5 V			1.4		
I <sub>OH</sub> (MAX)	Output high-source current				4		
I <sub>OL</sub> (MAX)	Output low-sink current				4	mA	
SYSTEM PE	RFORMANCE						
V <sub>RESET</sub>	Voltage where device comes out of reset	V33D pin			2.4	V	
t <sub>RESET</sub>	Pulse duration needed for reset	RESET pin	2			μs	
fsw	Switching frequency (wireless power transfer)			130		kHz	
t <sub>detect</sub>	Time to detect presence of device requesting power				0.5	S	
PWM RAIL							

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## 7.6 Typical Characteristics





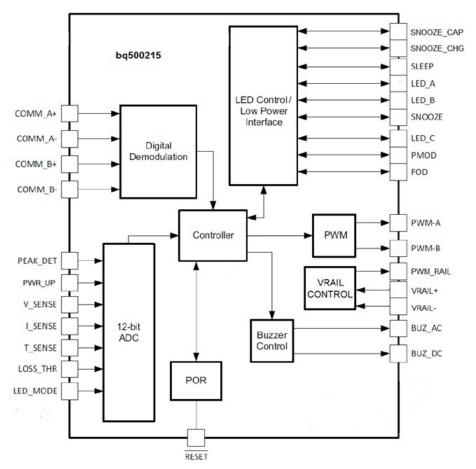
## 8 Detailed Description

## 8.1 Overview

The principle of wireless power transfer is simply an open-cored transformer consisting of a transmitter and receiver coils. The transmitter coil and electronics are typically built into a charger pad and the receiver coil and electronics are typically built into a portable device, such as a cell phone. When the receiver coil is positioned on the transmitter coil, magnetic coupling occurs when the transmitter coil is driven. The flux is coupled into the secondary coil, which induces a voltage and current flows. The secondary voltage is rectified, and power can be transferred effectively to a load, wirelessly. Power transfer can be managed through any of the various closed-loop control schemes.

After power is applied and the device comes out of reset, it can automatically begin the process of detecting and powering a receiver. The bq500215 sends a ping to detect the presence of a receiver on the pad. After a receiver is detected, the bq500215 attempts to establish communication and begin power transfer. If the transmitter detects the bq51025 receiver through its proprietary authentication protocol, the transmitter allows 10-W operation. If a standard 5-W WPC compliant receiver is detected, the transmitter allows 5-W of delivered power as per WPC specification. The bq500215 controls a full-bridge power stage to drive the primary coil. It regulates the power being delivered to the receiver by modulating the supply voltage of the power stage while operating at a constant frequency. The full bridge power stage allows for higher power delivery for a given supply voltage.

## 8.2 Functional Block Diagram



#### 8.3 Feature Description

#### 8.3.1 A29 Coil Specification

The bq500215 controller supports A29 TX coil type. The coil and matching capacitor specification for A29 transmitter has been established by the WPC Standard. This is fixed and cannot be changed on the transmitter side.

For a current list of coil vendors, see bqTESLA Transmitter Coil Vendors, SLUA649.

#### 8.3.2 Option Select Pins

There are two option select pins (pin 60, LOSS\_THR, and pin 61, LED\_MODE) on the bq500215 and five selector outputs (pins 19, 20, 22, 23, and 24) used to read multiple voltage thresholds. All the pin voltages will be read by bq500215 at power-up.

- Pin 60 is used to program the loss threshold and calibrate the FOD algorithms.
- Pin 61 is used to select the LED mode of the device.
- Pins 19, 20, 22, 23, and 24 are used to sequentially bias the five programming resistors shown in Figure 4.

At power-up, a bias current is applied to pins LED\_MODE and LOSS\_THR, and the resulting voltage is measured to identify the value of the attached programming resistor. For LED\_MODE, the selected bin determines the LED behavior based on Table 1. For the LOSS\_THR, the selected bin sets a threshold based on Table 2. See FOD and Parasitic Metal Object Detect (PMOD) Calibration for more information.

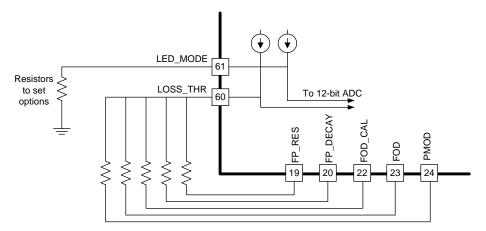


Figure 4. Pin 60 LOSS\_THR and Pin 61 LED\_MODE Connections



#### Feature Description (continued)

#### 8.3.3 LED Modes

The bq500215 can directly drive three LED outputs (pin 12, pin 13, and pin 25) through a simple current limit resistor (typically 470  $\Omega$ ), based on the mode selected. The three current limit resistors can be individually adjusted to tune or match the brightness of the LEDs. Do not exceed the maximum output current rating of the device.

The selection resistor, connected between pin 61 and GND, selects one of the desired LED indication schemes presented in Table 1.

LED	LED	DESCRIPTION		OPERATIONAL STATES						
CONTROL OPTION	SELECTION RESISTOR		LED	STANDBY	POWER TRANSFER	CHARGE COMPLETE	FAULT	FOD Warning	High Power Transfer <sup>(1)</sup>	
			LED_A, green							
х	<36.5 kΩ	Reserved, do not use	LED_B, red	_	_	—	_	—	—	
			LED_C, amber							
			LED_A, green	Off	Blink slow <sup>(2)</sup>	On	Off	Off	Blink fast <sup>(3)</sup>	
1	42.2 kΩ	Choice number 1	LED_B, red	Off	Off	Off	On	Blink fast <sup>(3)</sup>	Off <sup>(3)</sup>	
			LED_C, amber	—	—	—	-	_	—	
			LED_A, green	On	Blink slow <sup>(2)</sup>	On	Off	Off	Blink fast <sup>(3)</sup>	
2	48.7 kΩ	Choice number 2	LED_B, red	On	Off	Off	On	Blink fast <sup>(3)</sup>	Off <sup>(3)</sup>	
			LED_C, amber	_	—	—	—	_	—	
			LED_A, green	Off	On	Off	Blink fast <sup>(3)</sup>	On	On	
3(4)	56.2 kΩ	Choice number 3	LED_B, red	_	_	_	_	_	—	
		LED_C, amber	_	_	—	_	_	—		
			LED_A, green	Off	On	Off	Off	Off	On	
4	64.9 kΩ	Choice number 4	LED_B, red	Off	Off	Off	On	Blink fast <sup>(3)</sup>	Off	
			LED_C, amber	_	—	—	—	_	—	
			LED_A, green	Off	Off	On	Off	Off	Off	
5	75 kΩ	Choice number 5	LED_B, red	Off	On	Off	Off	On	On	
			LED_C, amber	Off	Off	Off	Blink slow <sup>(2)</sup>	Off	Off	
			LED_A, green	Off	Blink slow <sup>(2)</sup>	On	Off	Off	Blink fast <sup>(3)</sup>	
6	86.6 kΩ	Choice number 6	LED_B, red	Off	Off	Off	On	Blink fast <sup>(3)</sup>	Off	
			LED_C, amber	Off	Off	Off	Off	Off	Off	
			LED_A, green	Off	Blink slow <sup>(2)</sup>	Off	Off	Off	Blink fast <sup>(3)</sup>	
7	100 kΩ	Choice number 7	LED_B, red	Off	Off	On	Off	Off	Off	
			LED_C, amber	Off	Off	Off	On	Blink fast <sup>(3)</sup>	Off	
			LED_A, green	Off	Off	On	Blink slow <sup>(2)</sup>	Off	Off	
8	115 kΩ	Choice number 8	LED_B, red	Off	On	Off	Blink slow <sup>(2)</sup>	On	On	
			LED_C, amber	_	_	—	_	_	—	
			LED_A, green	Off	Blink slow <sup>(2)</sup>	On	Off	Off	Blink fast <sup>(3)</sup>	
9	133 kΩ	Choice number 9	LED_B, red	Off	OFF	Off	On	Blink fast <sup>(3)</sup>	Off	
			LED_C, amber	_	_	_	_	_	_	
			LED_A, green	Off	On	Off	Blink fast <sup>(3)</sup>	On	On	
10	154 kΩ	Choice number 10	LED_B, red	Off	Off	On	Off	Off	Off	
			LED_C, amber	_	_	_	_		_	

#### Table 1. LED Modes

(1) Power transfer when operating with bq51025 wireless power receiver

(2) Blink slow = 0.625 Hz

(3) Blink fast = 2.5 Hz

bq500215

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<sup>(4)</sup> The indication of the shutdown after an negative temperature coefficient (NTC) event may experience a delay in the rapid LED blinking even though the power transfer has been disabled. The indication delay may persist up to as long as the entire NTC FAULT holdoff time.



#### 8.3.4 FOD and Parasitic Metal Object Detect (PMOD) Calibration

The bq500215 supports multiple levels of protection against heating metal objects placed in the magnetic field. An initial analysis of the impulse response to a short ping (FOD ping) detects most metal objects before any power transfer is initiated. If a foreign metallic object is detected by the FOD ping, an FOD warning is issued (see Table 1) for up to 6 seconds after the object is removed. In the case where a bg51025 receiver with a potential foreign object is detected, the bq500215 transmitter will not configure the receiver in proprietary 10-W mode in order to limit the losses in the foreign object. After power transfer has started, improved FOD (WPC1.1) and enhanced PMOD (WPC 1.0) features continuously monitor input power, known losses, and the value of power reported by the RX device being charged. Using these inputs, the bq500215 can estimate how much power is unaccounted for and presumed lost due to metal objects placed in the wireless power transfer path. If this unexpected loss exceeds the threshold set by the FOD or PMOD resistors, a fault is indicated and power transfer is halted. The ID packet of the receiver being charged determines whether the FOD or PMOD algorithm is used. The ultimate goal of the FOD feature is safety, to protect misplaced metal objects from becoming hot. Reducing the loss threshold and making the system too sensitive leads to false trips and a bad user experience. Find the balance which best suits the application. If the application requires disabling one function or the other (or both), it is possible by leaving the respective FOD/PMOD terminal open. For example, to selectively disable the PMOD function, PMOD should be left open. A final level of protection is provided with an optional temperature sensor to detect any large increase in temperature in the system (see Shut Down Through External Thermal Sensor or Trigger).

#### NOTE

Disabling FOD results in a TX solution that is not WPC v1.1 compliant.

Resistors of 1% tolerance should be used for a reliable selection of the desired threshold. The FOD and PMOD resistors (pin 23 and pin 24) program the permitted power loss for the FOD and PMOD algorithms respectively. The FOD\_CAL resistor (pin 22), can be used to compensate for any load-dependent effect on the power loss. Using a calibrated FOD reference receiver with no foreign objects present, the FOD\_CAL resistor should be selected such that the calculated loss across the load range is substantially constant (within approximately 100 mW). After correcting for the load dependence, the FOD and PMOD thresholds should be re-set above the resulting average by approximately 400 mW for the transmitter to satisfy the WPC requirements on tolerated heating.

Contact TI for the TX tuning tool to set appropriate FOD, PMOD, and FOD\_CAL resistor values for your design.

Bin Number	Resistance (kΩ)	Loss Threshold (mW)
0	<36.5	250
1	42.2	300
2	48.7	350
3	56.2	400
4	64.9	450
5	75.0	500
6	86.6	550
7	100	600
8	115	650
9	133	700
10	154	750
11	178	800
12	205	850
13	>237	Feature disabled

#### **Table 2. Option Select Bins**



#### 8.3.5 FOD Ping Calibration

The bq500215 is able to detect most metal objects in the charging pad by analyzing the impulse response to a

short ping (FOD ping) sent before any power transfer is initiated. The bq500215 does this analysis by measuring the change in resonant frequency and decay of the pulse response and comparing it to given threshold values that are set by resistor in FP RES and FP DECAY pins.

Resistors of 1% tolerance should be used for a reliable selection of the desired threshold. The FP RES and FP\_DECAY resistors (pin 19 and pin 20) program the boundary conditions to determine is a receiver or a metal object is detected. The recommended resistor value for both FP\_RES and FP\_DECAY pins is 86.6 kΩ.

Contact TI for inquiries regarding FOD ping calibration.

#### NOTE

Removing resistors in FP DECAY and FP RES pins disables FOD ping and hence foreign object detection prior to power transfer.

#### 8.3.6 Shut Down Through External Thermal Sensor or Trigger

Typical applications of the bq500215 do not require additional thermal protection. This shutdown feature is provided for enhanced applications and is not limited to thermal shutdown. The key parameter is the 1-V threshold on pin 2, T\_SENSE. Voltage below 1-V on pin 2 causes the device to shut down.

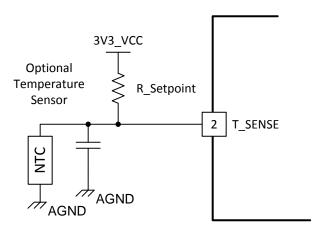
The application of thermal monitoring through a negative temperature coefficient (NTC) sensor, for example, is straightforward. The NTC forms the lower leg of a temperature-dependant voltage divider. The NTC leads are connected to the bq500215 device, pin 2 and GND. The threshold on pin 2 is set to 1-V, below which the system shuts down and a fault is indicated (depending on LED mode chosen).

To implement this feature follow these steps:

- 1. Consult the NTC data sheet and find the resistance versus temperature curve.
- 2. Determine the actual temperature where the NTC will be placed by using a thermal probe.
- 3. Read the NTC resistance at that temperature in the NTC data sheet, that is R\_NTC.
- 4. Use the following formula to determine the upper leg resistor (R Setpoint):
  - R Setpoint =  $2.3 \times R$  NTC

The system restores normal operation after approximately five minutes or if the receiver is removed. If the feature is not used, this pin must be pulled high.

NOTE Pin 2, T\_SENSE, must always be terminated; otherwise, erratic behavior may occur.





bq500215

(1)

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#### 8.3.7 Fault Handling and Indication

Table 3 shows end power transfer (EPT) packet responses, fault conditions, and the duration of how long the condition lasts until a retry in attempted. The LED mode selected determines how the LED indicates the condition or fault.

Table 3. Fault Handling and Indication

CONDITION	DURATION <sup>(1)</sup> (BEFORE RETRY)	HANDLING		
EPT-00	Immediate <sup>(2)</sup>	Unknown		
EPT-01	up tp 5 s <sup>(3)</sup>	Charge complete		
EPT-02	Infinite	Internal fault		
EPT-03	5 minutes	Over temperature		
EPT-04	Immediate <sup>(2)</sup>	Over voltage		
EPT-05	Immediate <sup>(2)</sup>	Over current		
EPT-06	Infinite	Battery failure		
EPT-07	Not applicable	Reconfiguration		
EPT-08	Immediate <sup>(2)</sup>	No response		
OVP (over voltage)	Immediate <sup>(2)</sup>			
OC (over current)	1 minute			
NTC (external sensor)	5 minutes			
PMOD/FOD warning	6 s	4-s LED only, 2-s LED + buzzer		
PMOD/FOD	5 minutes			

(1) After a FAULT, the magnetic field is recharacterized to improve the ability to detect the removal of the at-fault receiver. If the receiver is removed in the first second immediately following the detection of this fault (before the re-characterization is complete), the field corresponding to an empty pad may be associated with the faulty receiver and the LED indication may continue to indicate a fault state even though no receiver is present. This indication persists until either the HOLDOFF time expires or a new receiver disturbs the field, at which time normal operation, with proper LED indication, is resumed.

(2) Immediate is <1 s.

(3) The TX may retry immediately (<1 s) to start power after first EPT-01 is received. If the receiver is continuously sending EPT-01, the TX holdoff time will be 5 seconds

### 8.3.8 Power Transfer Start Signal

The bq500215 features two signal outputs to indicate that power transfer has begun. Pin 31 BUZ\_AC outputs a 400-ms duration, 4-kHz square wave for driving low cost AC type ceramic buzzers. Pin 32 BUZ\_DC outputs logic high, also for 400-ms, which is suitable for DC type buzzers with built-in tone generators, or as a trigger for any type of customized indication scheme. Do not exceed 4-mA loading from either of these pins which is more than adequate for small signaling and actuation. If not used, these pins should be left open.

#### 8.3.9 Power-On Reset

The bq500215 has an integrated power-on reset (POR) circuit which monitors the supply voltage and handles the correct device startup sequence. Additional supply voltage supervisor or reset circuits are not needed.

#### 8.3.10 External Reset, RESET Pin

The bq500215 can be forced into a reset state by an external circuit connected to the  $\overline{\text{RESET}}$  pin. A logic low voltage on this pin holds the device in reset. For normal operation, this pin is pulled up to 3.3-V supply with a 10-k $\Omega$  pullup resistor.

#### 8.3.11 Trickle Charge and CS100

The WPC specification provides an EPT message (EPT–01) to indicate charge complete. Upon receipt of the charge complete message, the bq500215 disables the output and changes the LED indication. The exact indication depends on the LED\_MODE chosen.



In some battery charging applications, there is a benefit to continue the charging process in trickle-charge mode to top off the battery. The WPC specification provides for an informational 'Charge Status' packet that conveys the level of battery charger. The bq500215 uses this command to enable top-off charging. The bq500215 changes the LED indication to reflect charge complete when a Charge Status message is 100% received, but unlike the response to an EPT, it will not halt power transfer while the LED indicates charge complete. The mobile device can use a CS100 packet to enable trickle charge mode.

If the reported charge status drops below 90%, normal charging indication is resumed.

## 8.4 Device Functional Modes

#### 8.4.1 Power Transfer

Power transfer depends on coil coupling. Coupling depends on the distance between coils, alignment, coil dimensions, coil materials, number of turns, magnetic shielding, impedance matching, frequency, and duty cycle.

Most importantly, the receiver and transmitter coils must be aligned for best coupling and efficient power transfer. The smaller the space between the coils is, the better the coupling.

Shielding is added as a backing to both the transmitter and receiver coils to direct the magnetic field to the coupled zone. Magnetic fields outside the coupled zone do not transfer power. Thus, shielding also serves to contain the fields to avoid coupling to other adjacent system components.

Regulation can be achieved by controlling any one of the coil coupling parameters. However, for WPC compatibility, the transmitter-side coils and capacitance are specified and the resonant frequency point is fixed. Power transfer is regulated by changing the supply voltage to the full-bridge power stage; higher voltage delivers more power. Duty cycle remains constant at 50% throughout the power band and frequency also remains constant at 130 kHz.

The WPC standard describes the dimensions, materials of the coils, and information regarding the tuning of the coils to resonance. The value of the inductor and resonant capacitor are critical to proper operation and system efficiency.

#### 8.4.2 Communication

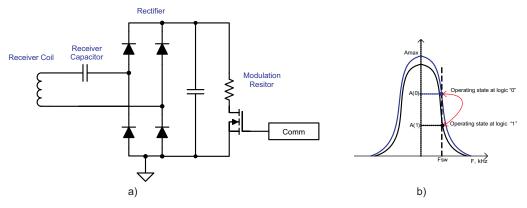
Communication within the WPC is from the receiver to the transmitter, where the receiver tells the transmitter to send power and how much. To regulate, the receiver must communicate with the transmitter whether to increase or decrease frequency. The receiver monitors the rectifier output and using amplitude modulation (AM), sends packets of information to the transmitter. A packet is comprised of a preamble, a header, the actual message, and a checksum, as defined by the WPC standard.

The receiver sends a packet by modulating an impedance network. This AM signal reflects back as a change in the voltage amplitude on the transmitter coil. The signal is demodulated and decoded by the transmitter-side electronics and the voltage on the inverter is adjusted to close the regulation loop. The bq500215 features internal digital demodulation circuitry.

The modulated impedance network on the receiver can either be resistive or capacitive. Figure 6 shows the resistive modulation approach, where a resistor is periodically added to the load, and the resulting amplitude change in the transmitter voltage. Figure 7 shows the capacitive modulation approach, where a capacitor is periodically added to the load and the resulting amplitude change in the transmitter voltage.



#### **Device Functional Modes (continued)**





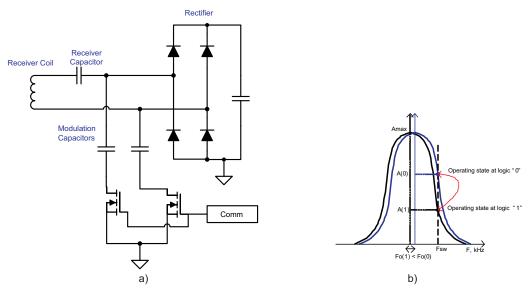


Figure 7. Receiver Capacitive Modulation Circuit

The bq500215 also supports a proprietary handshake with the bq51025 in which minimal communication from the TX to the RX is used. This proprietary handshake enables the bq500215 to deliver power to the bq51025 receiver at levels higher than 5 W. The transmitter-to-receiver communication is achieved through frequency modulation of the power signal.

#### 8.4.3 Power Trains

The bq500215 drives a full-bridge power stage, which drives the coil assembly. TI recommends the CSD97374CQ4M as the driver-plus-MOSFET device for this application. The supply voltage (Vrail) is controlled by the bq500215 device.

#### 8.4.4 Power Train Voltage Control

The bq500215 controls power delivery by modulating the supply voltage (Vrail) of the power stage driving the coil assembly. The bq500215 device generates a PWM control signal in the PWM\_RAIL terminal that controls an external power stage circuit (TI recommends CSD97374CQ4M). The switching frequency for this DC-DC controller signal is 520 kHz.



### **Device Functional Modes (continued)**

#### 8.4.5 Signal Processing Components

The COMM signal used to control power transfer is derived from the coil voltage. The AC coupled coil voltage is scaled down to a manageable level and biased to a 1-V offset. Series connected diodes are provided for protection from any possible transients.

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## 9 Application and Implementation

#### NOTE

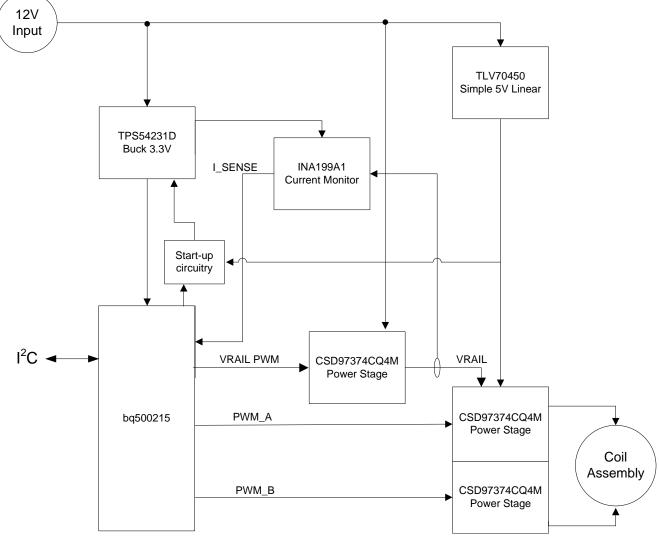
Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

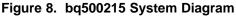
#### 9.1 Application Information

The bq500215 device is a wireless power transmitter controller designed for 5-W WPC compliant applications as well as up to 10-W applications (in combination with the bq51025 wireless receiver). It integrates all functions required to control wireless power transfer to a WPC v1.1 compliant receiver. Several tools are available for the design of the system. See the product folder on www.ti.com for more details. The following sections highlight some of the system design considerations.

### 9.2 Typical Application

Figure 8 shows the application block diagram for the transmitter.







## Typical Application (continued)

### 9.2.1 Design Requirements

#### Table 4. Design Parameters

DESIGN PARAMETER	VALUE
WPC coil type	A29
Input voltage	12 V

#### 9.2.2 Detailed Design Procedure

#### 9.2.2.1 Capacitor Selection

Capacitor selection is critical to proper system operation. The total capacitance value of  $2 \times 100$  nF + 47 nF is required in the resonant tank. This is the WPC system compatibility requirement, not a guideline.

#### NOTE

A total capacitance value of  $2 \times 100$  nF + 47 nF (C0G dielectric type, 100-V rating) is required in the resonant tank to achieve the correct resonance frequency.

The capacitors chosen must be rated for at least 100 V and must be of a high-quality C0G dielectric (sometimes also called NP0). These are typically available in a 5% tolerance, which is adequate. TI does not recommend the use of X7R types or below if WPC compliance is required because critical WPC Certification Testing, such as the minimum modulation or guaranteed power test, might fail.

The designer can combine capacitors to achieve the desired capacitance value. Various combinations can work depending on market availability. All capacitors must be of COG types (not mixed with any other dielectric types).

#### 9.2.2.2 Current Monitoring Requirements

The bq500215 is WPC v1.1 ready. To enable the PMOD or FOD features, provide current monitoring in the design.

For proper scaling of the current monitor signal, the current sense resistor should be 20 m $\Omega$  and the current shunt amplifier should have a gain of 50, such as the INA199A1. For FOD accuracy, the current sense resistor must be a quality component with 0.5% tolerance, at least 1/4-W rating, and a temperature stability of ±200 PPM. Proper current sensing techniques in the application hardware should also be observed.

#### 9.2.2.3 All Unused Pins

All unused pins can be left open unless otherwise indicated. Refer to the table in *Pin Configuration and Functions*. To improve PCB layout, ground unused pins, if it is an option.

#### 9.2.2.4 Input Regulators

The bq500215 requires 3.3  $V_{DC}$  to operate. A buck converter is used to step down from the supply voltage, such as the TPS54231D used in this design.

#### 9.2.2.5 Input Power Requirements

The design works with 12-V input voltage. A29 TX type requires 12-V system voltage.

#### 9.2.2.6 LED Mode

bq500215 can directly drive three LED outputs (pin 12 (LED-A), pin 13 (LED-B), and pin 25 (LED-C)). Select one of the desired LED indication schemes by choosing the selection resistor connected between pin 61 (LED\_MODE) and GND.

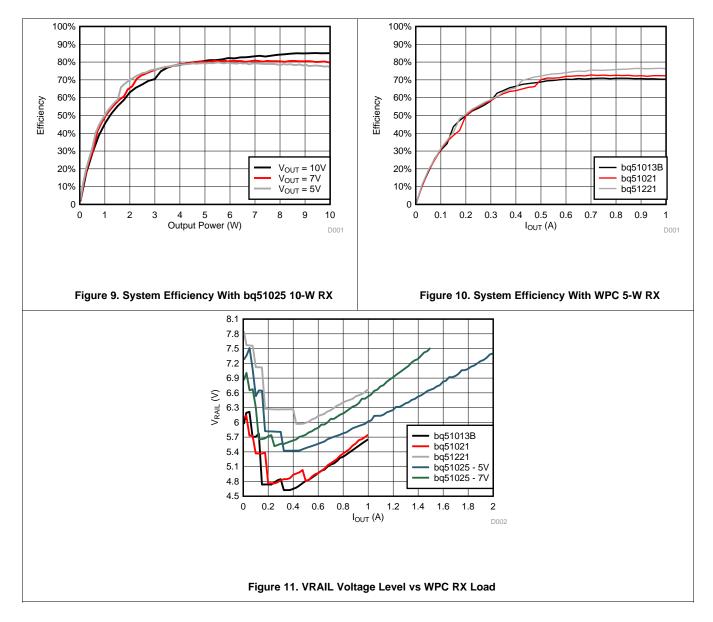
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#### **bq500215** SLUSBZ1A-OCTOBER 2014-REVISED NOVEMBER 2014

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#### 9.2.3 Application Curves





## **10** Power Supply Recommendations

This device is designed to operate from an input voltage supply range between 3- to 3.6-V, nominal 3.3-V. The A29 TX type requires a 12-V system voltage.

## 11 Layout

### 11.1 Layout Guidelines

Careful PCB layout practice is critical to proper system operation. Many references are available on proper PCB layout techniques. A few good tips are as follows:

The TX layout requires a 4-layer PCB layout for best ground plane technique. A 2-layer PCB layout can be achieved though not as easily. Ideally, the approach to the layer stack-up is:

- Layer 1 component placement and as much ground plane as possible
- Layer 2 clean ground
- Layer 3 finish routing
- Layer 4 clean ground

Thus, the circuitry is virtually sandwiched between grounds. This minimizes EMI noise emissions and also provides a noise-free voltage reference plane for device operation.

Keep as much copper as possible. Make sure the bq500215 GND pins and the EPAD GND power pad have a continuous flood connection to the ground plane. The power pad should also be stitched to the ground plane, which also acts as a heat sink for the bq500215. A good GND reference is necessary for proper bq500215 operation, such as analog-digital conversion, clock stability, and best overall EMI performance.

Separate the analog ground plane from the power ground plane and use only **one** tie point to connect grounds. Having several tie points defeats the purpose of separating the grounds.

The COMM return signal from the resonant tank should be routed as a differential pair. This is intended to reduce stray noise induction. The frequencies of concern warrant low-noise analog signaling techniques, such as differential routing and shielding, but the COMM signal lines do not need to be impedance matched.

The DC-DC buck regulator used from the 12-V input supplies the bq500215 with 3.3-V. Typically, the designer uses a single-chip controller solution with integrated power FET and synchronous rectifier or outboard diode. Pull in the buck inductor and power loop as close as possible to create a tight loop. Likewise, the power-train, full-bridge components should be pulled together as tight as possible. See the bq500215 EVM for an example of a good layout technique.

### 11.2 Layout Example

A DC-DC buck regulator is used to step down the system voltage to the 3.3-V supply to the bq500215. The system voltage is 12-V; with such a step-down ratio, switching duty-cycle is low and the regulator is mostly freewheeling. Therefore, place the freewheeling diode current loop as close to the switching regulator as possible and use wide traces. Place the buck inductor and power loop as close to that as possible to minimize current path.

Place 3.3-V buck regulator input bypass capacitors as close as possible to the buck IC.

## Layout Example (continued)

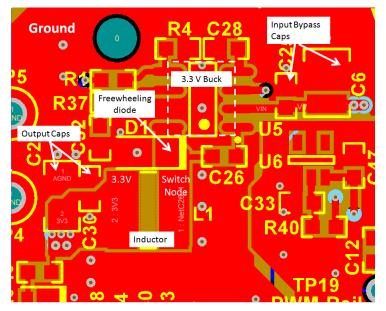


Figure 12. 3.3-V DC-DC Buck Regulator Layout

Make sure the bypass capacitors intended for the bq500215 3.3-V supply are actually bypassing these supply pins (pin 44, V33DIO, pin 45, V33D, and pin 46, V33A) to solid ground plane. This means they need to be placed as close to the device as possible and the traces must be as wide as possible.

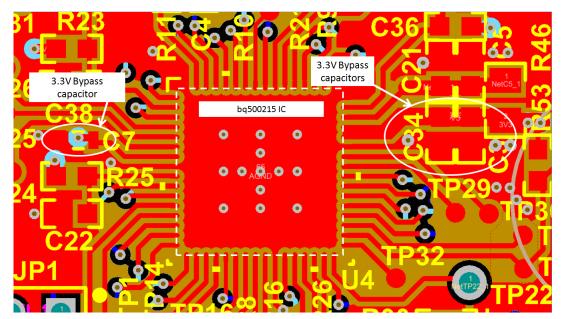
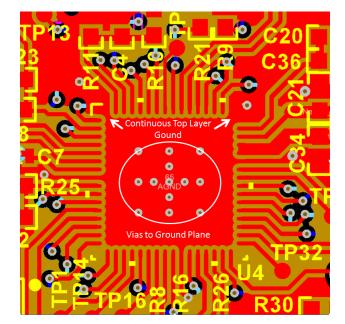


Figure 13. Bypass Capacitors Layout



### Layout Example (continued)



Make sure the bq500215 has a continuous flood connection to the ground plane.

Figure 14. Continuous GND Layout

A buck regulator is used to regulate the supply voltage to the full bridge. The buck power stage IC is controlled by a PWM signal generated by the bq500215 IC, and it is directly powered from the 12-V input supply. Because the buck output voltage can operate at a wide voltage range, significant current low is expected in both the buck power stage input and ground connections. Make sure wide traces and continuous pours are used for input and ground. Place input bypass capacitors, output capacitor and inductor as close as possible to the buck power stage to make the current loop as small as possible.

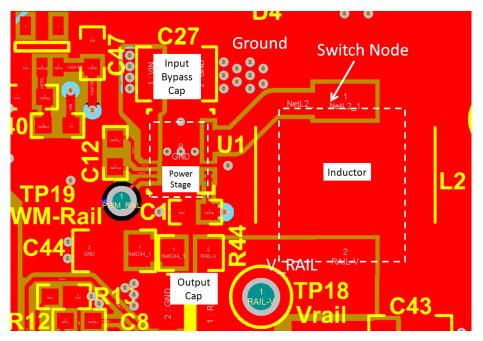


Figure 15. V\_RAIL Power Stage Layout



## Layout Example (continued)

The full-bridge power stage that drives the TX coil is composed of two half-bridge power stages and resonant capacitors. Inputs bypass capacitors should be placed as close as possible to the power stage ICs. The input and ground pours and traces should be made as wide as possible for better current flow. The trace to the coil and resonant capacitors should also be made as wide as possible.

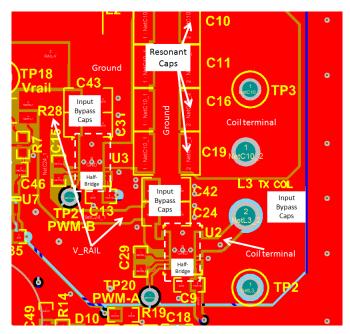


Figure 16. Ground Layout

To ensure proper operation, grounds conducting a large amount of current and switching noise must be isolated from low current, quiet grounds. Separate the ground pours for the power stages and the bq500215 IC. Connect all grounds to a single point at the main ground terminal.

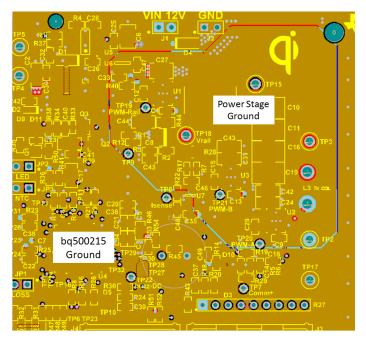


Figure 17. Ground Layout



### Layout Example (continued)

Proper current sensing layout technique is very important, as it directly affects the FOD and PMOD performance. When sampling the very-low voltages generated across a current sense resistor, be sure to use the so called 4-wire or Kelvin-connection technique. This is important to avoid introducing false voltage drops from adjacent pads and copper power routes. It is a common power-supply layout technique. Some high-accuracy sense resistors have dedicated sense pins.

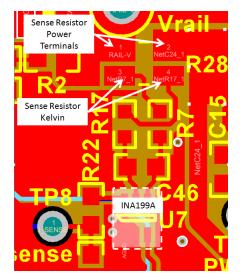


Figure 18. Current Sensing Layout

The COMM+/COMM- sense lines should be run as a balanced or differential pair. For communication, the WPC packet information runs at 2 kHz, which is essentially audio frequency content, and this balancing reduces noise pickup from the surrounding switching power electronics. The designer does not need to tune or impedance-match these lines as would be the case in RF signaling. It is important to keep this lines isolated from any fast switching signal such as PWM, to prevent noise from being injected into the line.

The V\_RAIL+/VRAIL- sense lines should also run as differential pair. Figure 19 shows a layout example for a differential pair layout.

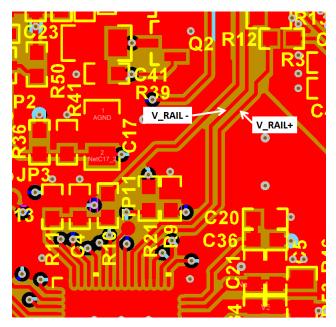


Figure 19. Balanced Differential Signal Layout



## Layout Example (continued)

A bypass capacitor needs to be connected between the point where the 3.3-V bias supply is connected to the COMM+ resistor divider and the divider/COMM– ground connection.

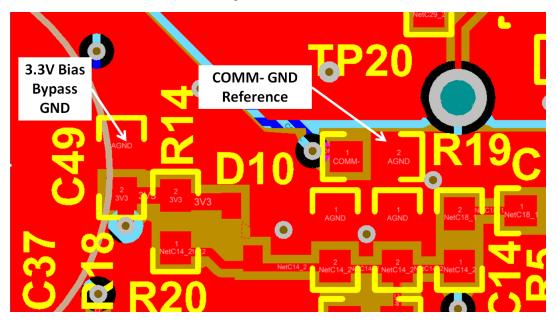


Figure 20. Bypass Capacitors Layout for COMM+ Resistor Divider 3.3-V Bias



## **12 Device and Documentation Support**

## 12.1 Device Support

- 1. Technology, Wireless Power Consortium, www.wirelesspowerconsortium.com/
- 2. Analog applications journal, *An Introduction to the Wireless Power Consortium Standard and TI's Compliant Solutions*, Johns, Bill, SLYT401
- 3. Data sheet, Qi Compliant Wireless Power Transmitter Manager, SLUSAL8
- 4. Data sheet, Integrated Wireless Power Supply Receiver, Qi (WPC) Compliant, bq51011, bq51013, SLVSAT9
- 5. Data sheet, *bq51025 WPC v1.1 Compliant Single Chip Wireless Power Receiver* With Proprietary 10-W Power Delivery, SLUSBX7
- 6. Application note, Building a Wireless Power Transmitter, SLUA635
- 7. Application note, bqTESLA Transmitter Coil Vendors, SLUA649

### 12.2 Trademarks

All trademarks are the property of their respective owners.

#### 12.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

## 12.4 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

## 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



16-Nov-2014

## **PACKAGING INFORMATION**

Orderable Device	Status	Package Type	Package	Pins	Package	Eco Plan	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking	Samples
	(1)		Drawing		Qty	(2)	(6)	(3)		(4/5)	
BQ500215RGCR	ACTIVE	VQFN	RGC	64	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	BQ500215	Samples
BQ500215RGCT	ACTIVE	VQFN	RGC	64	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-3-260C-168 HR	-40 to 85	BQ500215	Samples

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between

the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# PACKAGE OPTION ADDENDUM

16-Nov-2014

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# PACKAGE MATERIALS INFORMATION

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## TAPE AND REEL INFORMATION





# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nom	inal											
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
BQ500215RGCR	VQFN	RGC	64	2000	330.0	16.4	9.3	9.3	1.1	12.0	16.0	Q2
BQ500215RGCT	VQFN	RGC	64	250	180.0	16.4	9.3	9.3	1.1	12.0	16.0	Q2

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# PACKAGE MATERIALS INFORMATION

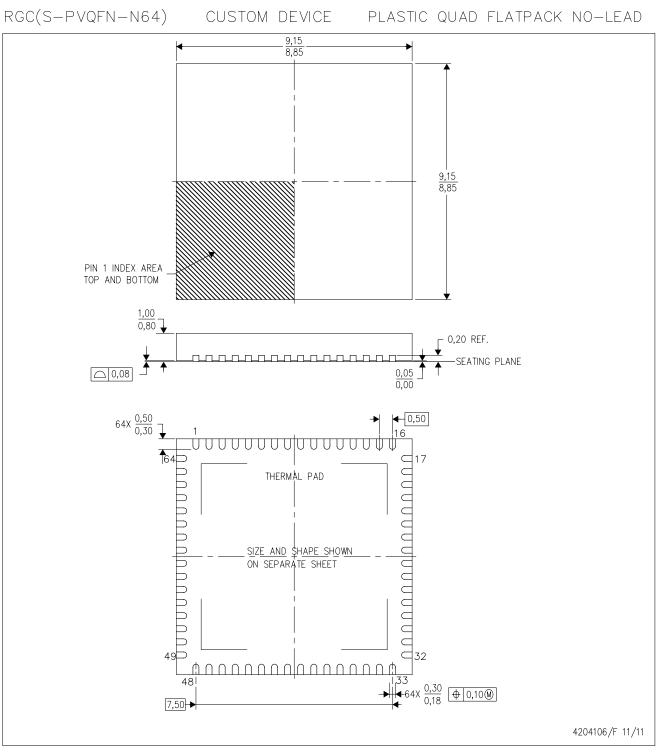
11-Apr-2015



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ500215RGCR	VQFN	RGC	64	2000	367.0	367.0	38.0
BQ500215RGCT	VQFN	RGC	64	250	210.0	185.0	35.0

# **MECHANICAL DATA**



NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5-1994.

- B. This drawing is subject to change without notice.
- C. Quad Flatpack, No-leads (QFN) package configuration.
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions.



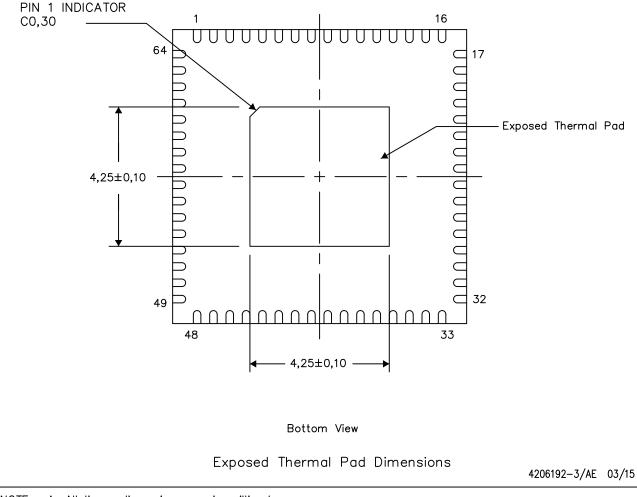


## THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

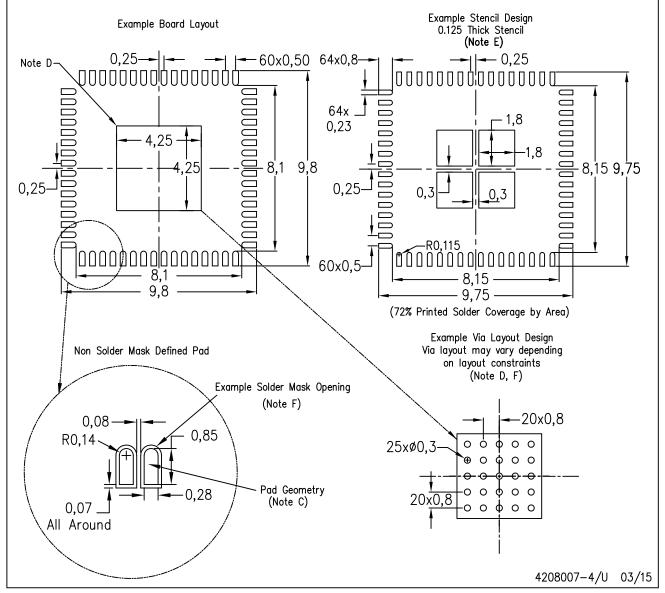


NOTE: A. All linear dimensions are in millimeters



RGC (S-PVQFN-N64)

# PLASTIC QUAD FLATPACK NO-LEAD



NOTES:

A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.

D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <a href="http://www.ti.com">http://www.ti.com</a>.

- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in thermal pad.



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