

# 0.5 dB LSB, 6-Bit, Silicon Digital Attenuator, 100 MHz to 40 GHz

### **Data Sheet**

### FEATURES

Ultrawideband frequency range: 100 MHz to 40 GHz Attenuation range: 0.5 dB steps to 31.5 dB Low insertion loss with impedance match 2.1 dB up to 18 GHz 2.9 dB up to 26 GHz 4.8 dB up to 40 GHz Attenuation accuracy with impedance match ±(0.10 + 1.0% of attenuation state) up to 18 GHz ±(0.15 + 0.8% of attenuation state) up to 26 GHz ±(0.35 + 2.5% of attenuation state) up to 40 GHz Typical step error with impedance match ±0.18 dB up to 18 GHz ±0.23 dB up to 26 GHz ±0.51 dB up to 40 GHz **High input linearity** P0.1dB insertion loss state: 30 dBm P0.1dB other attenuation states: 27 dBm IP3: 50 dBm typical High RF input power handling: 27 dBm average, 30 dBm peak **Tight distribution in relative phase** No low frequency spurious signals SPI and parallel mode control, CMOS/LVTTL compatible RF settling time (0.1 dB of final RF output): 250 ns 24-terminal, 4 mm × 4 mm LGA package Pin compatible with ADRF5720, low frequency cutoff version

#### **APPLICATIONS**

Industrial scanners Test and instrumentation Cellular infrastructure: 5G millimeter wave Military radios, radars, electronic counter measures (ECMs) Microwave radios and very small aperture terminals (VSATs)

### **GENERAL DESCRIPTION**

The ADRF5730 is a silicon, 6-bit digital attenuator with 31.5 dB attenuation control range in 0.5 dB steps.

This device operates from 100 MHz to 40 GHz with better than 4.8 dB of insertion loss and excellent attenuation accuracy. The ADRF5730 has a radio frequency (RF) input power handling capability of 27 dBm average and 30 dBm peak for all states.

The ADRF5730 requires a dual supply voltage of +3.3 V and -3.3 V. The device features serial peripheral interface (SPI), parallel mode control, and complementary metal-oxide semiconductor (CMOS)-/low voltage transistor to transistor logic (LVTTL)-compatible controls.

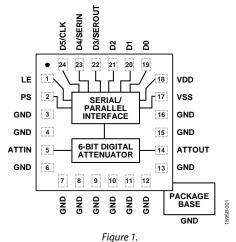
#### Rev. 0

Document Feedback

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# **ADRF5730**

### FUNCTIONAL BLOCK DIAGRAM



The ADRF5730 is pin-compatible with the ADRF5720 low frequency cutoff version, which operates from 9 kHz to 40 GHz.

The ADRF5730 RF ports are designed to match a characteristic impedance of 50  $\Omega$ . For wideband applications, impedance matching on the RF transmission lines can further optimize high frequency insertion loss, return loss, and attenuation accuracy characteristics. Refer to the Electrical Specifications section, the Typical Performance Characteristics section, and the Applications Information section for more details.

The ADRF5730 comes in a 24-terminal, 4 mm  $\times$  4 mm, RoHScompliant, land grid array (LGA) package and operates from  $-40^{\circ}$ C to  $+105^{\circ}$ C.

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### **REVISION HISTORY**

7/2018—Revision 0: Initial Version

## **SPECIFICATIONS**

### **ELECTRICAL SPECIFICATIONS**

 $V_{DD}$  = 3.3 V,  $V_{SS}$  = -3.3 V, digital voltages = 0 V or  $V_{DD}$ , case temperature ( $T_{CASE}$ ) = 25°C, and 50  $\Omega$  system, unless otherwise noted.

Parameter	Test Conditions/Comments	Min Typ	Max U	Jnit
FREQUENCY RANGE		100	40,000 N	ИНz
INSERTION LOSS (IL)				
With Impedance Match	See Figure 44			
	100 MHz to 10 GHz	1.6	d	βB
	10 GHz to 18 GHz	2.1	d	βB
	18 GHz to 26 GHz	2.9	d	βB
	26 GHz to 35 GHz	3.8	d	βB
	35 GHz to 40 GHz	4.8	d	B
Without Impedance Match	See Figure 43			
	100 MHz to 10 GHz	1.6	d	B
	10 GHz to 18 GHz	2.1	d	βB
	18 GHz to 26 GHz	2.7	d	βB
	26 GHz to 35 GHz	3.7	d	βB
	35 GHz to 40 GHz	5.2	d	Β
RETURN LOSS	ATTIN and ATTOUT, all attenuation states			
With Impedance Match	See Figure 44			
·	100 MHz to 10 GHz	20	d	B
	10 GHz to 18 GHz	19	d	βB
	18 GHz to 26 GHz	13	d	Β
	26 GHz to 35 GHz	11		B
	35 GHz to 40 GHz	11	d	B
Without Impedance Match	See Figure 43			
·	100 MHz to 10 GHz	19	d	βB
	10 GHz to 18 GHz	18	d	B
	18 GHz to 26 GHz	16		B
	26 GHz to 35 GHz	13		B
	35 GHz to 40 GHz	9	d	Β
ATTENUATION				
Range	Between minimum and maximum	31.5	d	βB
5	attenuation states			
Step Size	Between any successive attenuation states	0.5	d	βB
Accuracy	Referenced to insertion loss			
With Impedance Match	See Figure 44			
	100 MHz to 10 GHz	±(0.10 + 0.6% of sta	ate) d	lΒ
	10 GHz to 18 GHz	±(0.10 + 1.0% of sta	ate) d	βB
	18 GHz to 26 GHz	±(0.15 + 0.8% of sta	ate) d	lΒ
	26 GHz to 35 GHz	±(0.20 + 2.0% of sta	ate) d	βB
	35 GHz to 40 GHz	±(0.35 + 2.5% of sta	ate) d	lΒ
Without Impedance Match	See Figure 43			
	100 MHz to 10 GHz	±(0.10 + 0.5% of sta	ate) d	βB
	10 GHz to 18 GHz	±(0.10 + 1.0% of sta	ate) d	βB
	18 GHz to 26 GHz	±(0.15 + 0.8% of sta	ate) d	βB
	26 GHz to 35 GHz	±(0.25 + 1.8% of sta	ate) d	βB
	35 GHz to 40 GHz	±(0.40 + 5.0% of sta	ate) d	βB

## ADRF5730

Parameter	Test Conditions/Comments	Min Typ	Max	Unit
Step Error	Between any successive state			
With Impedance Match	See Figure 44			
	100 MHz to 10 GHz	±0.11		dB
	10 GHz to 18 GHz	±0.18		dB
	18 GHz to 26 GHz	±0.23		dB
	26 GHz to 35 GHz	±0.3		dB
	35 GHz to 40 GHz	±0.51		dB
Without Impedance Match	See Figure 43	_0.01		0.0
Millout impedance materi	100 MHz to 10 GHz	±0.11		dB
	10 GHz to 18 GHz	±0.19		dB
	18 GHz to 26 GHz	±0.23		dB
	26 GHz to 35 GHz	±0.25		dB
	35 GHz to 40 GHz	±0.65		dB
RELATIVE PHASE	Referenced to insertion loss			
With Impedance Match	See Figure 44			-
	10 GHz	15		Degrees
	18 GHz	30		Degrees
	26 GHz	50		Degrees
	35 GHz	75		Degrees
	40 GHz	100		Degrees
Without Impedance Match	See Figure 43			
	10 GHz	15		Degrees
	18 GHz	30		Degrees
	26 GHz	50		Degrees
	35 GHz	75		Degrees
	40 GHz	110		Degrees
SWITCHING CHARACTERISTICS	All attenuation states at input power = 10 dBm			
Rise and Fall Time ( $t_{RISE}$ and $t_{FALL}$ )	10% to 90% of RF output	35		ns
On and Off Time ( $t_{ON}$ and $t_{OFF}$ )	50% triggered control (CTL) to 90% of RF output	125		ns
RF Amplitude Settling Time				
0.1 dB	50% triggered CTL to 0.1 dB of final RF output	250		ns
0.05 dB	50% triggered CTL to 0.05 dB of final RF output	350		ns
Overshoot	so / thggerea ere to 0.05 ab or final fir output	1		dB
Undershoot		-2.5		dB
		-2.5		UD
RF Phase Settling Time	f = 5 GHz	100		
5° 1°	50% triggered CTL to 5° of final RF output	160		ns
	50% triggered CTL to 1° of final RF output	180		ns
INPUT LINEARITY <sup>1</sup>	100 MHz to 30 GHz			
0.1 dB Power Compression (P0.1dB)				
Insertion Loss State		30		dBm
Other Attenuation States		27		dBm
Third-Order Intercept (IP3)	Two-tone input power = 14 dBm per tone, $\Delta f = 1$ MHz, all attenuation states	50		dBm
DIGITAL CONTROL INPUTS	LE, PS, D0, D1, D2, D3/SEROUT, <sup>2</sup> D4/SERIN, D5/CLK pins			
Voltage				
Low (V <sub>INL</sub> )		0	0.8	V
High (V <sub>INH</sub> )		1.2	3.3	V
Current			5.5	
Low (I <sub>INL</sub> )		<1		μA
High (I <sub>INH</sub> )	D0, D1, D2	33		μΑ

**ADRF5730** 

Parameter	Test Conditions/Comments	Min	Тур	Max	Unit
DIGITAL CONTROL OUTPUT	D3/SEROUT pin <sup>2</sup>				
Voltage					
Low (Voutl)			0 ± 0.3		V
High (Vouтн)			$V_{\text{DD}} \pm 0.3$		V
Current (IOUTL, IOUTH)				0.5	mA
SUPPLY CURRENT	VDD and VSS pins				
Positive Supply Current			117		μA
Negative Supply Current			-117		μA
RECOMMENDED OPERATING CONDITIONS					
Supply Voltage					
Positive (V <sub>DD</sub> )		3.15		3.45	V
Negative (Vss)		-3.45		-3.15	V
Digital Control Voltage		0		V <sub>DD</sub>	V
RF Input Power <sup>3</sup>	$f = 100 \text{ MHz}$ to 30 GHz, $T_{CASE} = 85^{\circ}C$ , <sup>4</sup> all attenuation states				
ATTIN	Steady state average			27	dBm
	Steady state peak			30	dBm
	Hot switching average			24	dBm
	Hot switching peak			27	dBm
ATTOUT (Bidirectional Use)	Steady state average			18	dBm
	Steady state peak			21	dBm
	Hot switching average			15	dBm
	Hot switching peak			18	dBm
Case Temperature (T <sub>CASE</sub> )		-40		+105	°C

<sup>1</sup> Input linearity performance degrades over frequency, see Figure 30 and Figure 31.
<sup>2</sup> The D3/SEROUT pin is an input in parallel control mode and an output in serial control mode. See Table 5 for the pin function descriptions.
<sup>3</sup> For power derating over frequency, see Figure 2 to Figure 3. Applicable for all ATTIN and ATTOUT power specifications.
<sup>4</sup> For 105°C operation, the power handling degrades from the T<sub>CASE</sub> = 85°C specifications by 3 dB.

### TIMING SPECIFICATIONS

See Figure 34, Figure 35, and Figure 36 for the timing diagrams.

Table 2.

Parameter	Description	Min	Тур	Max	Unit
t <sub>scк</sub>	Minimum serial period, see Figure 34	70			ns
tcs	Control setup time, see Figure 34	15			ns
t <sub>сн</sub>	Control hold time, see Figure 34		20		ns
t <sub>LN</sub>	LE setup time, see Figure 34	15			ns
t <sub>LEW</sub>	Minimum LE pulse width, see Figure 34 and Figure 36		10		ns
t <sub>LES</sub>	Minimum LE pulse spacing, see Figure 34		630		ns
t <sub>ckn</sub>	Serial clock hold time from LE, see Figure 34		0		ns
t <sub>PH</sub>	Hold time, see Figure 36		10		ns
t <sub>PS</sub>	Setup time, see Figure 36		2		ns
tco	Clock to output (SEROUT) time, see Figure 35		20		ns

### **ABSOLUTE MAXIMUM RATINGS**

#### Table 3.

Parameter	Rating
Positive Supply Voltage	–0.3 V to +3.6 V
Negative Supply Voltage	–3.6 V to +0.3 V
Digital Control Input Voltage	-0.3 V to V <sub>DD</sub> + 0.3 V
RF Input Power <sup>1</sup> (f = 100 MHz to	
$30 \text{ GHz}, T_{CASE} = 85^{\circ}C^{2}$	
ATTIN	
Steady State Average	28 dBm
Steady State Peak	31 dBm
Hot Switching Average	25 dBm
Hot Switching Peak	28 dBm
ATTOUT	
Steady State Average	19 dBm
Steady State Peak	22 dBm
Hot Switching Average	16 dBm
Hot Switching Peak	19 dBm
Temperature	
Junction (T <sub>J</sub> )	135℃
Storage	–65°C to +150°C
Reflow	260°C
Continuous Power Dissipation (P <sub>DISS</sub> )	0.5 W
ESD Sensitivity	
Human Body Model (HBM)	
ATTIN and ATTOUT Pins	500 V
Digital Pins	2000 V
Charged Device Model (CDM)	1250 V

<sup>1</sup> For power derating over frequency, see Figure 2 and Figure 3. Applicable for all ATTIN and ATTOUT power specifications.

 $^2$  For 105°C operation, the power handling degrades from the  $T_{\text{CASE}}$  = 85°C specifications by 3 dB.

Stresses at or above those listed under Absolute Maximum

Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

#### THERMAL RESISTANCE

Thermal performance is directly linked to printed circuit board (PCB) design and operating environment. Careful attention to PCB thermal design is required.

 $\theta_{\text{JC}}$  is the junction to case bottom (channel to package bottom) thermal resistance.

#### Table 4. Thermal Resistance

Package Type	θις	Unit
CC-24-5	100	°C/W

### **POWER DERATING CURVES**

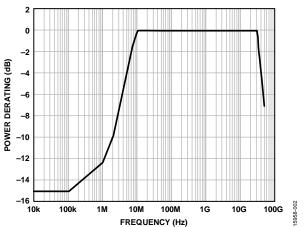


Figure 2. Power Derating vs. Frequency, Low Frequency Detail,  $T_{CASE} = 85^{\circ}C$ 

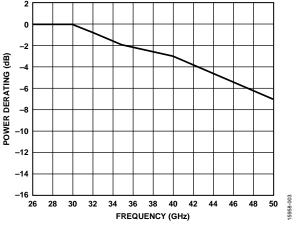


Figure 3. Power Derating vs. Frequency, High Frequency Detail,  $T_{CASE} = 85^{\circ}C$ 

#### **ESD CAUTION**



**ESD** (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

## **PIN CONFIGURATION AND FUNCTION DESCRIPTIONS**

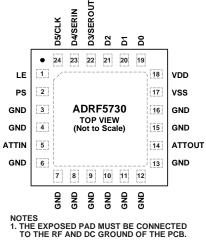
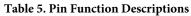


Figure 4. Pin Configuration

5958-004



Pin No.	Mnemonic	Description
1	LE	Latch Enable Input. See the Theory of Operation section for more information.
2	PS	Parallel or Serial Control Interface Selection Input. See the Theory of Operation section for more information.
3, 4, 6 to 13, 15, 16	GND	Ground. These pins must be connected to the RF and dc ground of the PCB.
5	ATTIN	Attenuator Input. This pin is dc-coupled to 0 V and ac matched to 50 $\Omega$ . No dc blocking capacitor is necessary when the RF line potential is equal to 0 V dc.
14	ATTOUT	Attenuator Output. This pin is dc-coupled to 0 V and ac matched to 50 $\Omega$ . No dc blocking capacitor is necessary when the RF line potential is equal to 0 V dc.
17	VSS	Negative Supply Input.
18	VDD	Positive Supply Input.
19	D0	Parallel Control Input for 0.5 dB Attenuator Bit. See the Theory of Operation section for more information.
20	D1	Parallel Control Input for 1 dB Attenuator Bit. See the Theory of Operation section for more information.
21	D2	Parallel Control Input for 2 dB Attenuator Bit. See the Theory of Operation section for more information.
22	D3/SEROUT	Parallel Control Input for 4 dB Attenuator Bit (D3).
		Serial Data Output (SEROUT). See the Theory of Operation section for more information.
23	D4/SERIN	Parallel Control Input for 8 dB Attenuator Bit (D4).
		Serial Data Input (SERIN). See the Theory of Operation section for more information.
24	D5/CLK	Parallel Control Input for 16 dB Attenuator Bit (D5).
		Serial Clock Input (CLK). See the Theory of Operation section for more information.
	EPAD	Exposed Pad. The exposed pad must be connected to the RF and dc ground of the PCB.

#### **INTERFACE SCHEMATICS**

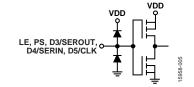


Figure 5. Digital Input Interface (LE, PS, D3/SEROUT, D4/SERIN, D5/CLK)

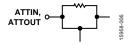


Figure 6. ATTIN and ATTOUT Interface

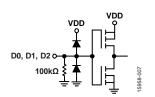


Figure 7. Digital Input Interface (D0, D1, D2)

### **TYPICAL PERFORMANCE CHARACTERISTICS**

### INSERTION LOSS, RETURN LOSS, STATE ERROR, STEP ERROR, AND RELATIVE PHASE

 $V_{DD}$  = 3.3 V,  $V_{SS}$  = -3.3 V, digital voltages = 0 V or  $V_{DD}$ ,  $T_{CASE}$  = 25°C, and a 50  $\Omega$  system, unless otherwise noted. Measured on probe matrix board using ground signal ground (GSG) probes close to the RF pins. See the Applications Information section for details on evaluation and probe matrix boards.

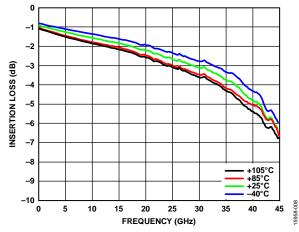


Figure 8. Insertion Loss vs. Frequency over Temperature with Impedance Match

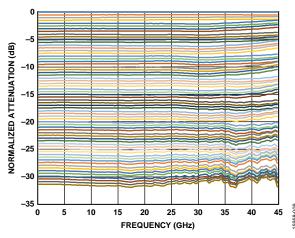


Figure 9. Normalized Attenuation vs. Frequency for All States at Room Temperature, with Impedance Match

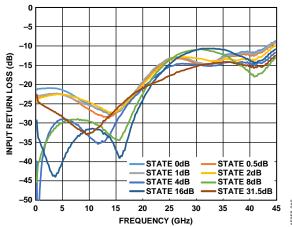


Figure 10. Input Return Loss vs. Frequency (Major States Only) with Impedance Match

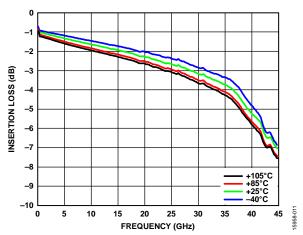


Figure 11. Insertion Loss vs. Frequency over Temperature Without Impedance Match

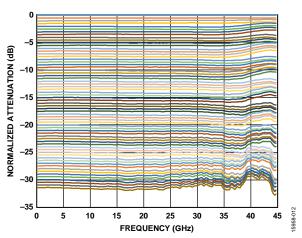


Figure 12. Normalized Attenuation vs. Frequency for All States at Room Temperature Without Impedance Match

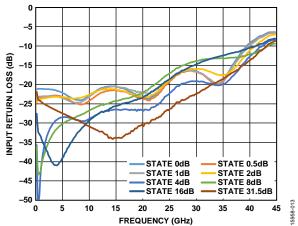


Figure 13. Input Return Loss vs. Frequency (Major States Only) Without Impedance Match

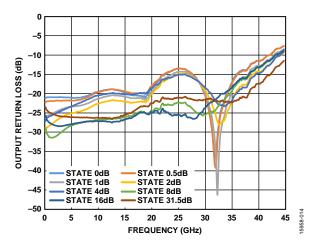


Figure 14. Output Return Loss vs. Frequency (Major States Only) with Impedance Match

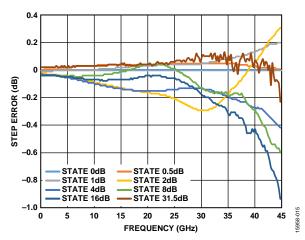


Figure 15. Step Error vs. Frequency (Major States Only) with Impedance Match

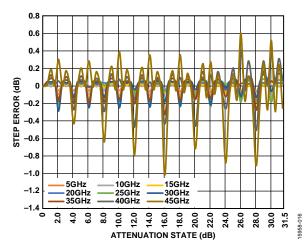


Figure 16. Step Error vs. Attenuation State over Frequency with Impedance Match

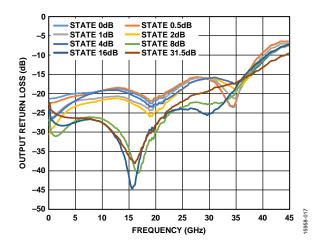


Figure 17. Output Return Loss vs. Frequency (Major States Only) Without Impedance Match

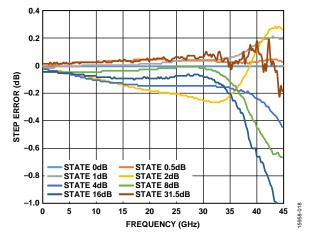


Figure 18. Step Error vs. Frequency (Major States Only) Without Impedance Match

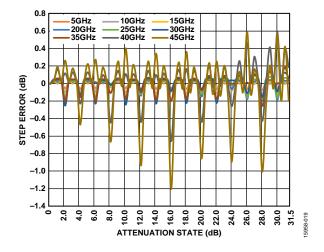


Figure 19. Step Error vs. Attenuation State over Frequency Without Impedance Match

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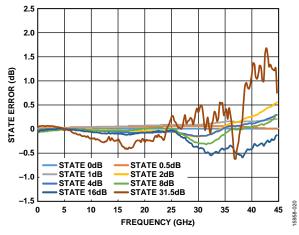


Figure 20. State Error vs. Frequency (Major States Only) with Impedance Match

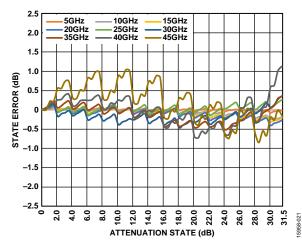


Figure 21. State Error vs. Attenuation State over Frequency with Impedance Match

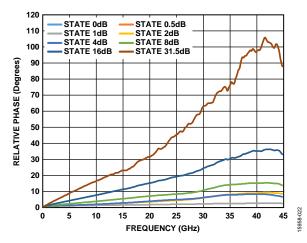


Figure 22. Relative Phase vs. Frequency (Major States Only) with Impedance Match

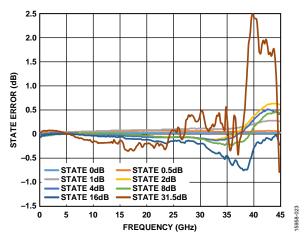


Figure 23. State Error vs. Frequency (Major States Only) Without Impedance Match

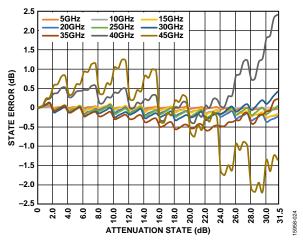


Figure 24. State Error vs. Attenuation State over Frequency Without Impedance Match

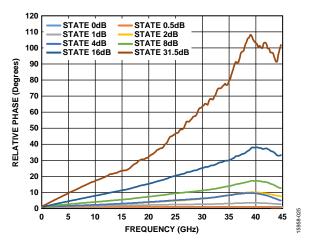


Figure 25. Relative Phase vs. Frequency (Major States Only) Without Impedance Match

## ADRF5730

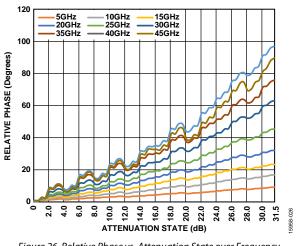


Figure 26. Relative Phase vs. Attenuation State over Frequency with Impedance Match

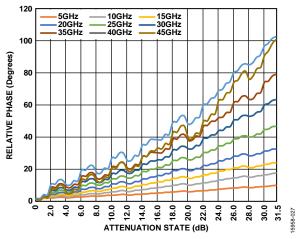


Figure 27. Relative Phase vs. Attenuation State over Frequency Without Impedance Match

## **ADRF5730**

### INPUT POWER COMPRESSION AND THIRD-ORDER INTERCEPT

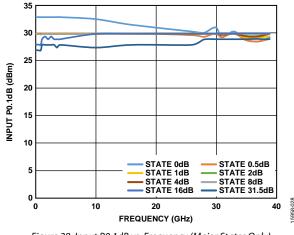


Figure 28. Input P0.1dB vs. Frequency (Major States Only)

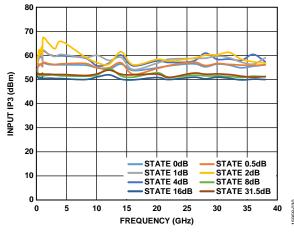


Figure 29. Input IP3 vs. Frequency (Major States Only)

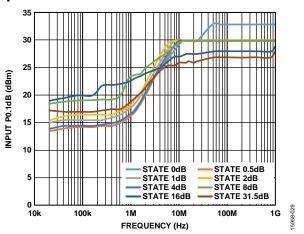


Figure 30. Input P0.1dB vs. Frequency (Major States Only), Low Frequency Detail

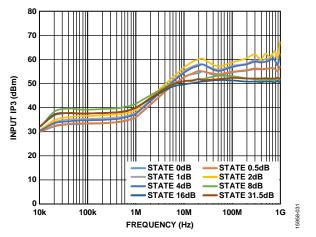


Figure 31. Input IP3 vs. Frequency (Major States Only), Low Frequency Detail

## THEORY OF OPERATION

The ADRF5730 incorporates a 6-bit fixed attenuator array that offers an attenuation range of 31.5 dB in 0.5 dB steps. An integrated driver provides both serial and parallel mode control of the attenuator array (see Figure 32).

Note that when referring to a single function of a multifunction pin in this section, only the portion of the pin name that is relevant is mentioned. For full pin names of the multifunction pins, refer to the Pin Configuration and Function Descriptions section.

### **POWER SUPPLY**

The ADRF5730 requires a positive supply voltage applied to the VDD pin and a negative supply voltage applied to the VSS pin. Bypassing capacitors are recommended on the supply lines to filter high frequency noise.

The power-up sequence is as follows:

- 1. Connect GND.
- 2. Power up VDD.
- 3. Power up VSS.
- 4. Apply the digital control inputs. The relative order of the digital control inputs is not important. However, powering the digital control inputs before the VDD supply can inadvertently forward bias and damage the internal ESD protection structures.
- 5. Apply an RF input signal to ATTIN or ATTOUT.

The power-down sequence is the reverse order of the power-up sequence.

#### Table 7. Truth Table

#### **RF INPUT AND OUTPUT**

Both RF ports (ATTIN and ATTOUT) are dc-coupled to 0 V. No dc blocking is required at the RF ports when the RF line potential is equal to 0 V.

The RF ports are internally matched to 50  $\Omega$ . Therefore, external matching components are not required. For wideband applications, use impedance matching to improve insertion loss, return loss, and attenuation accuracy performance at high frequencies. See the Impedance Matching section.

The ADRF5730 supports bidirectional operation at a lower power level. The power handling of the ATTIN and ATTOUT ports are different. Therefore, the bidirectional power handling is defined by the ATTOUT port. Refer to the RF input power specifications in Table 1.

### SERIAL OR PARALLEL MODE SELECTION

The ADRF5730 can be controlled in either serial or parallel mode by setting the PS pin to high or low, respectively (see Table 6).

#### **Table 6. Mode Selection**

PS	Control Mode
Low	Parallel
High	Serial

		Digital	Control Input <sup>1</sup>				
D5	D4	D3	D2	D1	D0	Attenuation State (dB)	
Low	Low	Low	Low	Low	Low	0 (reference)	
Low	Low	Low	Low	Low	High	0.5	
Low	Low	Low	Low	High	Low	1.0	
Low	Low	Low	High	Low	Low	2.0	
Low	Low	High	Low	Low	Low	4.0	
Low	High	Low	Low	Low	Low	8.0	
High	Low	Low	Low	Low	Low	16.0	
High	High	High	High	High	High	31.5	

<sup>1</sup> Any combination of the control voltage input states shown in Table 7 provides an attenuation equal to the sum of the bits selected.

### **ADRF5730**

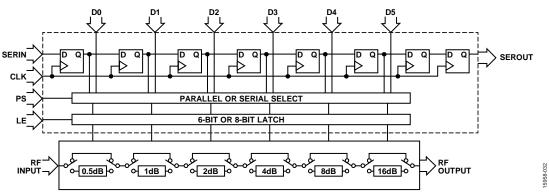


Figure 32. Simplified Circuit Diagram

### SERIAL MODE INTERFACE

The ADRF5730 supports a 3-wire SPI: serial data input (SERIN), clock (CLK), and latch enable (LE). The serial control interface is activated when PS is set to high.

The ADRF5730 attenuation states can be controlled using 6-bit or 8-bit SERIN data. If an 8-bit word is used to control the state of the attenuator, the first two bits, D7 and D6, are don't care bits. It does not matter if these two bits are held low or high, or if they are omitted altogether. Only Bits[D0:D5] set the state of the attenuator.

In serial mode, the SERIN data is clocked most significant bit (MSB) first on the rising CLK edges into the shift register. Then, LE must be toggled high to latch the new attenuation state into the device. LE must be set to low to clock new SERIN data into the shift register as CLK is masked to prevent the attenuator value from changing if LE is kept high. See Figure 34 in conjunction with Table 2 and Table 7.

### **USING SEROUT**

The ADRF5730 also features a serial data output, SEROUT. SEROUT outputs the serial input data at the 8<sup>th</sup> clock cycle, and can control a cascaded attenuator using a single SPI bus. Figure 35 shows the serial out timing diagram.

When using the attenuator in a daisy-chain operation, 8-bit SERIN data must be used due to the 8 clock cycle delay between SERIN and SEROUT.

It is optional to use a 1 k $\Omega$  resistor between SEROUT on the first attenuator and SERIN of the next attenuator to filter the signal (see Figure 33).

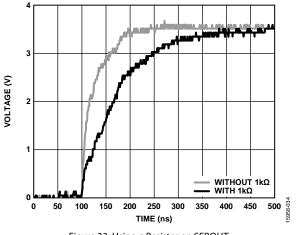


Figure 33. Using a Resistor on SEROUT

## **ADRF5730**

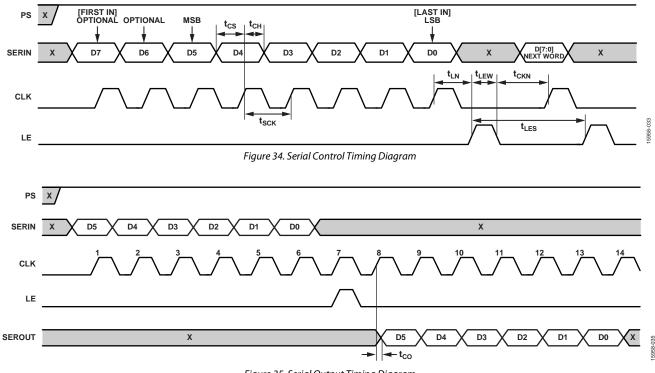


Figure 35. Serial Output Timing Diagram

#### PARALLEL MODE INTERFACE

The ADRF5730 has six digital control inputs, D0 (LSB) to D5 (MSB), to select the desired attenuation state in parallel mode, as shown in Table 7. The parallel control interface is activated when PS is set to low.

There are two modes of parallel operation: direct parallel and latched parallel.

#### **Direct Parallel Mode**

To enable direct parallel mode, the LE pin must be kept high. The attenuation state is changed by the control voltage inputs (D0 to D5) directly. This mode is ideal for manual control of the attenuator.

#### Latched Parallel Mode

To enable latched parallel mode, the LE pin must be kept low when changing the control voltage inputs (D0 to D5) to set the attenuation state. When the desired state is set, LE must be toggled high to transfer the 6-bit data to the bypass switches of the attenuator array, and then toggled low to latch the change into the device until the next desired attenuation change (see Figure 36 in conjunction with Table 2).

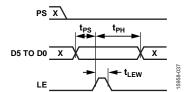
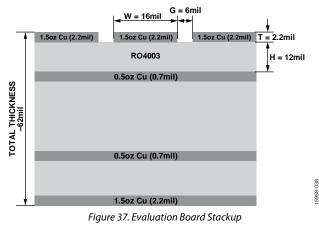


Figure 36. Latched Parallel Mode Timing Diagram

### APPLICATIONS INFORMATION evaluation board

The ADRF5730-EVALZ is a 4-layer evaluation board. The top and bottom copper layer are 0.5 oz (0.7 mil) plated to 1.5 oz (2.2 mil) and are separated by dielectric materials. The stackup for this evaluation board is shown in Figure 37.



All RF and dc traces are routed on the top copper layer, whereas the inner and bottom layers are grounded planes that provide a solid ground for the RF transmission lines. The top dielectric material is 12 mil Rogers RO4003, offering optimal high frequency performance. The middle and bottom dielectric materials provide mechanical strength. The overall board thickness is 62 mil, which allows 2.4 mm RF launchers to be connected at the board edges.

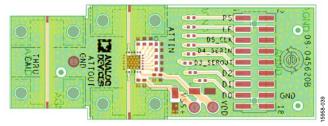
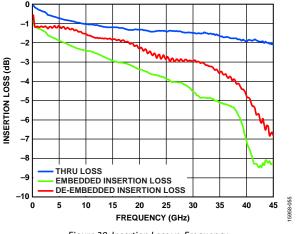


Figure 38. Evaluation Board, Top View

The RF transmission lines are designed using a coplanar waveguide (CPWG) model, with a trace width of 16 mil and ground clearance of 6 mil to have a characteristic impedance of 50  $\Omega$ . For optimal RF and thermal grounding, as many through vias as possible are arranged around transmission lines and under the exposed pad of the package.

The ADRF5730-EVALZ does not have high frequency impedance matching implemented on the RF transmission lines. For more details on the impedance matched circuit, refer to the Impedance Matching portion of the Probe Matrix Board section. Thru calibration can be used to calibrate out the board loss effects from the ADRF5730-EVALZ evaluation board measurements to determine the device performance at the pins of the IC. Figure 39 shows the typical board loss for the ADRF5730-EVALZ evaluation board at room temperature, the embedded insertion loss, and the de-embedded insertion loss for the ADRF5730.



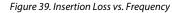


Figure 38 shows the actual ADRF5730 evaluation board with component placement.

Two power supply ports are connected to the VDD and VSS test points, TP1 and TP2, and the ground reference is connected to the GND test point, TP4. On the supply traces, VDD and VSS, a 100 pF bypass capacitor is used to filter high frequency noise. Additionally, unpopulated components positions are available for applying extra bypass capacitors.

All the digital control pins are connected through digital signal traces to the 2  $\times$  9-pin header, P1. There are provisions for a resistor capacitor (RC) filter that helps eliminate dc-coupled noise. The ADRF5730 was evaluated without an external RC filter, the series resistors are 0  $\Omega$ , and shunt capacitors are unpopulated on the evaluation board.

The RF input and output ports (ATTIN and ATTOUT) are connected through 50  $\Omega$  transmission lines to the 2.4 mm RF launchers, J1 and J2, respectively. These high frequency RF launchers are connected by contact and are not soldered onto the board.

A thru calibration line connects the unpopulated J3 and J4 launchers. This transmission line is used to estimate the loss of the PCB over the environmental conditions being evaluated.

The schematic of the ADRF5730-EVALZ evaluation board is shown in Figure 40.

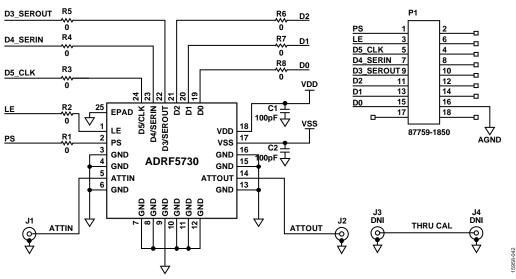


Figure 40. Evaluation Board Schematic

Component	Default Value	Description Capacitor, C0402 package	
C1, C2	100 pF		
J1 to J4	Not applicable	2.4 mm end launch connector (Southwest Microwave: 1492-04A-5)	
P1	Not applicable	$2 \times 9$ -pin header	
R1 to R11	0 Ω	Resistor, 0402 package	
TP1, TP2, TP4	Not applicable	Through-hole mount test point	
U1	ADRF5730	ADRF5730 digital attenuator, Analog Devices, Inc.	

### **PROBE MATRIX BOARD**

The probe matrix board is a 4-layer board. Similar to the evaluation board, the probe matrix board also uses a 12 mil Rogers RO4003 dielectric. The top and bottom copper layers are 0.5 oz (0.7 mil) plated to 1.5 oz (2.2 mil). The RF transmission lines are designed using a CPWG model with a width of 16 mil and ground spacing of 6 mil to have a characteristic impedance of 50  $\Omega$ .

Figure 41 and Figure 42 show the cross sectional view and the top view of the board, respectively. Measurements are made using GSG probes at close proximity to the RF pins. Unlike the evaluation board, probing reduces reflections caused by mismatch arising from connectors, cables, and board layout, resulting in a more accurate measurement of the device performance.

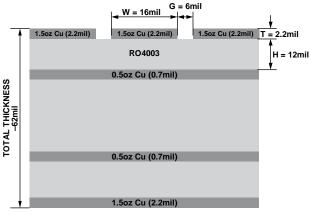


Figure 41. Probe Matrix Board Stackup

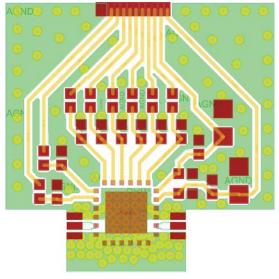


Figure 42. Probe Matrix Board Top View

The probe matrix board includes a thru reflect line (TRL) calibration kit, allowing board loss de-embedding. The actual board duplicates the same layout in matrix form to assemble multiple devices at one time. All S-parameters were measured on this board.

#### Impedance Matching

Impedance matching at the RF pins can improve insertion loss, return loss, and attenuation accuracy at high frequencies. Figure 43 and Figure 44 show the difference in the transmission lines at the ATTIN and ATTOUT pins.

The dimensions of the 50  $\Omega$  lines are 16 mil trace width and 6 mil gap. To implement this impedance matched circuit, the pad length is extended by 5 mil (from 17 mil to 22 mil). The calibration reference kit does not include the 5 mil matching line and, therefore, the measured insertion loss includes the losses of the matching circuit.

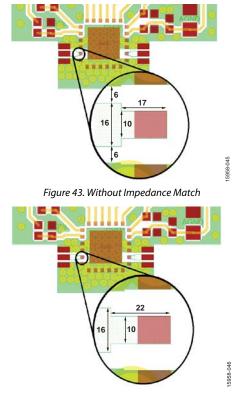


Figure 44. With Impedance Match

5958-043

5958-044

## **OUTLINE DIMENSIONS**

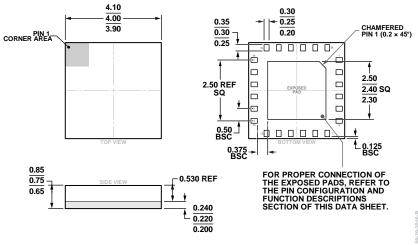


Figure 45. 24-Terminal Land Grid Array [LGA] 4 mm × 4 mm Body and 0.75 mm Package Height (CC-24-5) Dimensions shown in millimeters

#### **ORDERING GUIDE**

Model <sup>1</sup>	Temperature Range	Package Description	Package Option
ADRF5730BCCZN	-40°C to +105°C	24-Terminal Land Grid Array [LGA]	CC-24-5
ADRF5730BCCZN-R7	-40°C to +105°C	24-Terminal Land Grid Array [LGA]	CC-24-5
ADRF5730-EVALZ		Evaluation Board	

<sup>1</sup> Z = RoHS Compliant Part.

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